## Solutions to Ampere's Law

Say we know the current distribution  $J(\bar{r})$  occurring in some physical problem, and we wish to find the resulting magnetic flux density  $B(\bar{r})$ .

**Q**: How do we find  $B(\overline{r})$  given  $J(\overline{r})$ ?

A: Two ways! We either directly solve the differential equation:

 $\nabla \mathbf{x} \mathbf{B}(\overline{\mathbf{r}}) = \mu_0 \mathbf{J}(\overline{\mathbf{r}})$ 

Or we first solve this differential equation for vector field  $\mathbf{A}(\mathbf{\bar{r}})$ :

$$-\nabla^{2}\boldsymbol{A}(\bar{\boldsymbol{r}}) = \mu_{0}\boldsymbol{J}(\bar{\boldsymbol{r}})$$

and then find  $B(\overline{r})$  by taking the curl of  $A(\overline{r})$  (i.e.,  $\nabla \times A(\overline{r}) = B(\overline{r})$ ).

It turns out that the **second** option is often the easiest!

To see why, consider the vector Laplacian operator if vector field  $\mathbf{A}(\overline{r})$  is expressed using Cartesian base vectors:

$$\nabla^{2}\boldsymbol{A}(\overline{\boldsymbol{r}}) = \nabla^{2}\boldsymbol{A}_{x}(\overline{\boldsymbol{r}})\,\hat{\boldsymbol{a}}_{x} + \nabla^{2}\boldsymbol{A}_{y}(\overline{\boldsymbol{r}})\,\hat{\boldsymbol{a}}_{y} + \nabla^{2}\boldsymbol{A}_{z}(\overline{\boldsymbol{r}})\,\hat{\boldsymbol{a}}_{z}$$

We therefore write **Ampere's Law** in terms of **three** separate **scalar** differential equations:

$$\nabla^{2}\mathcal{A}_{x}\left(\overline{\mathbf{r}}\right)=-\mu_{0}\mathcal{J}_{x}\left(\overline{\mathbf{r}}\right)$$

$$\nabla^{2}\mathcal{A}_{\mathcal{Y}}(\overline{\mathbf{r}}) = -\mu_{0}\mathcal{J}_{\mathcal{Y}}(\overline{\mathbf{r}})$$

$$\nabla^{2}\mathcal{A}_{z}\left(\overline{\mathbf{r}}\right)=-\mu_{0}\mathcal{J}_{z}\left(\overline{\mathbf{r}}\right)$$

Each of these differential equations is **easily solved**. In fact, we **already know** their solution!

Recall we had the **exact** same differential equation in electrostatcs (i.e., Poisson's equation):

$$\nabla^{2} \mathcal{V}(\overline{\mathbf{r}}) = \frac{-\rho_{v}(\overline{\mathbf{r}})}{\varepsilon_{0}}$$

We know the solution  $V(\overline{r})$  to this differential equation is:

$$V(\overline{\mathbf{r}}) = \frac{1}{4\pi \,\varepsilon_0} \iiint \frac{\rho_v(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} \, dv'$$

Mathematically, Poisson's equation is **exactly** the same as **each** of the three scalar differential equations at the top of the page, with these **substitutions**:

$$\mathcal{V}(\bar{\mathbf{r}}) \to \mathcal{A}_{x}(\bar{\mathbf{r}}) \qquad \rho_{v}(\bar{\mathbf{r}}) \to \mathbf{J}_{x}(\bar{\mathbf{r}}) \qquad \frac{\mathbf{I}}{\mathbf{\epsilon}_{v}} \to \mu_{0}$$

The **solutions** to the **magnetic** differential equation are therefore:

$$\mathcal{A}_{x}\left(\overline{\mathbf{r}}\right) = \frac{\mu_{0}}{4\pi} \iiint_{\nu} \frac{\mathcal{J}_{x}\left(\overline{\mathbf{r}}'\right)}{\left|\overline{\mathbf{r}} - \overline{\mathbf{r}}'\right|} d\nu'$$

$$\mathcal{A}_{\mathcal{Y}}(\overline{\mathbf{r}}) = \frac{\mu_{0}}{4\pi} \iiint_{\mathcal{V}} \frac{\mathcal{J}_{\mathcal{Y}}(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} d\mathbf{v}'$$

$$\mathcal{A}_{z}\left(\overline{\mathbf{r}}\right) = \frac{\mu_{0}}{4\pi} \iiint_{v} \frac{\mathcal{J}_{z}\left(\overline{\mathbf{r}}'\right)}{\left|\overline{\mathbf{r}}-\overline{\mathbf{r}}'\right|} dv'$$

and since:

$$\mathbf{A}(\overline{\mathbf{r}}) = \mathbf{A}_{x}(\overline{\mathbf{r}}) \ \hat{a}_{x} + \mathbf{A}_{y}(\overline{\mathbf{r}}) \ \hat{a}_{y} + \mathbf{A}_{z}(\overline{\mathbf{r}}) \ \hat{a}_{z}$$

and:

$$\mathbf{J}(\overline{\mathbf{r}}) = J_{x}(\overline{\mathbf{r}}) \ \hat{a}_{x} + J_{y}(\overline{\mathbf{r}}) \ \hat{a}_{y} + J_{z}(\overline{\mathbf{r}}) \ \hat{a}_{z}$$

we can **combine** these three solutions and get the **vector** solution to our **vector** differential equation:

$$\mathbf{A}(\overline{\mathbf{r}}) = \frac{\mu_0}{4\pi} \iiint_{\mathbf{v}} \frac{\mathbf{J}(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} \, d\mathbf{v}'$$

Therefore, given current distribution  $\mathbf{J}(\overline{\mathbf{r}})$ , we use the above equation to determine magnetic vector potential  $\mathbf{A}(\overline{\mathbf{r}})$ . We then take the curl of this result to determine magnetic flux density  $\mathbf{B}(\overline{\mathbf{r}})$ .

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For surface current, the resulting magnetic vector potential is:

$$\mathbf{A}(\overline{\mathbf{r}}) = \frac{\mu_0}{4\pi} \iint_{\mathcal{S}} \frac{\mathbf{J}_{\mathcal{S}}(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} d\mathcal{S}'$$

and for a current I flowing along contour C, we find:

$$\mathbf{A}(\overline{\mathbf{r}}) = \frac{\mu_0 \ \mathbf{I}}{4\pi} \oint_{\mathcal{C}} \frac{\overline{d\ell'}}{|\overline{\mathbf{r}} - \overline{\mathbf{r}'}|}$$

Again, ponder the **analogy** between these equations involving sources and potentials and the equivalent equation from electrostatics:

$$V(\overline{r}) = \frac{1}{4\pi \epsilon_0} \iiint_{\nu} \frac{\rho_{\nu}(\overline{r}')}{|\overline{r} - \overline{r}'|} d\nu'$$