

1. Pf: Let  $x^*$  be a relative minimum pt of  $f$  over  $\Omega$  and an interior pt. of  $\Omega$ . Let  $dl$  be any arbitrary direction (all are feasible). Then Prop 1 says that

$\nabla f(x^*) dl \geq 0$ . Since every direction is feasible,  $-dl$  is, so again by Prop 1 we have

$$\nabla f(x^*) [-dl] = -\nabla f(x^*) dl \geq 0 \Rightarrow \nabla f(x^*) dl \leq 0.$$

Putting together the two inequalities, we have

$$\nabla f(x^*) dl = 0. \text{ Since } dl \text{ was arbitrary, this must hold for all } dl, \text{ which implies } \nabla f(x^*) = 0.$$

2. a)  $f(a) = E[(X_k - (a_1 X_{k-1} + a_2 X_{k-2} + \dots + a_p X_{k-p}))^2]$ .

FONC:  $\nabla f(a) = 0$ , i.e.  $\frac{\partial f(a)}{\partial a_i} = 0 \quad \forall i$ .

Note first that  $\frac{\partial}{\partial a_i} E[g(a)] = E[\frac{\partial}{\partial a_i} g(a)]$ . Then -

$$\frac{\partial}{\partial a_i} f(a) = E\left[2\left(X_k - \sum_{j=1}^p a_j X_{k-j}\right) X_{k-i}\right]$$

$$= 2E[X_k X_{k-i}] - 2 \sum_{j=1}^p a_j E[X_{k-j} X_{k-i}] = 0$$

$$R_x(i) = \sum_{j=1}^p a_j R_x(i-j)$$

where  $R_x(l)$  is the lag- $l$  autocorrelation of the stationary process  $\{X_k\}$ .

b). For  $p=1$ , this becomes  $a_1 = \frac{R_x(1)}{R_x(0)}$

which is the normalized lag-1 autocorrelation

c). The power spectral density (PSD) of the filter output has the form  $\frac{C_1}{(\frac{1}{RC})^2 + (2\pi f)^2}$ , so the autocorrelation

of the filter output is of the form  $C_2 e^{-\frac{|l|}{RC}}$ . Then

$$R_x(l) = C_2 e^{-\frac{|l|}{RC}} = C_2 e^{-|l|/\tau}$$

2c) (cont) The FONC for  $p=3$  are then the equations:

$$e^{-1/8} = a_1 e^0 + a_2 e^{-1/8} + a_3 e^{-2/8}$$

$$e^{-2/8} = a_1 e^{-1/8} + a_2 e^0 + a_3 e^{-1/8}$$

$$e^{-3/8} = a_1 e^{-2/8} + a_2 e^{-1/8} + a_3 e^0$$

$$\text{or } \begin{bmatrix} 1 & e^{-1/8} & e^{-2/8} \\ e^{-1/8} & 1 & e^{-1/8} \\ e^{-2/8} & e^{-1/8} & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} e^{-1/8} \\ e^{-2/8} \\ e^{-3/8} \end{bmatrix}$$

and the solution is  $a_1 = e^{-1/8}$ , &  $a_2 = a_3 = 0$ .

It is easy to see that this surprising result holds for any RC, any sampling frequency  $f_s$ , and any  $p$ , that is,  $a_1 = e^{-T/RC}$ ,  $a_2 = \dots = a_p = 0$ . This is one reason for calling an RC lowpass filter a "first order" filter -- in digital form, it would appear as an FIR filter with its only non-zero coefficient at lag 1.

$$\begin{aligned} \text{d). } E[e_k^2] &= E[(x_k - e^{-1/8} x_{k-1})^2] = R_x(0) - 2e^{-1/8} R_x(1) + e^{-2/8} R_x(0) \\ &\Rightarrow 1/G_p = E[e_k^2]/R_x(0) = 1 - 2e^{-1/8}(e^{-1/8}) + e^{-2/8} = 1 - e^{-1/4} = 0.22 \\ &\Rightarrow G_p = 4.5 \quad (4.5 \text{ dB}). \end{aligned}$$

3. Simple matrix algebra (though a little tedious).

4.  $f_1(x) = a^T x = \sum_i a_i x_i$        $x$  and  $a$  are column vectors.  
 $\nabla f_1(x) = a^T$        $F_1(x) = 0$        $\nabla f$  is a row vector

$f_2(x) = x^T A x$  with  $A$  symmetric.

$$f_2(x) = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j = \sum_{i=1}^n x_i \sum_{j=1}^n a_{ij} x_j$$

$$\frac{\partial f_2(x)}{\partial x_k} = \sum_{j \neq k} a_{kj} x_j + 2a_{kk} x_k + \sum_{i \neq k} a_{ik} x_i$$

$$= \sum_j a_{kj} x_j + \sum_i x_i a_{ik}$$

$$= (k^{\text{th}} \text{ row of } A) \cdot x + x^T (k^{\text{th}} \text{ col of } A)$$

$$= 2x^T \cdot (k^{\text{th}} \text{ col of } A) \text{ since } A \text{ is symmetric.}$$

So,  $\nabla f_2(x) = 2x^T A$  (a row vector).

Continuing, since  $\frac{\partial f_2(x)}{\partial x_k} = 2 \sum_i x_i a_{ik} = 2 \sum_j a_{kj} x_j$

Then  $\frac{\partial f_2(x)}{\partial x_k \partial x_l} = 2a_{kl} \Rightarrow F_2(x) = 2A$

5.  $f_1(x) = 2x_1^2 + x_2^2 - 3x_1 - x_1x_2$

$$\nabla f_1(x) = (4x_1 - x_2 - 3, -x_1 + 2x_2)$$

FOC for interior points (all points interior here):

$$\nabla f_1(x) = (0, 0) \Rightarrow \begin{aligned} 4x_1 - x_2 - 3 &= 0 \\ -x_1 + 2x_2 &= 0 \end{aligned}$$

Solving these 2 simultaneous linear eqns:

$$x_1 = 6/7 \text{ and } x_2 = 3/7 \text{ satisfies FOC.}$$

Check 2<sup>nd</sup> order conditions:

$$H_1 = \begin{pmatrix} 4 & -1 \\ -1 & 2 \end{pmatrix} \text{ Test for positive-definite by checking determinant of each principal sub-matrix}$$

$$\begin{aligned} \det(4) &= 4 > 0 \\ \det(H_1) &= 7 > 0 \end{aligned} \left. \vphantom{\begin{aligned} \det(4) &= 4 > 0 \\ \det(H_1) &= 7 > 0 \end{aligned}} \right\} H_1 \text{ is positive-definite,}$$

so the point  $(6/7, 3/7)^T$  is a rel. min. pt. of  $f_1(x)$ .

$$f_2(x) = 2x_2^3 + 3x_1^2 + 6x_1x_2 + 12x_1 \quad \text{No constraints.}$$

$$\nabla f_2(x) = (6x_1 + 6x_2 + 12, 6x_1 + 6x_2^2)$$

$$\text{FOC: } 6x_1 + 6x_2 + 12 = 0 \text{ and } 6x_1 + 6x_2^2 = 0.$$

Fortunately, the 1<sup>st</sup> eqn is linear, so  $x_1 = -x_2 - 2$ .

$$\text{Now } 6x_1 + 6x_2^2 = 0 \Rightarrow x_1 + x_2^2 = 0 \Rightarrow -x_2 - 2 + x_2^2 = 0.$$

Using quadratic formula,  $x_2 = 2$  or  $x_2 = -1$ .

For  $x_2 = 2$ ,  $x_1 = -4$  and for  $x_2 = -1$ ,  $x_1 = -1$ .

So, two points meet FOC:  $(-4, 2)^T$  and  $(-1, -1)^T$ .

Check 2<sup>nd</sup> order conditions:

$$H_2 = \begin{pmatrix} 6 & 6 \\ 6 & 12x_2 \end{pmatrix} \quad \begin{aligned} \det(6) &= 6 \\ \det(H_2) &= 72x_2 - 36 \end{aligned}$$

These are possible rel. min. pts.

$(-4, 2)^T$ :  $\det H_2 = 144 - 36 > 0 \Rightarrow$  meets SOSC and is rel min. pt.

$(-1, -1)^T$ :  $\det H_2 = -72 - 36 < 0 \Rightarrow$  fails SOSC and is not a rel min pt.

6.  $\max f(x, y, z) = \frac{xyz}{x+2y+2z^2}$  s.t.  $xy=2$  and  $x, y, z \geq 0$ .  
 substitute:  $x = \frac{2}{y}$  This is OK since  $y \geq 0$  implies  $x \geq 0$ .

Now we have  $\max g(y, z) = \frac{2z}{\frac{2}{y} + 2y + 2z^2} = \frac{z}{\frac{1}{y} + y + z^2}$  s.t.  $y, z \geq 0$   
 Note that  $g(y, z) \geq 0$  for all  $y, z$ . for all  $a \geq 0$  and  $b \geq 0$ .

Since  $a \geq b \iff \frac{1}{a} \leq \frac{1}{b}$ , maximizing  $g$  is equivalent to minimizing  $\frac{1}{g}$ . Letting  $h = \frac{1}{g}$ , we have:

$$\min h(y, z) = \frac{\frac{1}{y} + y + z^2}{z} \text{ s.t. } y, z \geq 0.$$

FONC for interior points:  $\nabla h = 0$

$$0 = \frac{\partial h}{\partial y} = \frac{z(-y^{-2} + 1) - 0}{z^2} = \frac{-\frac{1}{y^2} + 1}{z} \Rightarrow y^2 = 1 \Rightarrow y = 1 \text{ or } y = -1$$

ok

not allowed.

$$0 = \frac{\partial h}{\partial z} = \frac{z(2z) - (\frac{1}{y} + y + z^2)}{z^2} = \frac{z^2 - \frac{1}{y} - y}{z^2} \text{ with } y=1, z^2=2$$

$z = \sqrt{2}$  or  $z = -\sqrt{2}$

ok

not allowed.

So,  $y=1, z=\sqrt{2}$  satisfies FONC and

may be a rel. min. pt. Since it is an interior pt, check 2<sup>nd</sup> order conditions:

$$H = \begin{pmatrix} \frac{2y^{-3}}{z} & \frac{y^{-2}-1}{z^2} \\ \frac{y^{-2}-1}{z^2} & \frac{y^{-1}+y}{z^4} \end{pmatrix} \quad H(1, \sqrt{2}) = \begin{pmatrix} \sqrt{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix}$$

Check for  $H(1, \sqrt{2})$  pos definite:

$$\det(H) = \sqrt{2} > 0 \quad \det(H) = \frac{\sqrt{2}}{2} > 0 \Rightarrow H \text{ pos. def.}$$

So  $y=1, z=\sqrt{2}$  is rel. min. pt. of  $h$  s.t.  $y, z \geq 0$  and so  $(2, 1, \sqrt{2})^T$  is a rel max point of  $f$  s.t.  $x, y, z \geq 0$ .

The value of  $f$  at this point is 0.3536. For any point on boundary ( $x=0$  or  $y=0$  or  $z=0$ )  $f=0$ , so  $(2, 1, \sqrt{2})$  is global max

of  $f$  s.t.  $x, y, z \geq 0$ .