

EECS 861  
Homework #12

1. A decision is based on 2 samples,  $Y_1$  and  $Y_2$ .  $Y$  is a multivariate Gaussian random vector

$$Y = \begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix} \quad E[Y | H_0] = \begin{pmatrix} -1 \\ -1 \end{pmatrix} \quad \text{and} \quad E[Y | H_1] = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{with} \quad \Sigma = \begin{pmatrix} 1 & .8 \\ .8 & 1 \end{pmatrix}$$

- a. Design the optimum detector. Assume  $P(H_0) = P(H_1) = 1/2$ .
- b. Find  $P_e$ .
- c. Repeat parts a. and b. with

$$E[Y | H_0] = \begin{pmatrix} -1 \\ -1 \end{pmatrix} \quad \text{and} \quad E[Y | H_1] = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{with} \quad \Sigma = \begin{pmatrix} 1 & -0.8 \\ -0.8 & 1 \end{pmatrix}$$

- d. Explain why the results, i.e.,  $P_e$ , from b. and c. are different.
- e. The 500 bits in the file below (sheet labeled Volts maps 0->-1 and 1->+1)

[http://www.ittc.ku.edu/~frost/EECS\\_861/EECS\\_861\\_HW\\_Fall\\_2023/Homework-12-Problem-1-bits.xls](http://www.ittc.ku.edu/~frost/EECS_861/EECS_861_HW_Fall_2023/Homework-12-Problem-1-bits.xls)

are sampled at two sample/bit, the resulting transmitted signal is corrupted by additive Gaussian correlated noise with  $\Sigma = \begin{pmatrix} 1 & .8 \\ .8 & 1 \end{pmatrix}$ , apply optimum detector found in part a. to the received signal given in the file below and estimate the  $P_e$  of your detector, then compare to  $P_e$  found in part b..

[http://www.ittc.ku.edu/~frost/EECS\\_861/EECS\\_861\\_HW\\_Fall\\_2023/Homework-12-Problem-1.xls](http://www.ittc.ku.edu/~frost/EECS_861/EECS_861_HW_Fall_2023/Homework-12-Problem-1.xls)

2. Let  $s_1[k] = -0.75, -0.75, -0.75$  for  $k=0, 1, 2$  and  $s_0[k] = -s_1[k]$ , i.e.,  $s_0[k] = 0.75, 0.75, 0.75$  for  $k=0, 1, 2$   
Assume

$$P(s_1) = 0.5 = P(s_0)$$

$$Y[k] = S[k] + N[k] \quad \text{for } k=0 \dots 2 \quad \text{where}$$

$S[k]$  &  $N[k]$  are statistically independent

$N[k]$  is white Gaussian noise with a zero mean and unit variance, i.e.,  $\sigma_N=1$ .

- a. Find the MAP decision algorithm.
- b. Find the probability of error.
- c. Apply the MAP decision algorithm for the follow observations  
 $y(k) = -0.4, 0.1, 0.1$  for  $k=0 \dots 2$
- d. Repeat a)-c) for  $s_1[k] = 0.25, -1.25, 0.25$
- e. What are the results from part b. and part d. the same.

3. A received signal  $X(t)$  contains pulses of amplitude +4 with width  $10 \mu\text{s}$  plus bandlimited white Gaussian noise  $N(t)$ . The noise PSD is

$$S_N(f) = \begin{cases} 3 \times 10^{-5} & |f| < 1\text{MHz} \\ 0 & \text{elsewhere} \end{cases}$$

$X(t)$  is sampled at a rate of 10 Msamples/sec. Samples are collected in time synchronization with the pulses. The received signal is  $N(t)$  if no pulse or  $X(t)+N(t)$  for  $10 \mu\text{s}$  if a pulse is present.

- a. Design a MAP pulse detector assuming  $\text{Prob}(\text{pulse})=0.5$

b. For your pulse detector and given the parameters above calculate the probability of detection and false alarm.

c. Design a pulse detector using a Neyman-Pearson (N-P) rule with a  $P_{fa} = 0.01$  and find probability of detection.

d. Apply the MAP detector with  $\text{Prob}(\text{pulse})=0.5$  to the data set given below. How many pulses are in this record. This file contains a record of collected samples.

[http://www.ittc.ku.edu/~frost/EECS\\_861/EECS\\_861\\_HW\\_Fall\\_2023/HW-12\\_Problem-3\\_data.xls](http://www.ittc.ku.edu/~frost/EECS_861/EECS_861_HW_Fall_2023/HW-12_Problem-3_data.xls)

4. Let  $f_X(x; \theta) = \frac{1}{\sqrt{5\pi}} e^{-\frac{(x-\theta)^2}{5}}$ . Given  $x_1, \dots, x_N$  be  $N$  statistically independent samples from  $f_X(x)$

Is  $\bar{x} = \frac{1}{N} \sum_{i=1}^N x_i$  an unbiased estimator for  $\theta$ ; yes or no and justify.