

Addressing Spectrum Congestion by Spectrally-Cooperative Radar Design

Peng Seng Tan

Electrical Engineering & Computer Science Department

University of Kansas

Scope of Presentation

- Introduction
 - Motivation
 - Categories of current solutions/approaches
- Proposed Solution (2-step approach)
 - Spectrally Efficient Waveform Design
 - Results from this step
 - Sparse Spectrum Allocation using Information Theory
 - Results from this step
- Applications of results to Radar System Implementation
- Conclusion

Scope of Presentation

- **Introduction**
 - Motivation
 - Categories of current solutions/approaches
- Proposed Solution (2-step approach)
 - Spectrally Efficient Waveform Design
 - Results from this step
 - Sparse Spectrum Allocation using Information Theory
 - Results from this step
- Applications of results to Radar System Implementation
- Conclusion

Motivation: Resolving Spectrum Congestion issues

- **Rise in demand** for Radio Frequency (RF) spectrum in recent years in wireless communications due to increase in demand in:
 - Mobile Telephony services such as FaceTime and Skype
 - Cable/Satellite TV streaming
 - 5th Generation Mobile Telecommunications Protocol
 - Internet of Things (IOT)
- This imposes a **strain** on current radar systems who maintains **largest share** of RF spectrum

Motivation: Resolving Spectrum Congestion issues

- Leads to **Spectrum Congestion** issues and rise of **Mutual Interference** among systems (e.g. radar versus cell phone) who need to coexist within finite spectrum allocation, i.e. **Spectrum Sharing**
- Main initiative to resolve these challenges rests within the **radar community**
- Question Posed: Does Radar needs **all these spectrum to be fully filled** or can it be just partially filled in an optimal manner ?

Current Approaches

- Presently, resolving the issues associated with spectrum sharing can be broadly classified into 3 categories:
 - Category 1: Design of **Cognitive Radio** to ensure **radar's performance is not degraded**
 - Category 2: Design of **Cognitive Radar** as **main party** responsible in **interference mitigation**
 - Category 3: **Joint design** of both Cognitive Radio/Radar **spectrum allocation and waveforms**
- These categories have also been given acronyms such as the “Three 'A's of Communications – Radar Spectrum Sharing : **Avoid, Accept and Amalgamate**”

Scope of Presentation

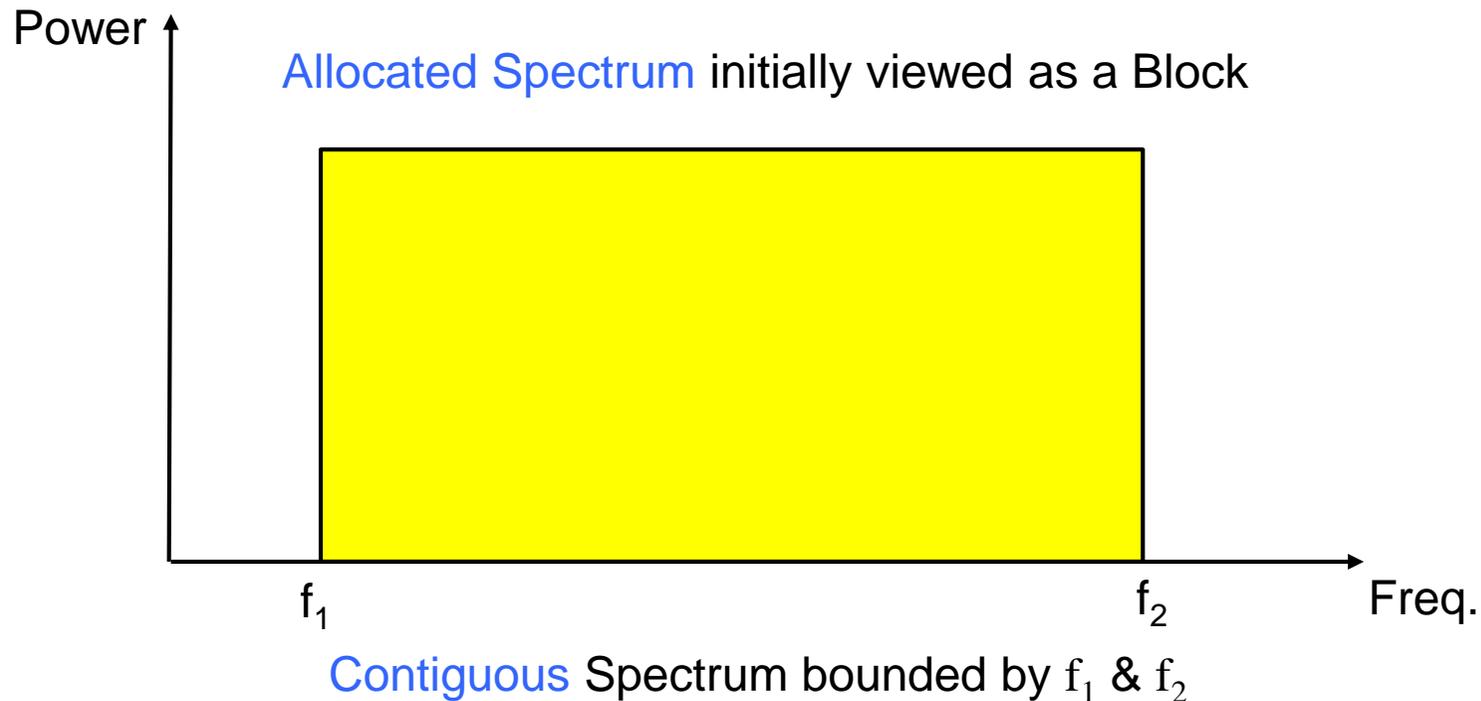
- Introduction
 - Motivation
 - Categories of current solutions/approaches
- **Proposed Solution (2-step approach)**
 - Spectrally Efficient Waveform Design
 - Results from this step
 - Sparse Spectrum Allocation using Information Theory
 - Results from this step
- Applications of results to Radar System Implementation
- Conclusion

Dissertation Research

- Dissertation research is on developing a **2-step** approach **grouped** under the **2nd category** of Cognitive Radar
- **Step 1** involves the design of a **Spectrally Efficient Radar Transmit waveform** so as to **minimize** mutual interference:
 - Built on the existing framework of **Poly-phased Coded Frequency Modulated** (PCFM) waveforms
- **Step 2** involves the design of a **Sparse Spectrum Allocation** algorithm so as to **reduce** radar's **spectrum usage** while **maintaining** range resolution performance
 - An alternative approach to Sparse Frequency Waveform design

Overall Problem Formulation

- The next few slides provides some description of the Proposed Solution achieved via the 2-step approach

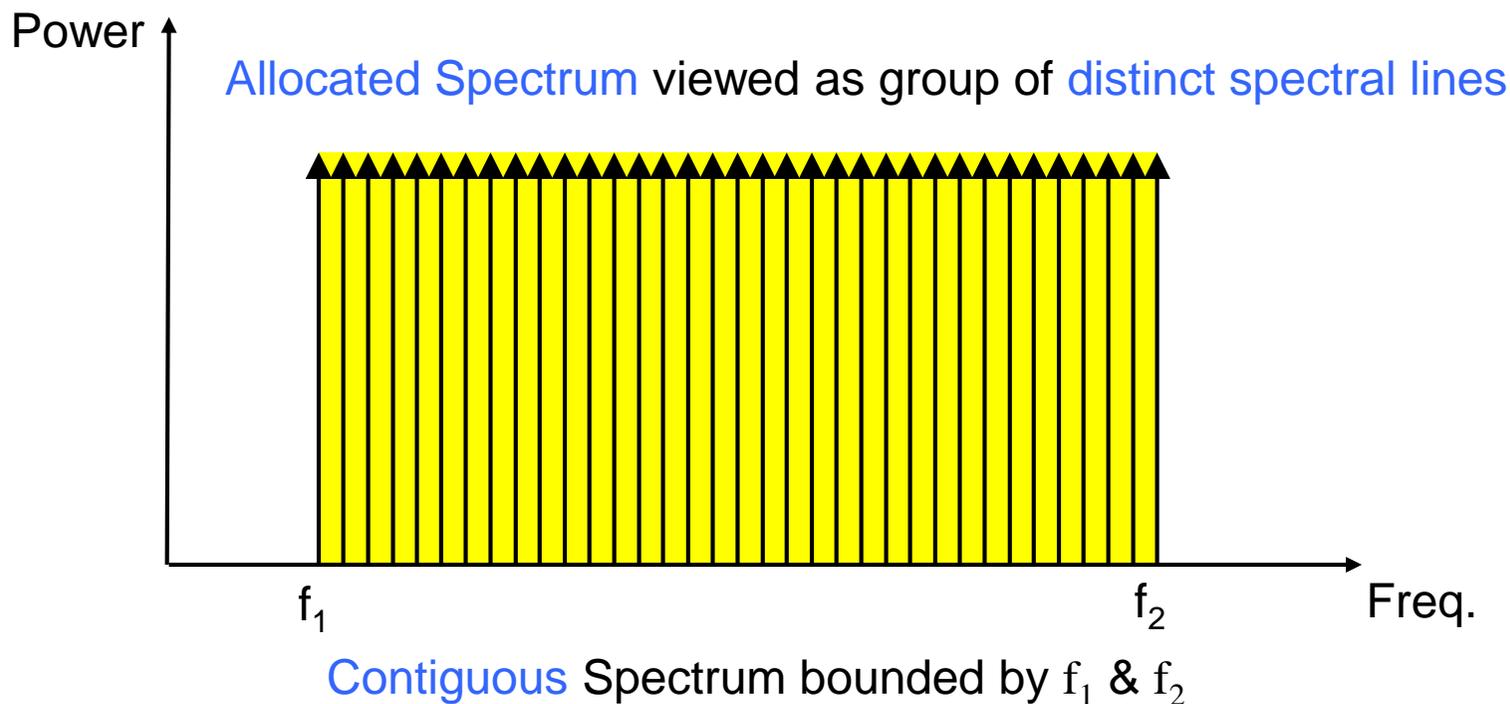


Overall Problem Formulation

- Question: Can we build a radar transmit signal that does not fully utilize the allocated spectrum ?
- How do we evaluate its performance ?
- How do we process this type of sparse radar transmit signal ?

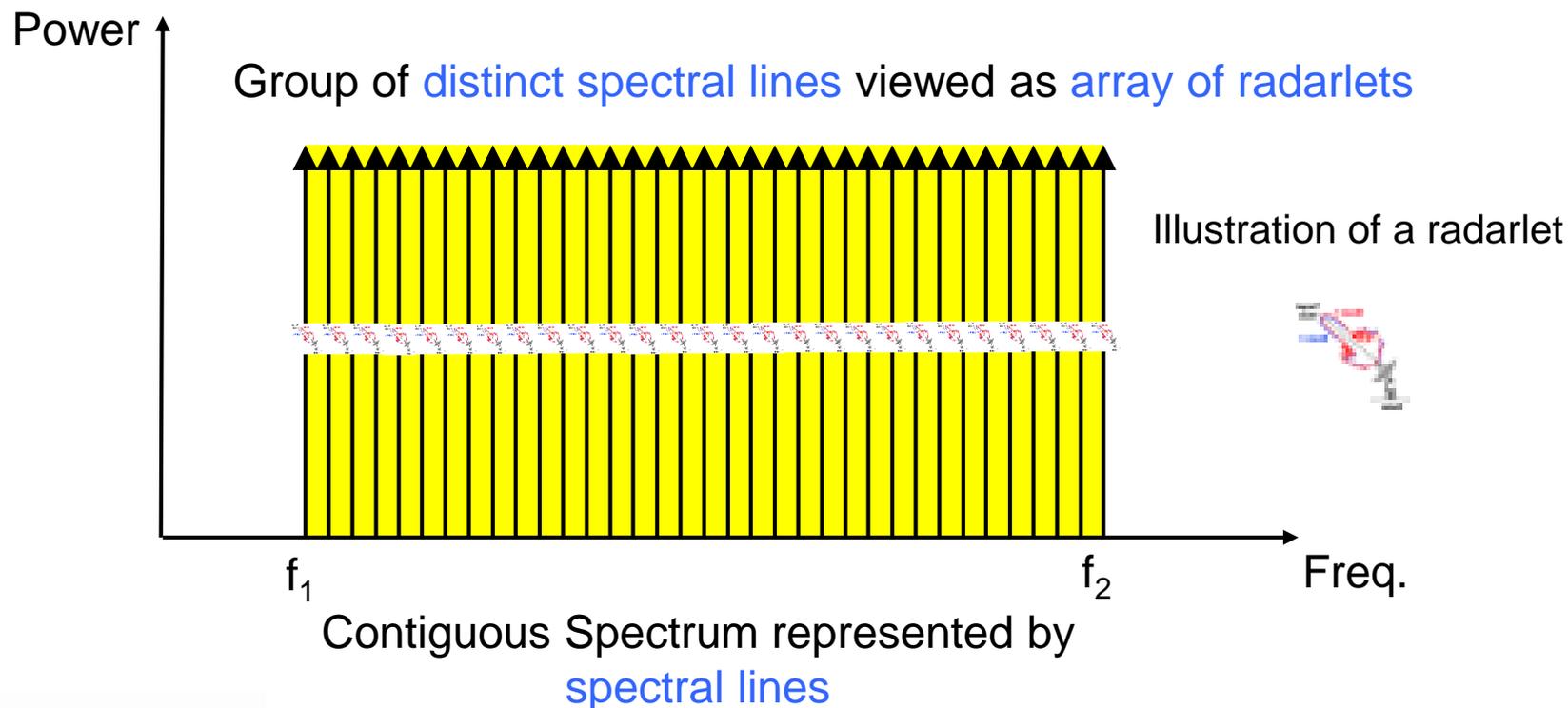
Overall Problem Formulation

- We are going to represent the spectrum by N number of spectral lines, for instance, CW tones or Pulsed Radar



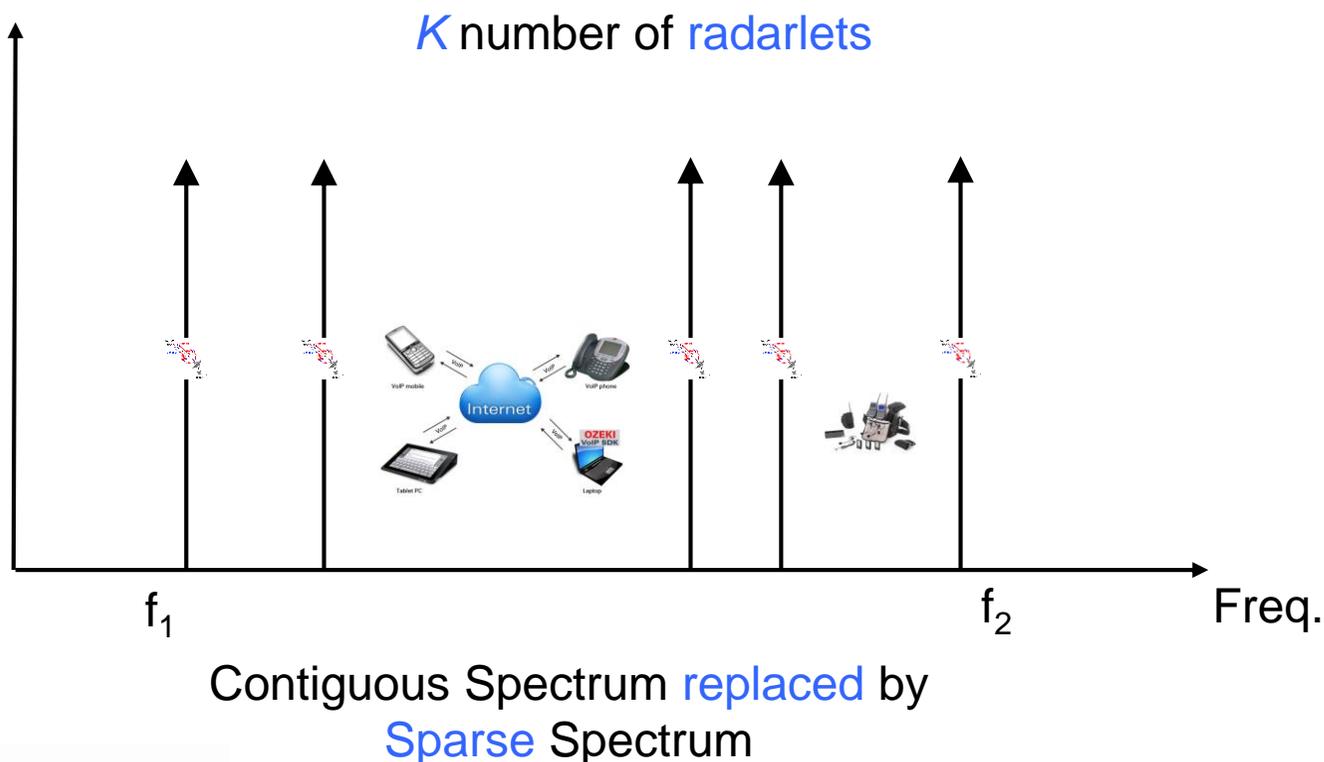
Solution Formulation

- Let this group of N spectral lines represent an array of N radarlets starting with no bandwidth (e.g. CW tones)



Formulation of Two-step approach

- We are going to thin the radarlets from N to K radarlets. The net spectrum usage will be the ratio (K / N)

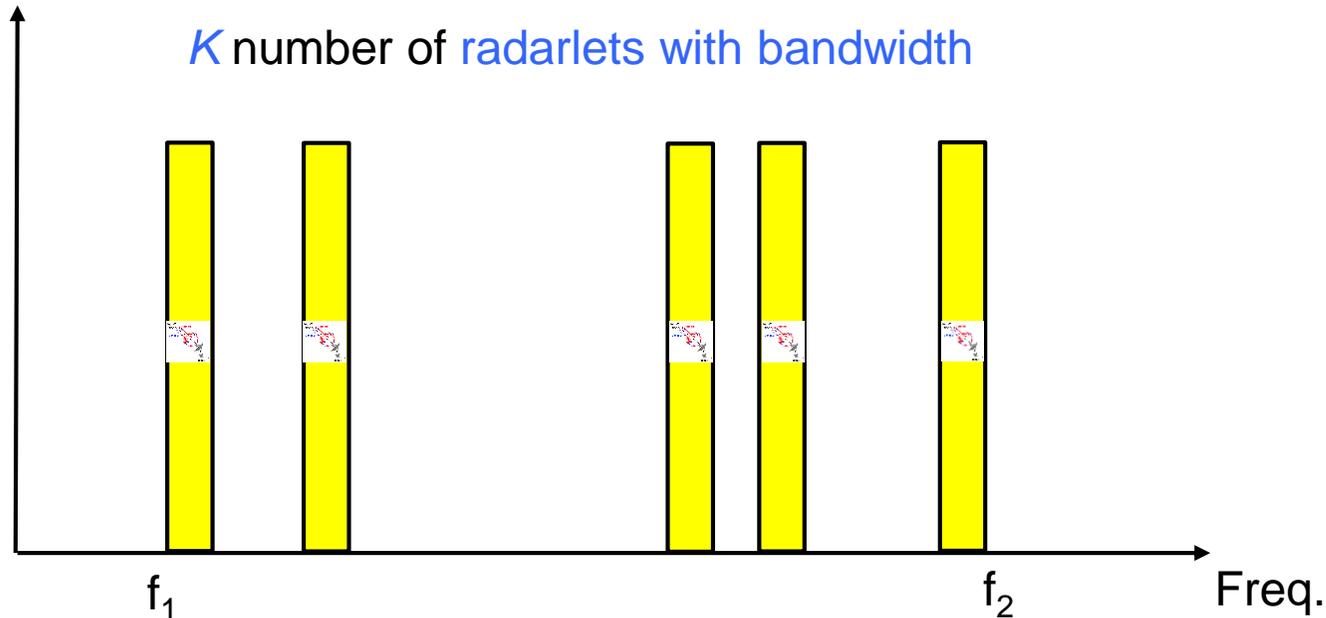


Formulation of Two-step approach

- The locations of the K resulting spectral lines are not confined to integer multiple of the Pulse Repetition Frequency so as to increase the degrees of freedom for the optimization process
- How do we design such a sparse radarlet array ?
- What optimality criteria do we use to determine the locations of this sparse radarlet array ?

Formulation of Two-step approach

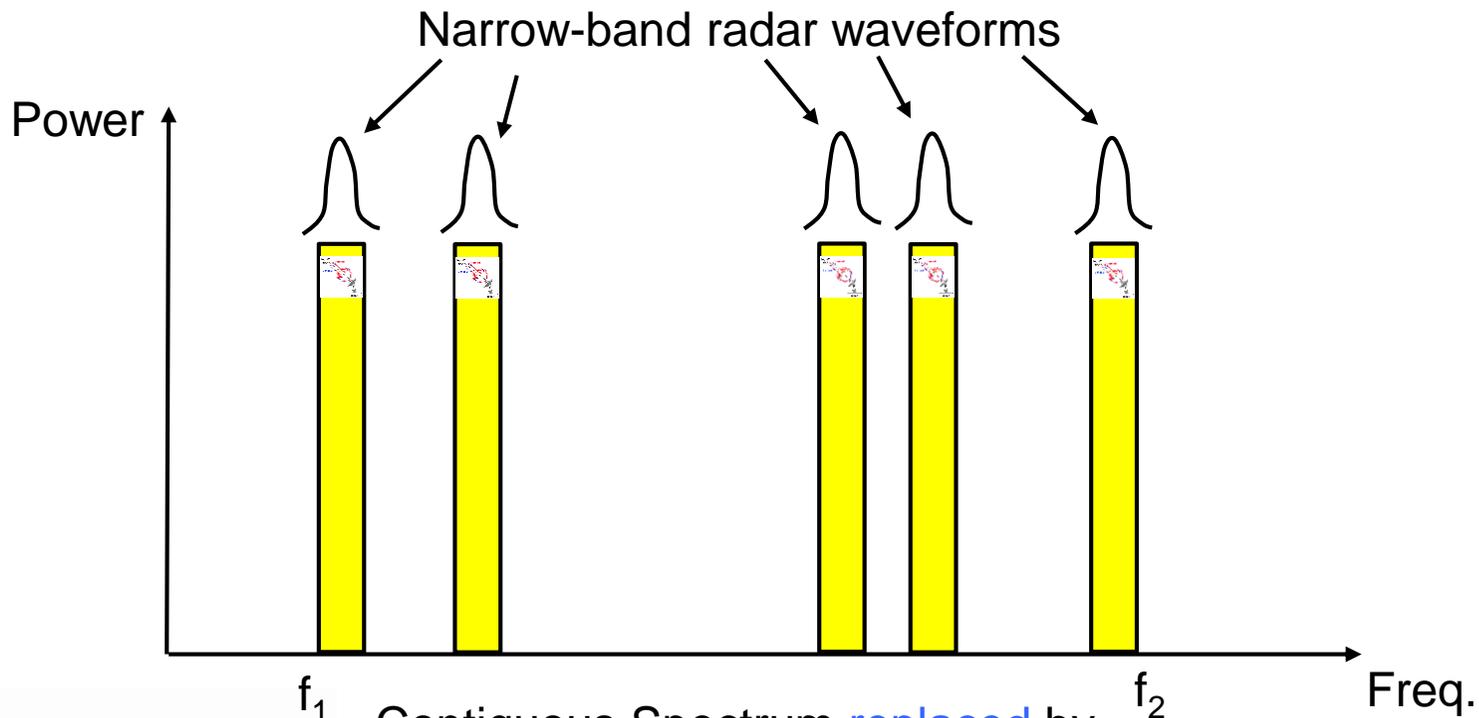
- We are going to **modulate** each of the K radarlet so that each radarlet will possess a **finite bandwidth**



Contiguous Spectrum **replaced** by
Sparse Spectrum

Formulation of Two-step approach

- The **modulated radar waveform** for each radarlet should provide good **spectral containment** properties



Formulation of Two-step approach

- Thus, in addition to determining the locations of the sparse radarlet array, we also want to **confine** the **spectral content** of each radarlet
- This will ensure that the **spectral content** of each radarlet will not **leak** into the spectrum of other systems to become **interference signals**
- Need to select the type of radar waveform that is **both spectrally well-contained** as well as other properties like **low side-lobe** performance

Scope of Presentation

- Introduction
 - Motivation
 - Categories of current solutions/approaches
- Proposed Solution (2-step approach)
 - Spectrally Efficient Waveform Design
 - Results from this step
 - Sparse Spectrum Allocation using Information Theory
 - Results from this step
- Applications of results to Radar System Implementation
- Conclusion

Higher-order PCFM

Problem Setup

Background

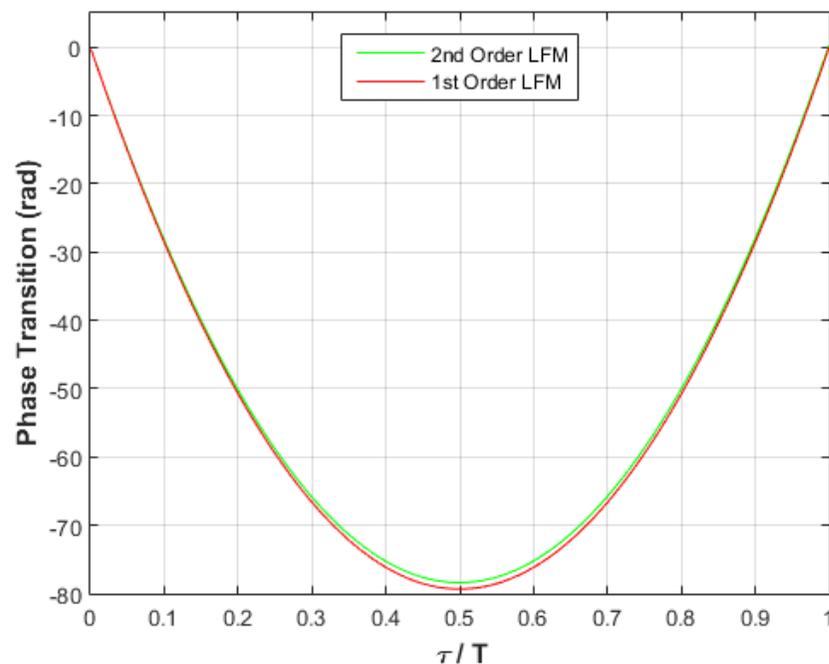
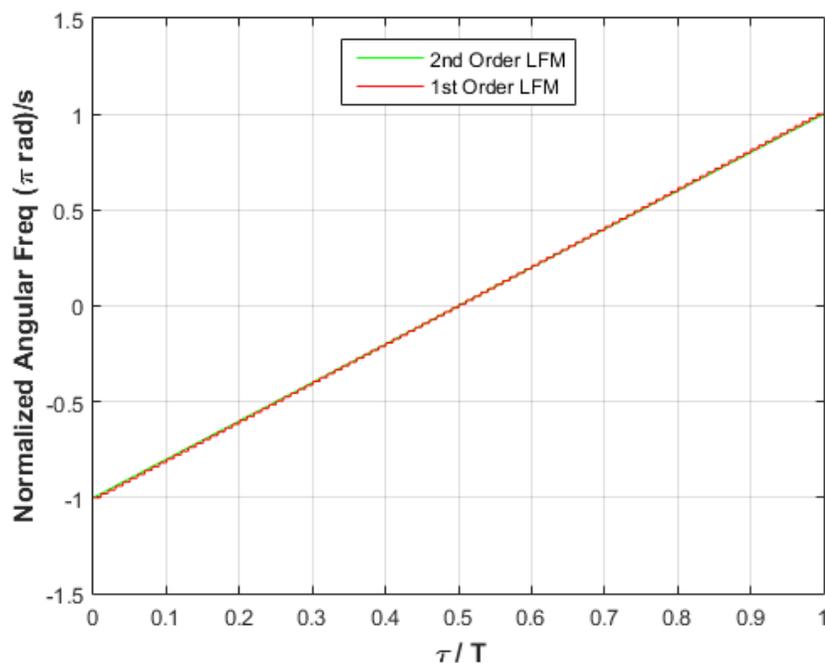
- Polyphase-coded Frequency Modulated (PCFM) radar waveforms are realized by a variant of Continuous Phase Modulation (CPM) signals from communications
 - Converts an arbitrary polyphase code into a **physically-realizable** FM waveform
- PCFM waveforms are:
 - **Spectrally efficient** – phase is continuous and differentiable thus providing good spectral containment
 - **Power efficient** – constant modulus
 - Able to achieve **low autocorrelation sidelobes** relative to time-bandwidth (BT) product where B is the **3 dB** bandwidth

Higher-order PCFM Waveform

- Previous research demonstrated PCFM waveforms generated from Polyphase codes akin to **first-order** hold in phase (where traditional codes represent a **zero-order** hold)
- In my research, I have investigated the **Higher-order** PCFM waveform implementation as the prospective benefits are:
 - Offers additional degrees-of-freedom (DOF) in waveform design **without any increase** in the *BT* product
 - Higher-order terms produce **smoother phase trajectory**, maintaining good spectral containment
 - Allows for the possibility to **combine multiple orders** to obtain even lower autocorrelation sidelobes

Higher-order PCFM Waveform

- As an example, let's examine the plots of instantaneous frequency and phase of a LFM signal generated using first-order PCFM waveform versus second-order PCFM waveform



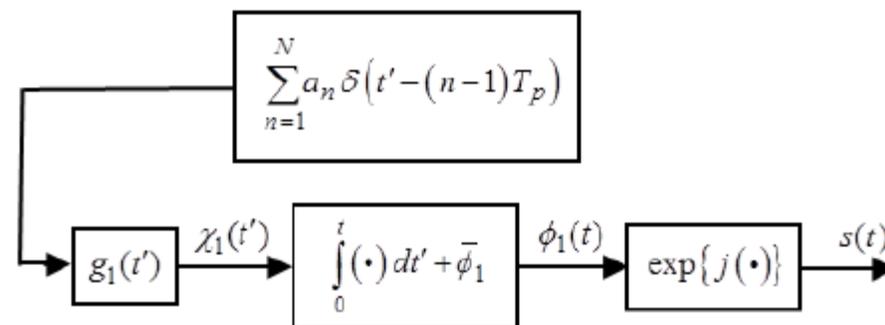
1st Order Implementation

- The 1st order PCFM implementation to realize phase function $\phi_1(t)$:

$$\chi_1(t) = \sum_{n=1}^N a_n g_1(t - (n-1)T_p)$$

$$\phi_1(t) = \int_0^t \chi_1(t') dt' + \bar{\phi}_1$$

- $\chi_1(t)$ is the 1st order coded function produced by the N “**phase change**” **code** values a_n
- $g_1(t)$ is a shaping filter (e.g. rectangular)
- T_p is the duration of one phase change
- $\bar{\phi}_1$ is the initial phase value (arbitrary)



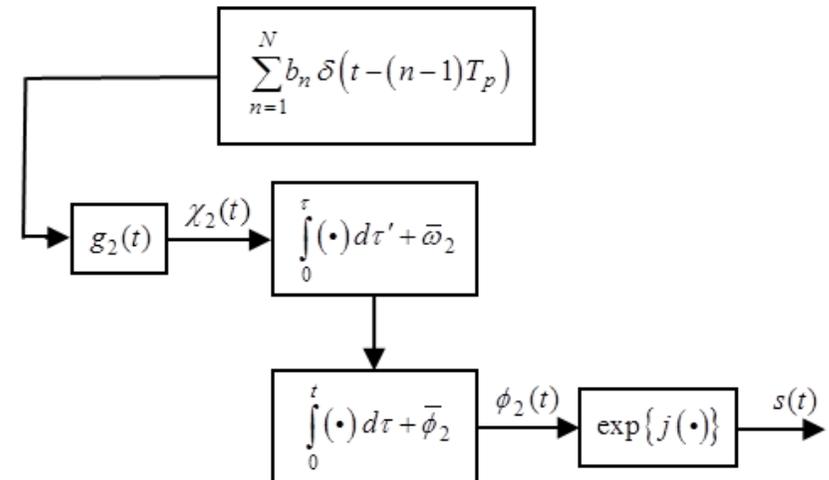
2nd Order PCFM Implementation

- Generalize to 2nd order PCFM implementation for phase function $\phi_2(t)$:

$$\chi_2(t) = \sum_{n=1}^N b_n g_2(t - (n-1)T_p)$$

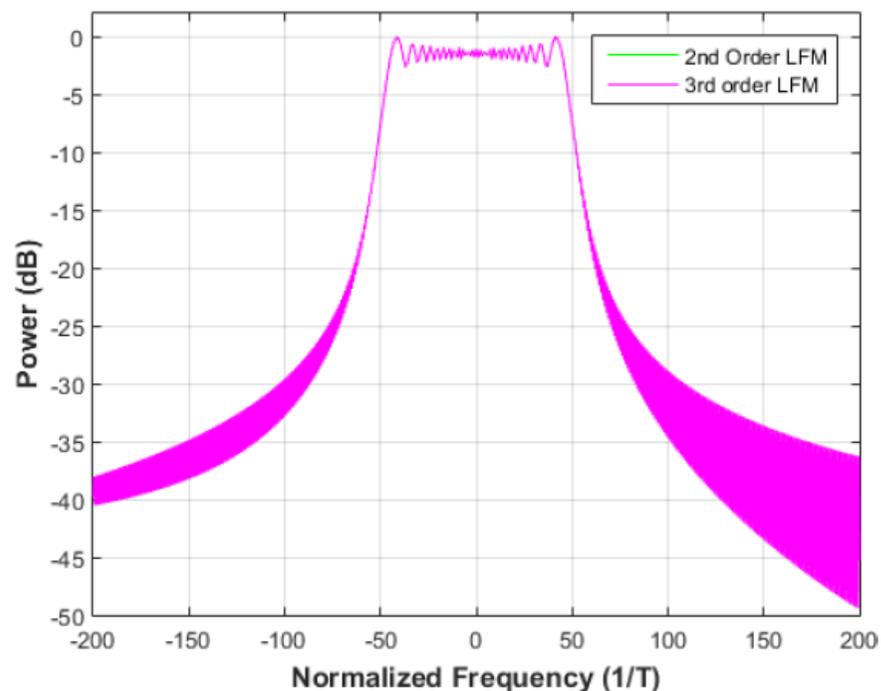
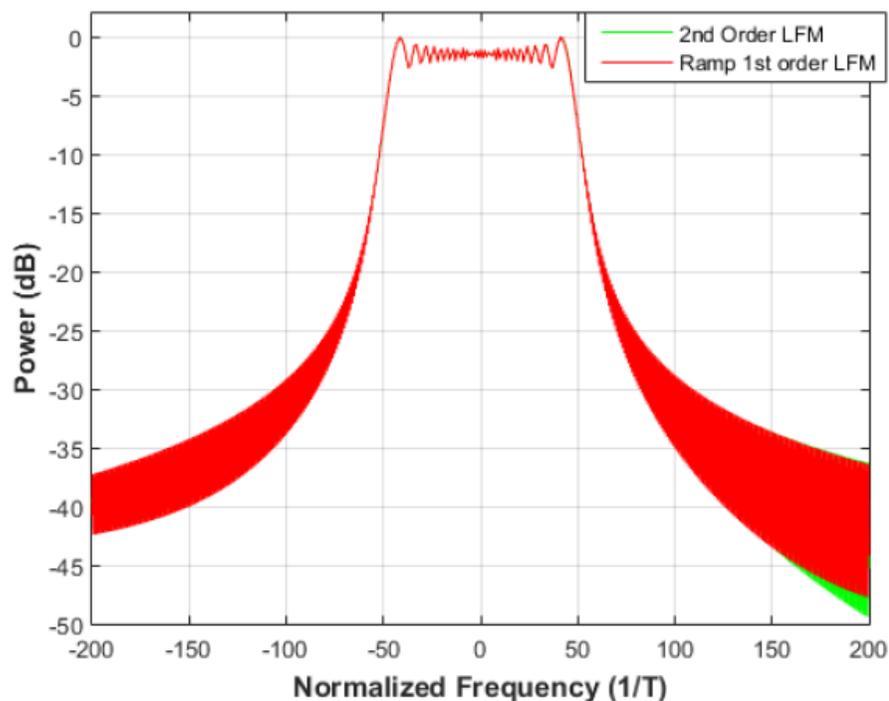
$$\phi_2(t) = \int_0^t \int_0^{t'} \chi_2(t'') dt'' dt' + \int_0^t \bar{\omega}_2 dt' + \bar{\phi}_2$$

- $\chi_2(t)$ is the 2nd order coded function produced by N “frequency change” code values b_n
- $g_2(t)$ is a shaping filter
- $\bar{\omega}_2$ & $\bar{\phi}_2$ are initial frequency & phase



Relationships between different orders of PCFM

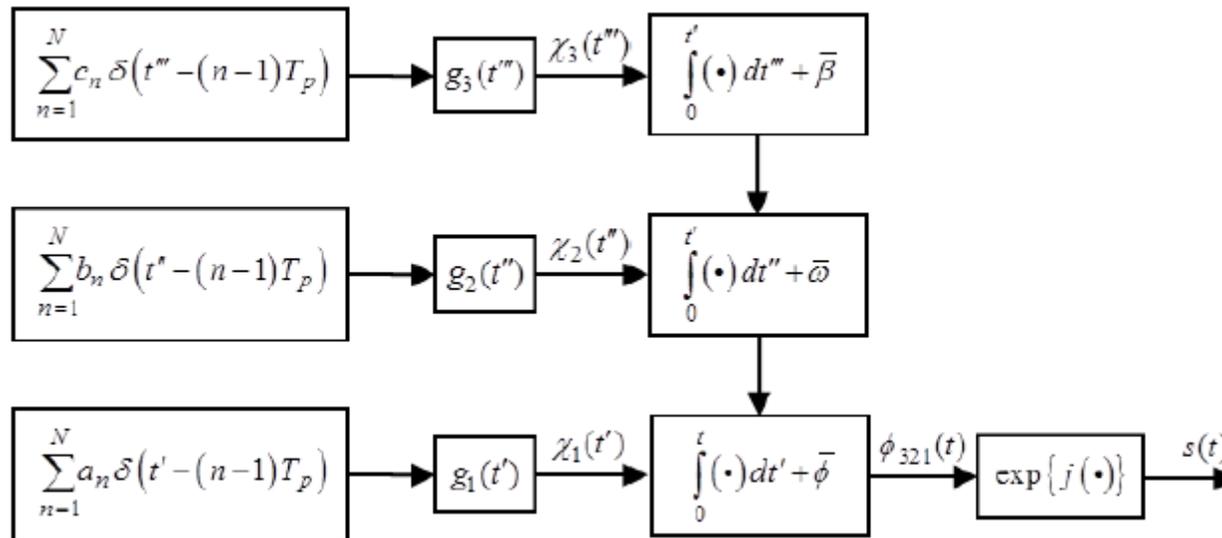
- For instance, we can generate an exact LFM waveform of $BT = 100$ using either 1st, 2nd or 3rd order of implementations



Multi-Order PCFM Implementation

- The 1st and higher orders of implementation can also be combined to become a multiple-order of implementation

$$\phi_{321}(t) = \int_0^t \chi_1(t') dt' + \int_0^t \int_0^{t'} \chi_2(t'') dt'' dt' + \int_0^t \int_0^{t'} \int_0^{t''} \chi_3(t''') dt''' dt'' dt' \\ + \int_0^t \int_0^{t'} \bar{\beta}_{321} dt'' dt' + \int_0^t \bar{\omega}_{321} dt' + \bar{\phi}_{321}$$



Higher-Order Optimization Process

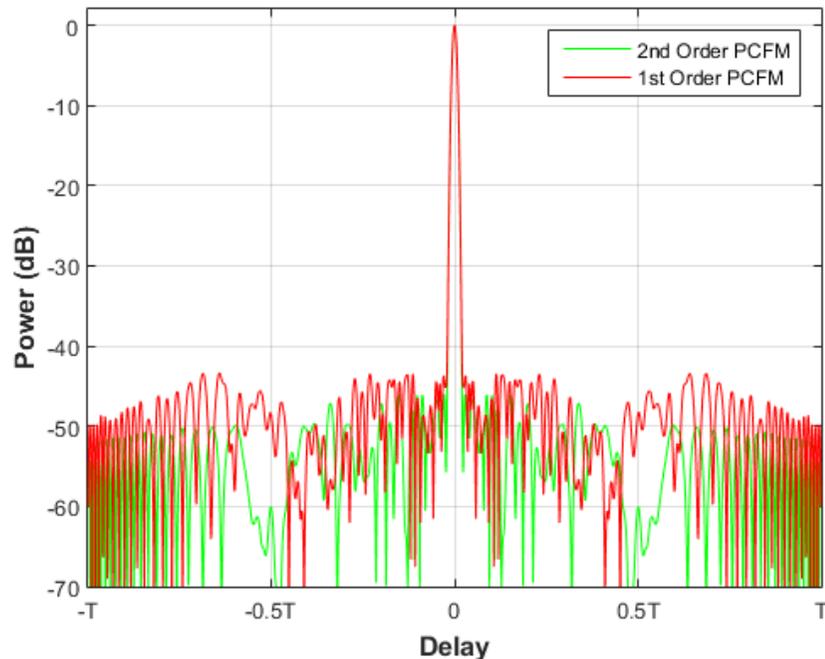
- When performing optimization for higher-order implementation such as second, third, fourth etc., the *Frequency Template Error (FTE)* metric is used to maintain spectral containment
- The greedy optimization approach denoted as “**performance diversity**” combining PSL, ISL & FTE metrics is used to optimize the higher-order PCFM codes
 - Multiple metrics help to avoid local minima via greedy search
 - Global optimality not guaranteed, but finds “good enough” local optimality
- When combining multiple orders, optimization may be performed **jointly** (i.e. simultaneously), or **sequentially** across the different orders

Higher-order PCFM

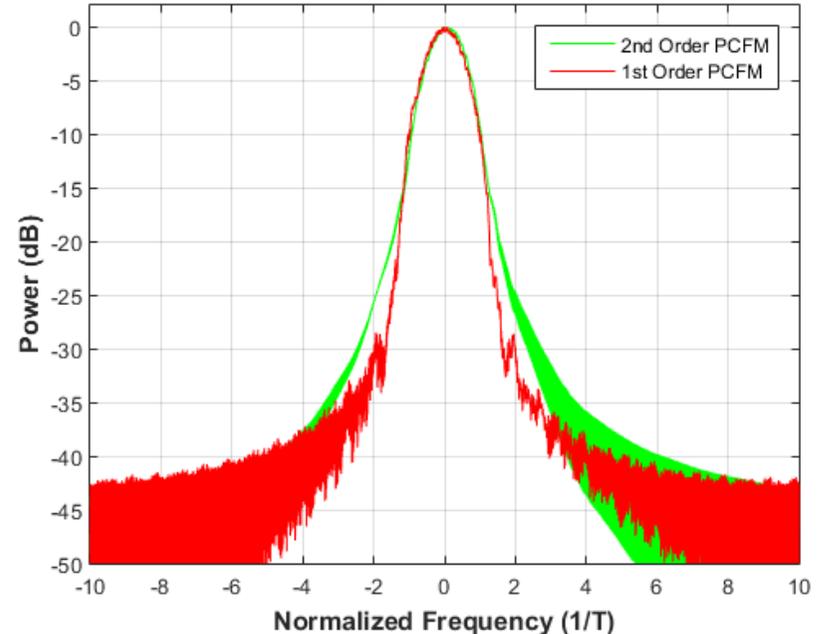
Simulation Results

2nd order PCFM (Standalone)

- Let's examine the 1st & 2nd order PCFM implementations after optimization for $BT = 100$



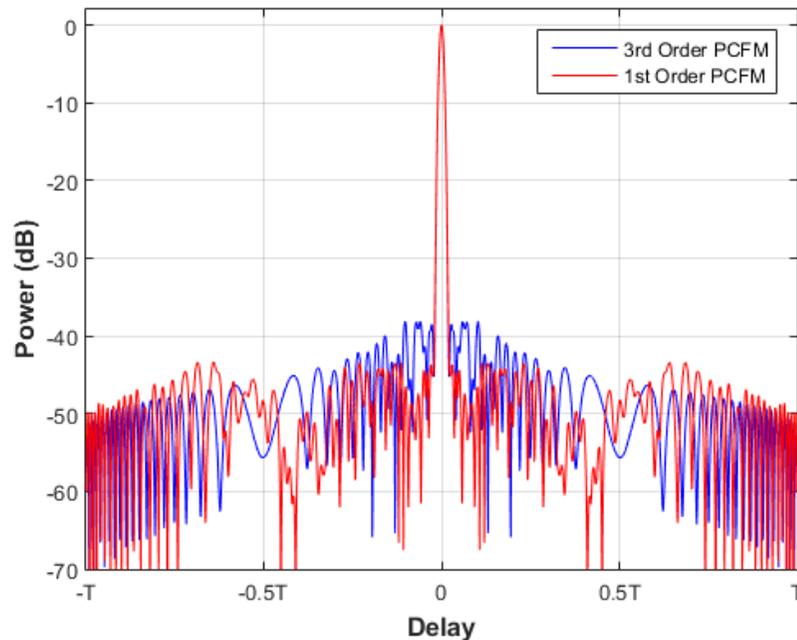
Autocorrelation of 1st & 2nd order optimized waveforms with $BT = 100$



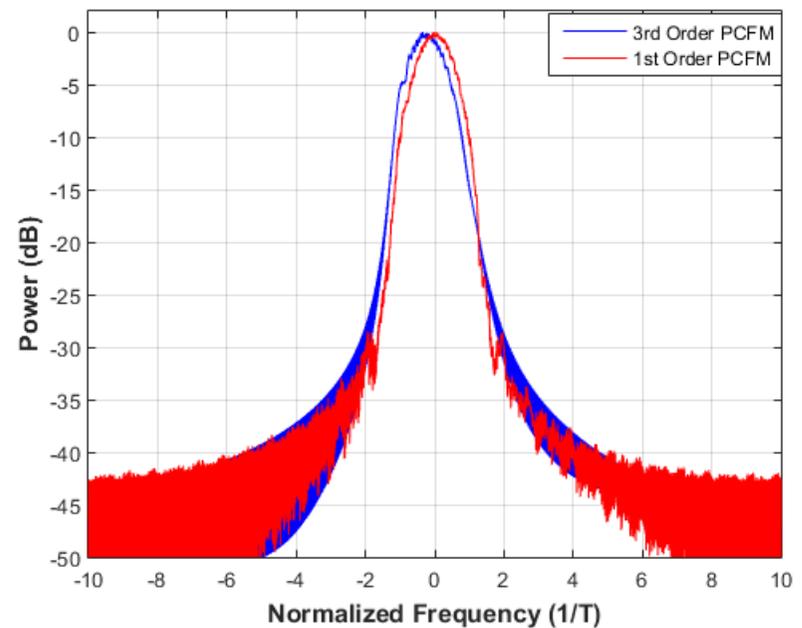
Spectral Content of 1st & 2nd order optimized waveforms with $BT = 100$

3rd order PCFM (Standalone)

- Likewise, we examine the 1st & 3rd order PCFM implementations after optimization



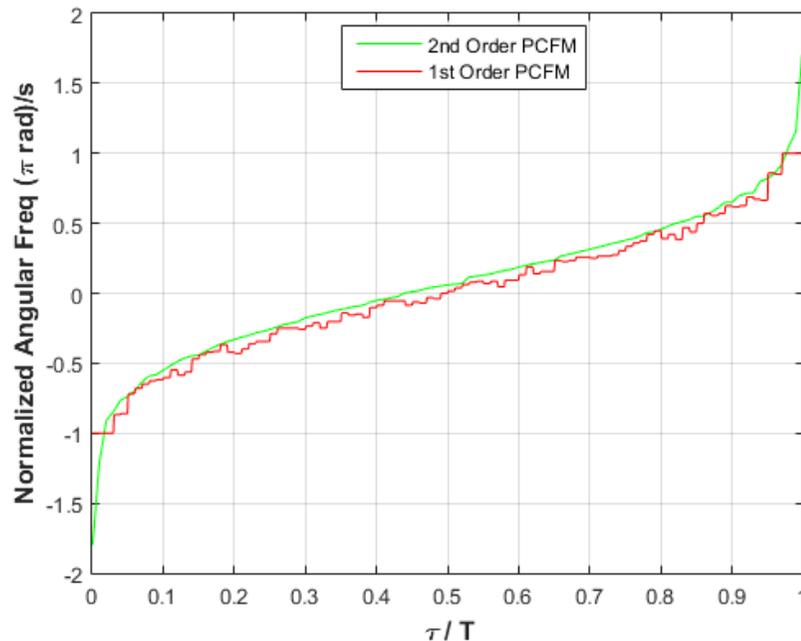
Autocorrelation of 1st & 3rd order optimized waveforms with $BT = 100$



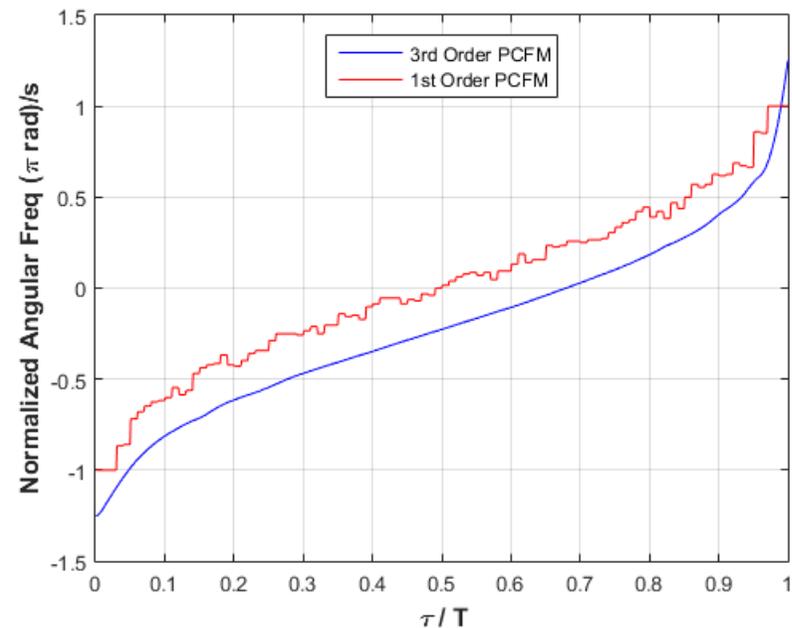
Spectral Content of 1st & 3rd order optimized waveforms with $BT = 100$

Instantaneous Freq. of Standalone PCFM

- Let's also examine the Instantaneous frequency of 1st, 2nd & 3rd order PCFM implementations after optimization



Instantaneous frequency of 1st & 2nd order optimized waveforms with $BT = 100$



Instantaneous frequency of 1st & 3rd order optimized waveforms with $BT = 100$

Summary of Individual Optimization Performance

- PSL and ISL values for optimizing $BT = 100$ waveforms for 1st, 2nd & 3rd order representations
 - Note: **individually optimized** (i.e. **not combined with other orders**)

PSL & ISL for 1st, 2nd & 3rd order optimized waveforms for $BT = 100$

	1 st order	2 nd order	3 rd order	HFM bound
PSL (dB)	-43.4	-46.0	-38.1	-43.0
ISL (dB)	-59.5	-63.5	-57.4	

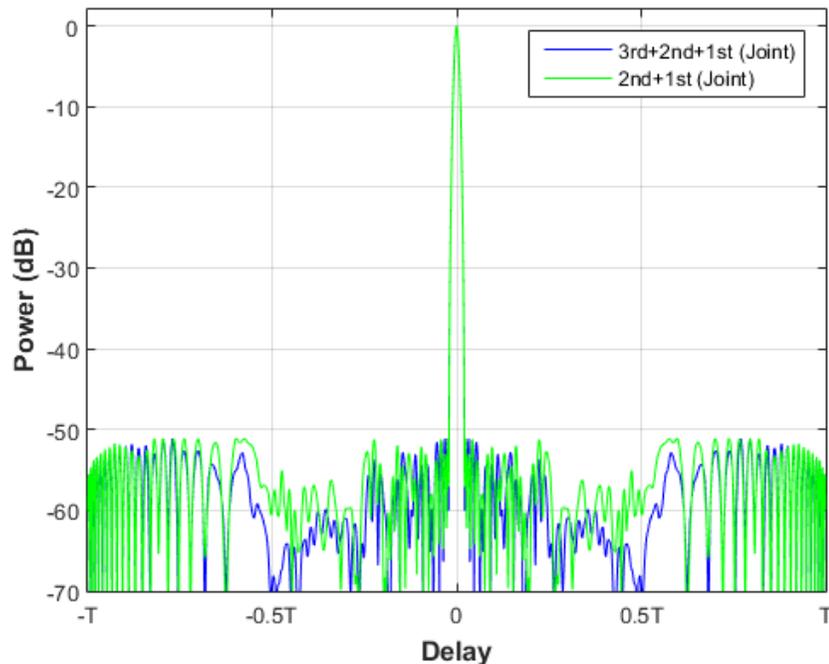

Original PCFM
implementation

- Useful benchmark: **hyperbolic FM (HFM)** bound on PSL: $-20 \log_{10}(BT) - 3$ dB

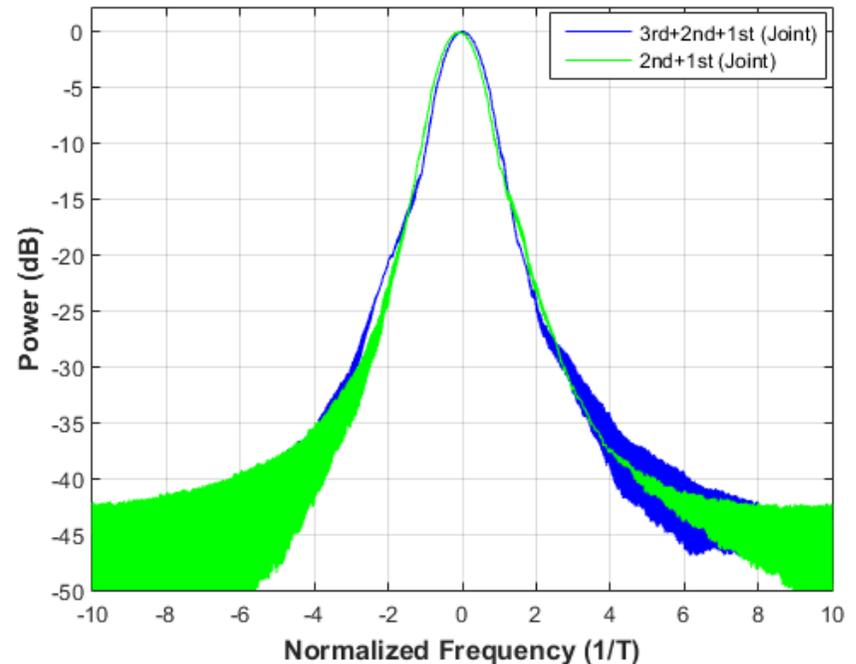
T. Collins & P. Atkins, "Nonlinear frequency modulation chips for active sonar" *IEEE Proc. Radar, Sonar & Navigation*, Dec 1999.

Multi-order PCFM (Combination)

- Let's examine the joint optimization of ($3^{\text{rd}}+2^{\text{nd}}+1^{\text{st}}$) orders versus ($2^{\text{nd}}+1^{\text{st}}$) orders



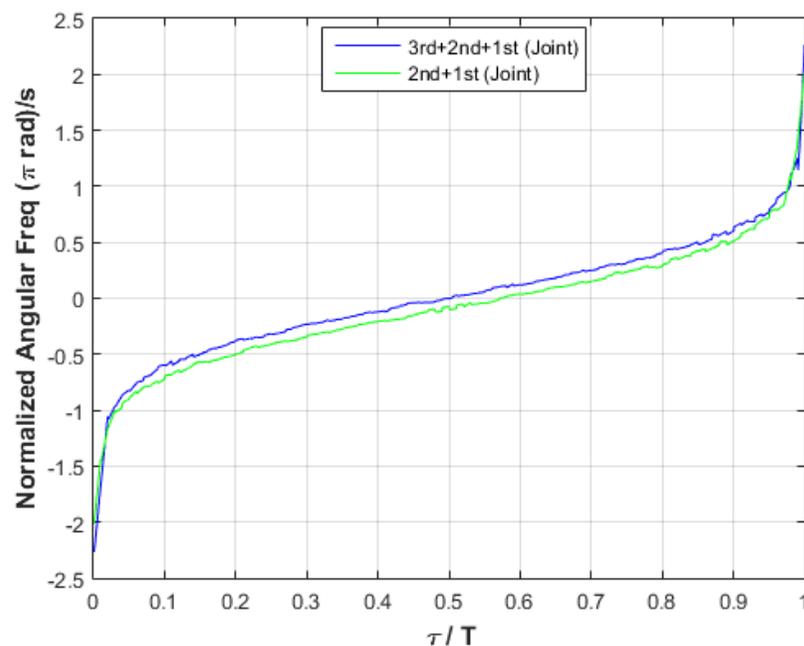
Autocorrelation of jointly optimized waveforms with $BT = 100$



Spectral Content of jointly optimized waveforms with $BT = 100$

Instantaneous Freq. of Multi-order PCFM

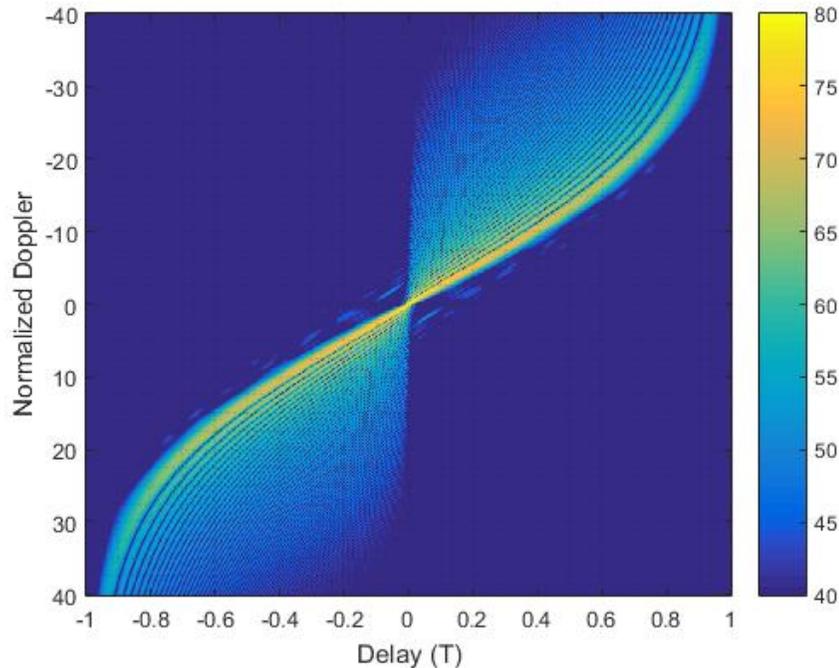
- Let's also examine the Instantaneous frequency of these multi-order PCFM implementations after optimization



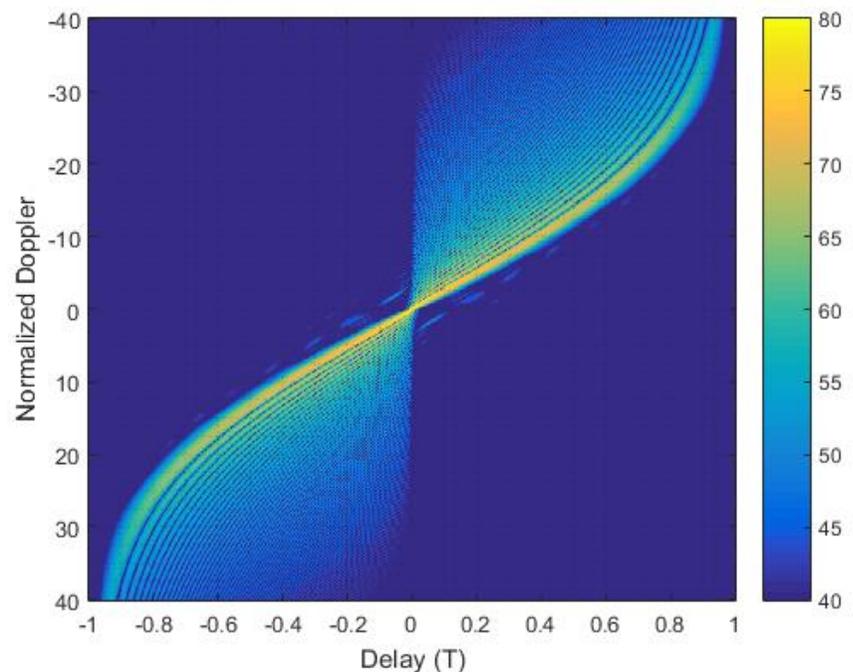
Instantaneous frequency of jointly 1st, 2nd & 3rd order versus of jointly 1st & 2nd order optimized waveforms

Multi-order PCFM (Combination)

- We also examine the ambiguity plots of these two multi-order PCFM waveforms



Ambiguity function of jointly 1st & 2nd order optimized waveforms with $BT = 100$



Ambiguity function of jointly 1st, 2nd & 3rd order optimized waveforms with $BT = 100$

Summary of Multi-Order Performance

- The **ordering** of sequential optimization was based on the observation of how much **each contributes to sidelobe reduction individually**
- Based on these results, **joint** optimization appears **marginally superior** to sequential optimization for the multi-order PCFM implementations

PSL & ISL for sequential and joint optimization of multiple orders for $BT = 100$

	Joint 1 st & 2 nd orders	Joint 1 st , 2 nd & 3 rd orders	Seq. 1 st & 2 nd orders	Seq. 1 st , 2 nd & 3 rd orders
PSL (dB)	-51.1	-51.1	-50.7	-51.2
ISL (dB)	-66.4	-67.9	-66.0	-66.8

Scope of Presentation

- Introduction
 - Motivation
 - Categories of current solutions/approaches
- Proposed Solution (2-step approach)
 - Spectrally Efficient Waveform Design
 - Results from this step
 - **Sparse Spectrum Allocation using Information Theory**
 - **Results from this step**
- Applications of results to Radar System Implementation
- Conclusion

Sparse Spectrum Allocation

Problem Setup

Problem Setup

- Let's view all the frequencies as measurements taken by the K radarlets in **frequency** domain
- The frequency measurements can be represented by the following **measurement model**:

$$\mathbf{v} = \mathbf{H}\boldsymbol{\gamma} + \mathbf{n}$$
$$\mathbf{H} = [\mathbf{h}_1, \mathbf{h}_2, \dots, \mathbf{h}_i, \dots], i = 1 \dots M$$

- \mathbf{H} is the **linear operator** that relates the **radar propagation** to the **resolution cell** γ_i and back to the **receiver**
- This is the well known **Linear model**

Cramèr-Rao Bound (CRB)

- We want to perform estimation of the radar range profile $\boldsymbol{\gamma} = [\gamma_1, \gamma_2, \dots, \gamma_m]$ from measurements made by the radarlet array
- Now, **CRB** provides a lower bound on estimation error variance for any **unbiased** estimator
- Also, CRB is equal to the inverse of the **Fisher Information matrix \mathbf{J}** of the measurements:

$$\mathbf{J} = (\mathbf{H}'\mathbf{K}_n^{-1}\mathbf{H} + \mathbf{K}_\gamma^{-1})$$

\mathbf{K}_γ : A prior Covariance matrix of the vector $\boldsymbol{\gamma}$

\mathbf{K}_n : Noise Covariance matrix due to the measurements noise vector \mathbf{n}

Cramèr-Rao Bound (CRB)

- For an **efficient** estimator such as the Minimum Mean Square Error estimator (**MMSE**), when applied to a **Linear model**, the **error covariance** \mathbf{K}_ε will be **equal** to the CRB
- Next, let's denote the Fisher Information matrix from K radar frequency measurements as \mathbf{J}_K
- Also, let's denote the Fisher Information matrix from $(K-1)$ radar frequency measurements as \mathbf{J}_{K-1}

Marginal Fisher Information

- Therefore, for the k^{th} frequency measurement, the Marginal Fisher Information (MFI) matrix is defined as the **nonnegative definite** matrix $\Delta\mathbf{J}(K)$:

$$\Delta\mathbf{J}(K) = \mathbf{J}_{K-1}^{-1} - \mathbf{J}_K^{-1}$$

- From $\Delta\mathbf{J}(K)$, the MFI computed from the k^{th} frequency measurement is given as:

$$\begin{aligned} MFI &= \frac{1}{M} \times \text{Tr}(\Delta\mathbf{J}(K)) \\ &= \frac{1}{M} \times \left[\text{Tr}(\mathbf{J}_{K-1}^{-1}) - \text{Tr}(\mathbf{J}_K^{-1}) \right] \\ &= \frac{1}{M} \times \left[\text{Tr}(\mathbf{K}_{\varepsilon(K-1)}) - \text{Tr}(\mathbf{K}_{\varepsilon(K)}) \right] \end{aligned}$$

Marginal Fisher Information

- The MFI can be viewed as a measure of the **unique** or new **information** provided after adding the k^{th} measurement
- The new information will help to further **reduce** the **uncertainty** in estimating the radar range profile γ
- In another words, the error variances within \mathbf{K}_ε will be reduced with the new information

Sparse Spectrum Allocation

- Assuming that the contiguous spectrum consists of N radar frequencies & using the MFI as an **optimization metric**, a **Sparse Spectrum Allocation** algorithm can be developed for determining:
 - Locations of K out of N possible radarlet frequencies ($K < N$) that provides the least estimated error variances for that value of K
 - Optimization process (OP) is performed for one frequency at a time and will complete one iteration when all K radarlet frequencies are determined
 - OP can also be performed for one group of Q frequencies at a time ($K = P \times Q$) and will complete one iteration when all P groups of radarlet frequencies are determined

Sparse Spectrum Allocation

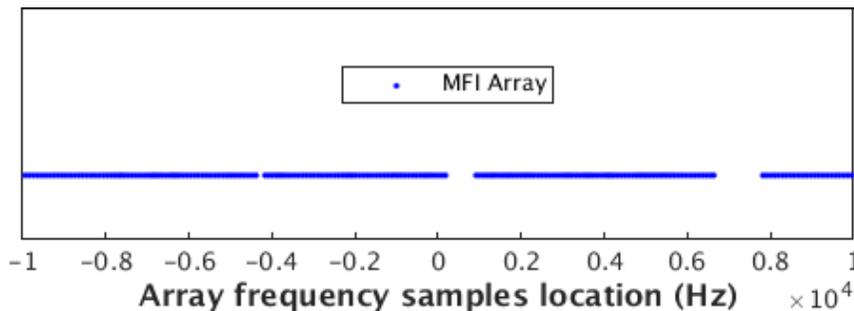
- The algorithm will **continue** in its iterations until **no single** frequency location or **a group** of frequency locations **can be changed further** to obtain **additional MFI**
- The spectrum corresponding to the remaining $(N - K)$ radar frequencies can then be released for **reuse**

Sparse Spectrum Allocation

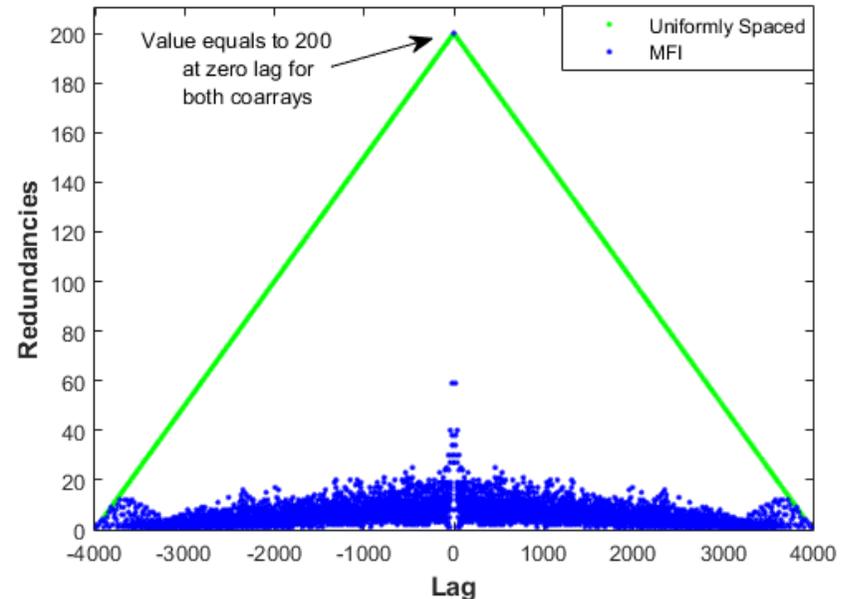
Simulation Results

Sparse Spectrum Allocation (SSA) Results

- Using the MFI measure as the metric of optimization, the sparse frequency array obtained for single frequency location insertion (1st approach) is as shown below for 50% spectrum usage



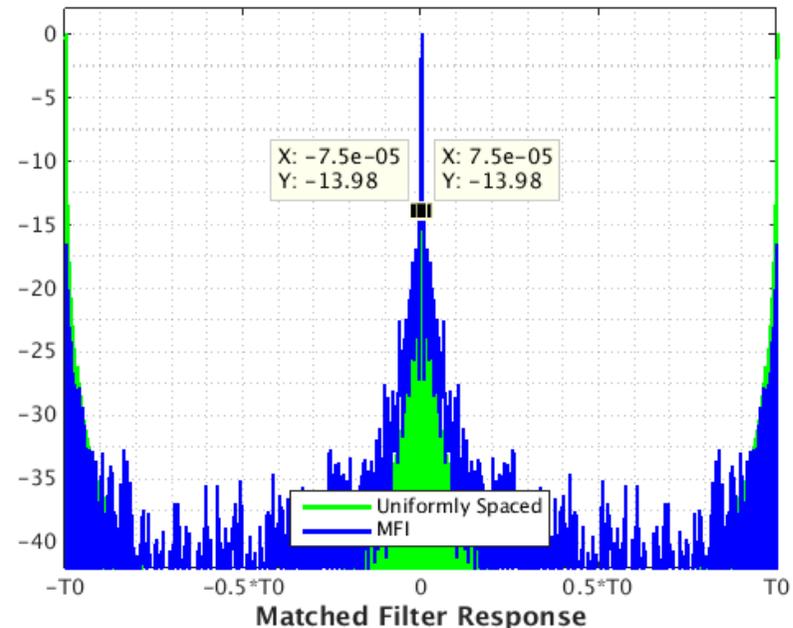
Frequency locations for 50% of spectrum usage



Coarrays from Sparse frequency array and Uniformly-spaced frequency array

Matched Filter Response of SSA Results

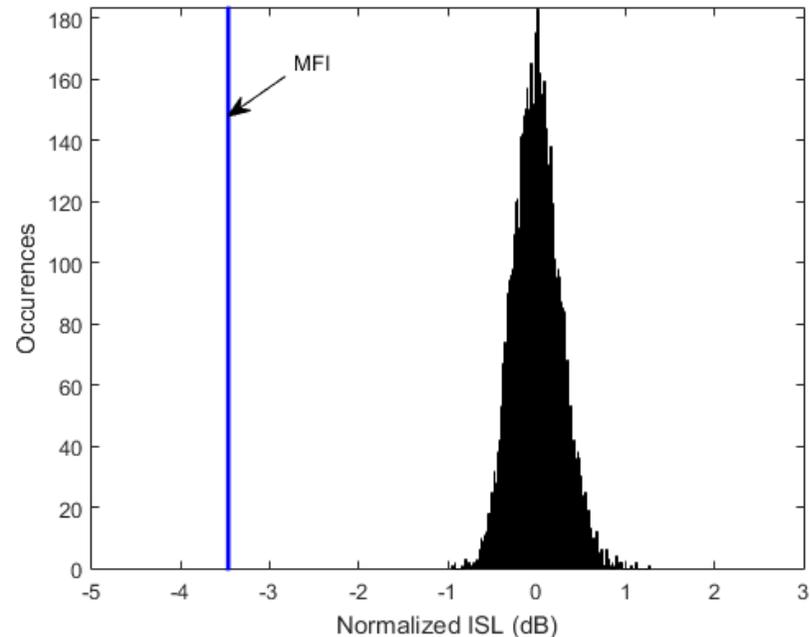
- To investigate the estimation error variances obtained using the previous sparse frequency array, we perform a **Matched Filter** operation
- Resulting plot is analogous to beam pattern obtained using Delay-Sum beamformer as weight vector
- Although it has higher side-lobes compared to uniformly-spaced sampling, but there are **no grating lobes**



Matched Filter response from Sparse frequency array versus Uniformly-spaced frequency array

ISL of SSA Results versus Randomly-spaced

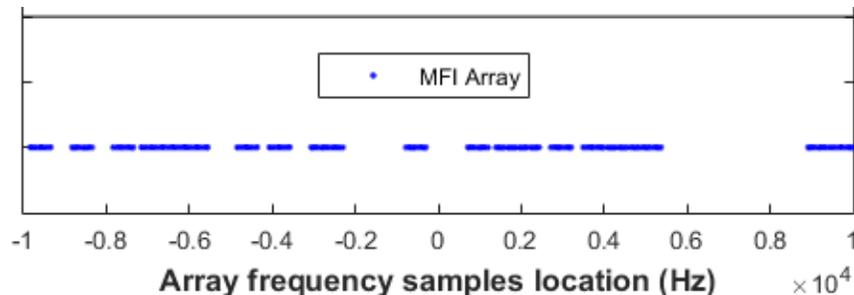
- Next, the Integrated Sidelobe level (ISL) obtained from the SSA is benchmarked against that obtained from a **randomly-spaced** frequency array
- Results obtained from **10000 trials** of randomly-spaced frequency array are plotted using a histogram
- The ISL obtained from SSA is at least **13 σ** away from the mean value of the randomly-spaced frequency array



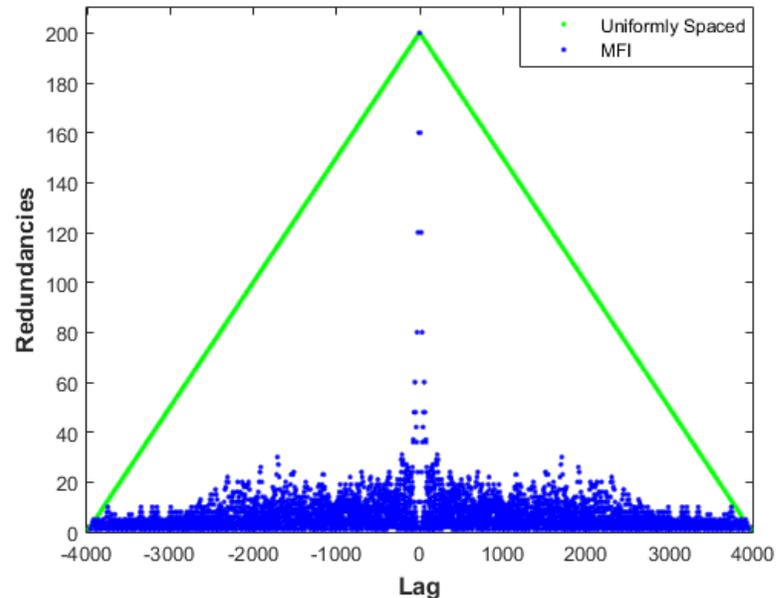
Error variances from Sparse frequency array versus randomly-spaced frequency array

SSA Results (Block implementation)

- To improve the utilization of the unused spectrum, the K radarlet frequencies is grouped into frequency blocks of equal sizes (2nd approach) and results are shown below for 50% spectrum usage



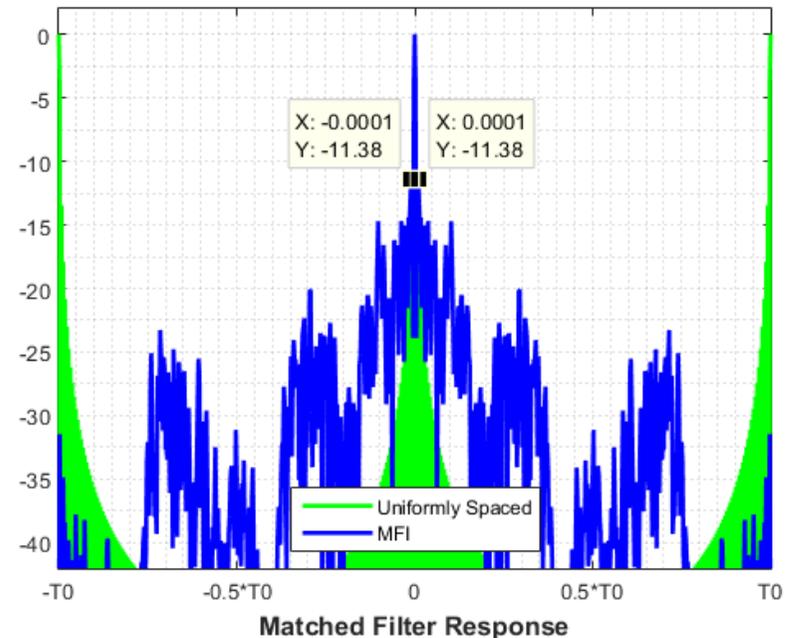
Block size of 1.25% each (50% of spectrum usage)



Coarrays from Sparse frequency array (block implementation) and Uniformly-spaced frequency array

SSA Results (Block implementation)

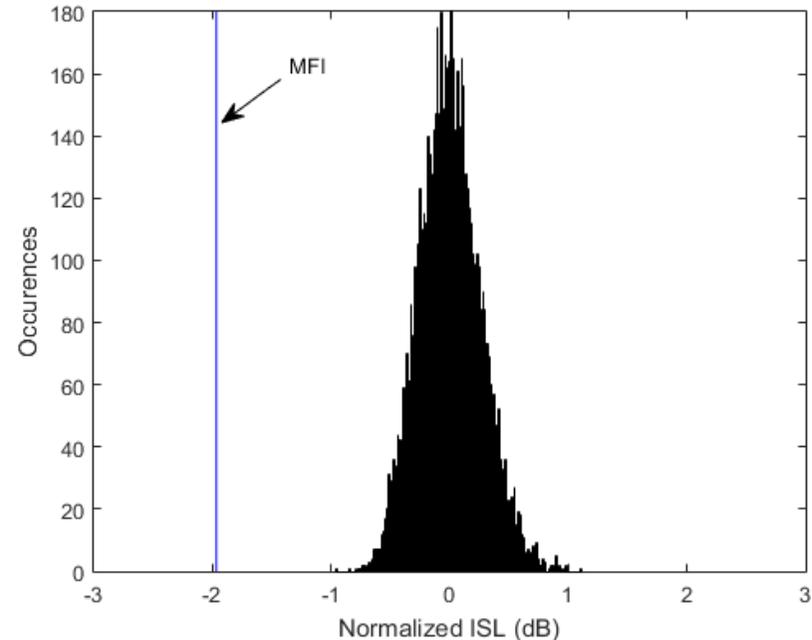
- Likewise, we perform the Matched Filter operation on the results obtained using the approach of frequency block implementation
- Compared to using single frequency insertion, the **block implementation** suffers from additional **PSL** and **ISL degradation**
- However, there are again no grating lobes as compared to uniformly-spaced frequency implementation



Matched Filter response of Sparse frequency array (block implementation) versus Uniformly-spaced frequency array

Sidelobe of SSA Results versus Randomly-spaced

- Again, the ISL from Block implementation of SSA is benchmarked against that from a randomly-spaced frequency array
- Results obtained from 10000 trials of randomly-spaced frequency array are again plotted using a histogram
- The ISL obtained from Block SSA implementation is still 7.66σ away from the mean ISL value of randomly-spaced frequency array



Error variances from Block-based SSA results versus randomly-spaced frequency array

Summary of SSA Performance

- Results obtained from constructing the sparse frequency measurement array model using **SSA** algorithm indicates that this approach is viable as :
 - **Range resolution** is still preserved even when using 25.0% of the original spectrum at the expense of sidelobe degradation
 - **Coarray** derived has **features** of a low-redundancy linear array (**LRLA**)
 - The **sidelobe performance** obtained from both single-frequency location insertion and block-frequency location insertion approaches are **much superior** compared to that from **random insertion** of these frequency locations

Scope of Presentation

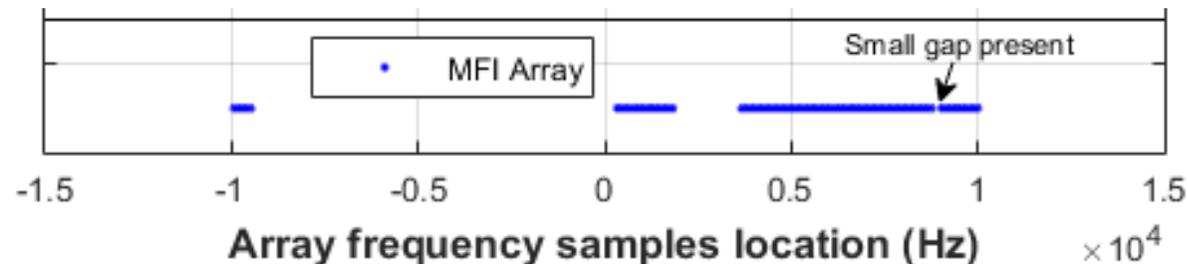
- Introduction
 - Motivation
 - Categories of current solutions/approaches
- Proposed Solution (2-step approach)
 - Spectrally Efficient Waveform Design
 - Results from this step
 - Sparse Spectrum Allocation using Information Theory
 - Results from this step
- Applications of results to Radar System Implementation
- Conclusion

Application 1: Composite PCFM waveform

Waveform results

Applying SSA results to PCFM waveform design

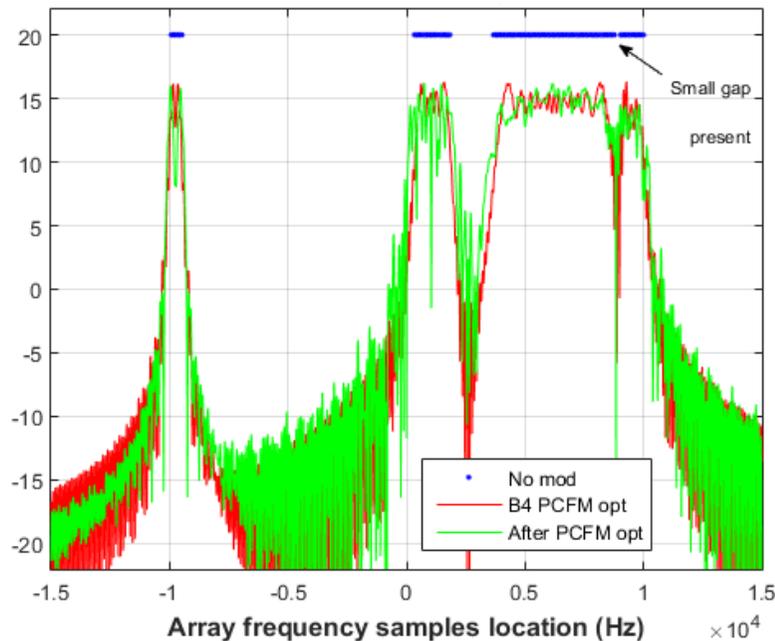
- In this example, SSA results for **spectrum usage of 40%** is used to generate the composite PCFM waveform
- From the SSA results shown below, it is seen that the spectral locations that are selected can be represented by **4 disjointed segments**



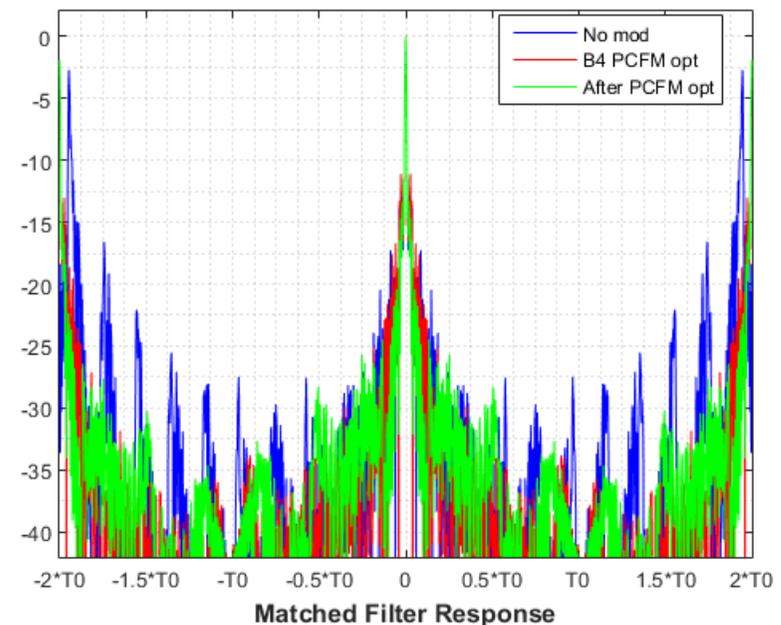
SSA results for spectrum usage of 40% and
block size of 2.50%

Applying SSA results to PCFM waveform design

- Plots of Spectral Content and Autocorrelation function of the PCFM waveform before/after optimization are shown



Spectrum Content of composite PCFM waveform with $BT = 200$



Autocorrelation of composite PCFM waveform with $BT = 200$

Application 2: Radar Range Profile Estimation

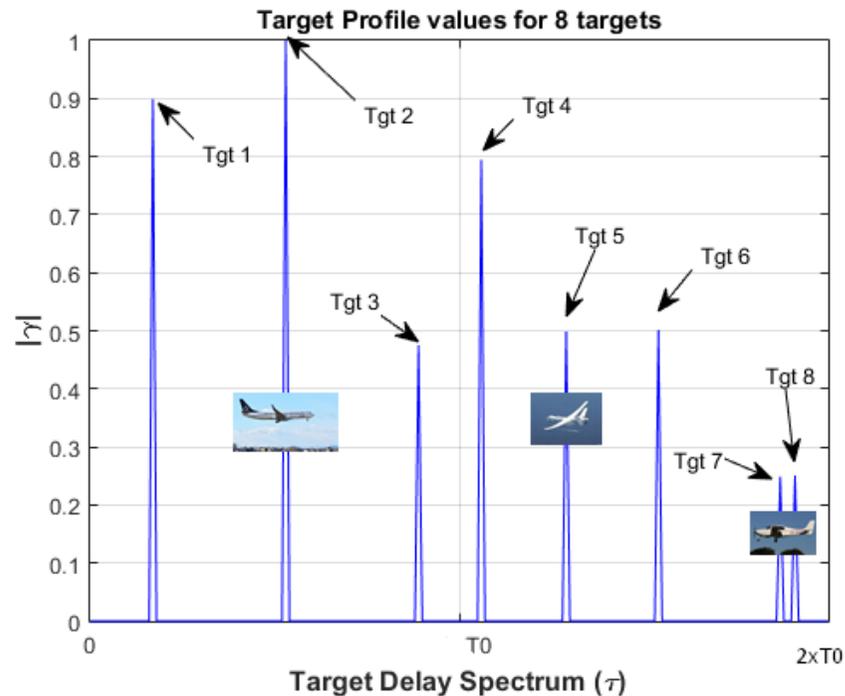
Simulation Results

Estimation of Radar Range Profile γ

- Next, I will demonstrate the feasibility of using the SSA results for a radar range profile estimation application
- The problem setup is defined as **low-density** target distribution scenario (**25** range cells containing complex target scattering coefficients out of $M = 400$ range cells)
- The remaining range cells are filled with very low-valued random Gaussian complex numbers
- Complex Gaussian noise is added to the measurements

Radar Range Profile

- Below is an example snapshot of the radar range profile before clutter and noise are added, i.e. **low-density target distribution scenario**



Iterative MMSE estimator

- For the radar range profile estimation application, an iterative MMSE estimator is developed for this application
- The equations for the MMSE estimator as well as computing the estimated range profile are as follows:

$$\mathbf{W}_{MMSE} = \mathbf{K}_\gamma \mathbf{H}' (\mathbf{H} \mathbf{K}_\gamma \mathbf{H}' + \mathbf{K}_n)^{-1}$$

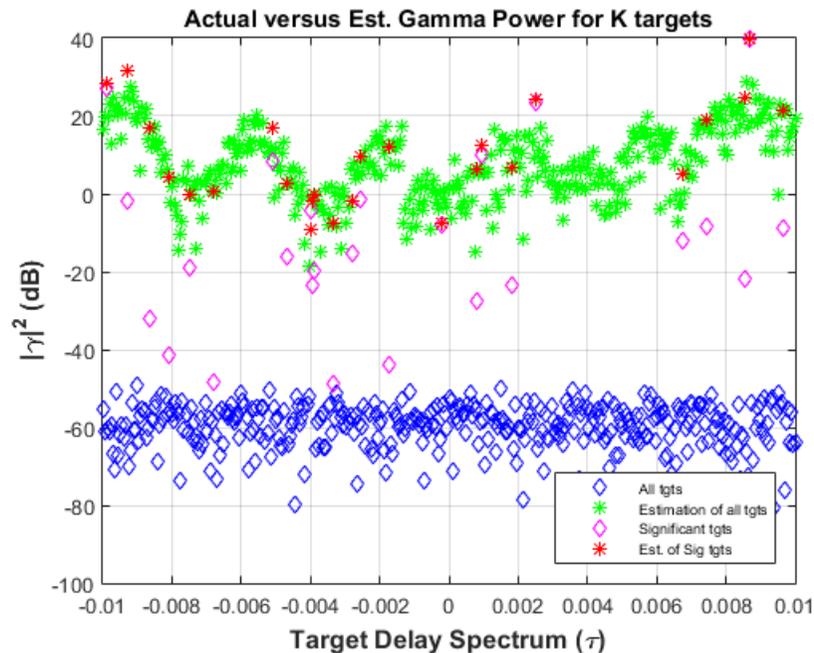
$$\tilde{\boldsymbol{\gamma}} = \mathbf{W}_{MMSE} \mathbf{V}$$

Iterative MMSE estimator

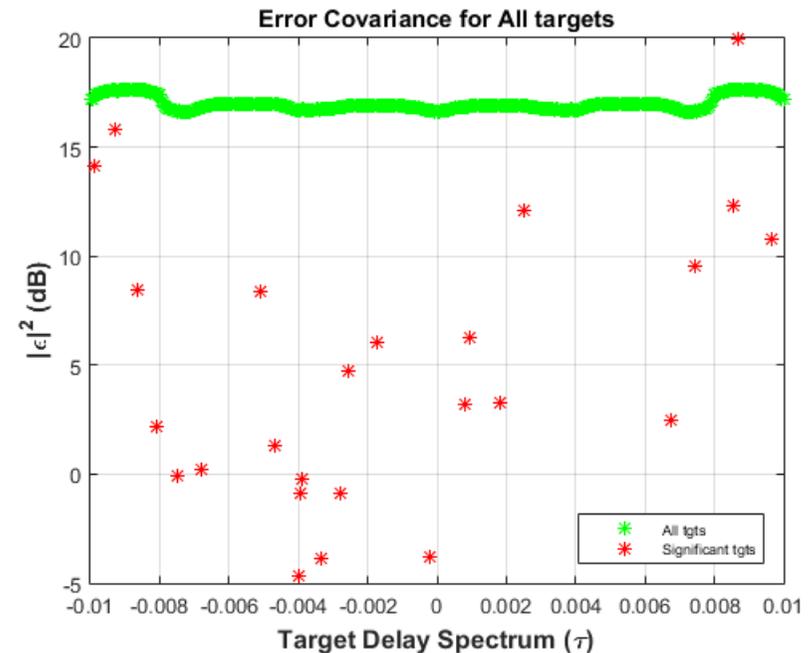
- In each P^{th} iteration, the $\hat{\gamma}_i$ from the range bins $i = 1, 2, \dots, M$ that contains the largest magnitude is identified and added to a set Θ containing range cells $[j_1, j_2, \dots, j_{p-1}]$. Also, $i \notin \Theta$
- The $\hat{\gamma}_{j_q}$ for each element in this set Θ of range cells is assumed to be the true estimate of the scattering coefficient for that range cell
- Also, the a priori target covariance, \mathbf{K}_γ for all locations is updated after each iteration

Initial MMSE estimation of γ using 50% spectrum

- At the 1st iteration, the results of the estimated $\hat{\gamma}$ is equivalent to performing a Matched Filter to each range cell within the range profile



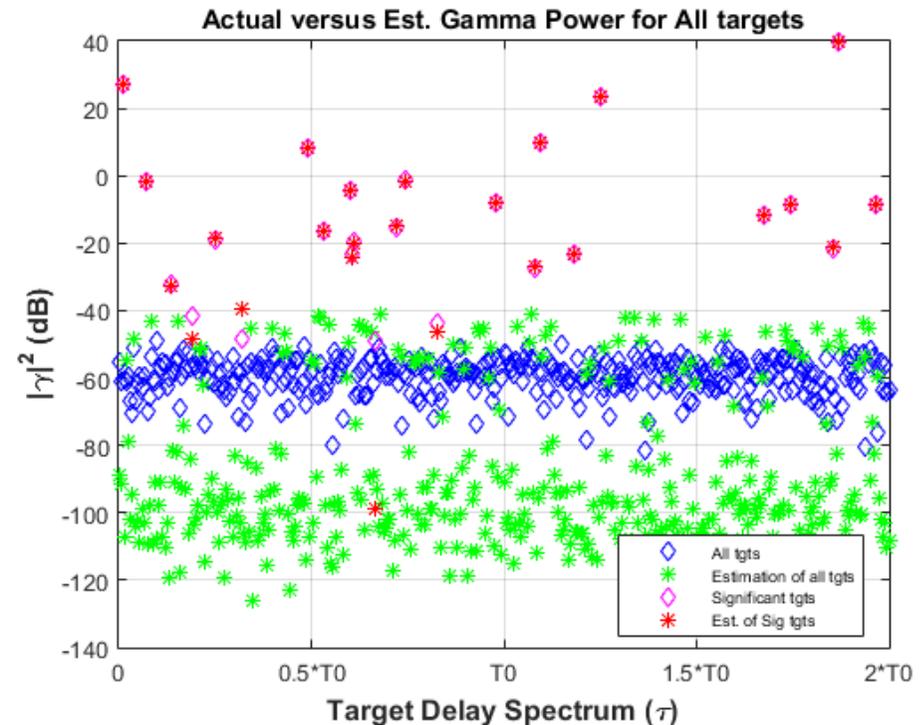
Actual versus Estimated γ for 50% spectrum usage (1st iteration)



Error Covariance for all targets (1st iteration)

Final MMSE estimation of γ using 50% spectrum

- The Iterative MMSE filter is then reiteratively applied to obtain the final results of the estimated γ for all range cells in the unambiguous range
- Results demonstrates the viability of using the block implementation approach for this the SSA algorithm



Actual versus Estimated γ for 50% spectrum usage (block insertion implementation)

Scope of Presentation

- Introduction
 - Motivation
 - Categories of current solutions/approaches
- Proposed Solution (2-step approach)
 - Spectrally Efficient Waveform Design
 - Results from this step
 - Sparse Spectrum Allocation using Information Theory
 - Results from this step
- Applications of results to Radar System Implementation
- Conclusion

Conclusions

- In this presentation, I have successfully illustrated a **two-step** approach to address the issues of both **Spectrum Congestion** and **Spectrum Sharing** between radar and communication systems
- The results obtained from this approach demonstrates that
 - **3-dB range resolution** can be preserved while utilizing as low as **25.0%** of the original spectrum **represented** as disjointed spectrum segments
 - The **PCFM waveform implementation** for these disjointed spectrum segments is able to **prevent spectrum leakage** to forbidden spectrum bands
 - It is viable to apply the frequency measurements obtained from such sparse spectrum usage to **perform radar range profile estimation**

Future Directions

- For Step 1 of the approach involving **higher-order PCFM waveforms**, the next step is to implement these waveforms in the lab using AWG and evaluate the measured output waveform's spectrum shape as well as performance in transmit-receive operations
- For Step 2 of the approach involving **SSA** algorithm and **MFI**, the next step is to apply this algorithm to a real-life **system's spectrum usage** so as to derive a sparse spectrum solution for this system

List of PhD. Publications

- S.D. Blunt, J. Jakobosky, P. McCormick, **Peng Seng Tan**, and J.G. Metcalf, "Holistic Radar Waveform Diversity," to appear in **Academic Press Library in Signal Processing Volume 7 (SIGP): Array, Radar and Communications Engineering**, eds. F. Gini, N.D. Sidiropoulos, M. Pesavento, and P.A. Naylor, Elsevier, 2017
- **Peng Seng Tan**, John Jakobosky, James M. Stiles and Shannon D. Blunt , "Higher-Order Representations of Polyphase-Coded FM Radar Waveforms: Relationships between various orders" to be submitted to **IET Radar, Sonar & Navigation** (after NRL release approval)
- **Peng Seng Tan**, James M. Stiles and Shannon D. Blunt, "Optimizing Sparse Allocation for Radar Spectrum Sharing," **2016 IEEE Radar Conference**, Philadelphia, Pennsylvania, May 02-06, 2016.
- **Peng Seng Tan**, John Jakobosky, James M. Stiles and Shannon D. Blunt, "On Higher-Order Representations of Polyphase-Coded FM Radar Waveforms," , **2015 IEEE International Radar Conference**, Arlington, Virginia, May 11-15, 2015.
- **Peng Seng Tan**, John Paden, Jilu Li, Jie-Bang Yan and Prasad Gogineni, "Robust Adaptive MVDR Beamforming for Processing Radar Depth Sounder Data," **2013 IEEE International Symposium on Phased Array Systems and Technology**, Waltham, MA, Oct 14-18, 2013
- Ulrik Nielsen, Theresa M. Stumpf, **Peng Seng Tan**, Prasad Gogineni, and Jorgen Dall, "Towards a Comprehensive Model of Ice Sheet Scattering Properties at VHF and P-band for Design and Optimization of Multichannel Ice Sounding Techniques," **2013 Progress in Electromagnetics Research Symposium (PIERS)**, Stockholm, Sweden, Aug 12-15, 2013

Thank you!

Questions?