<u>Vector Algebra using</u> <u>Orthonormal Base Vectors</u>

Q: Just why do we express a vector in terms of 3 orthonormal base vectors? Doesn't this just make things even more complicated ??

A: Actually, it makes things much simpler. The evaluation of vector operations such as addition, subtraction, multiplication, dot product, and cross product all become straightforward if all vectors are expressed using the same set of base vectors.

Consider two vectors **A** and **B**, each expressed using the same set of base vectors \hat{a}_x , \hat{a}_y , \hat{a}_z :

 $\mathbf{A} = \mathbf{A}_{x} \, \hat{a}_{x} + \mathbf{A}_{y} \, \hat{a}_{y} + \mathbf{A}_{z} \, \hat{a}_{z}$

 $\mathbf{B} = B_x \ \hat{a}_x + B_y \ \hat{a}_y + B_z \ \hat{a}_z$

Jim Stiles

1. Addition and Subtraction

If we **add** these two vectors together, we find:

$$\mathbf{A} + \mathbf{B} = (A_{x} \ \hat{a}_{x} + A_{y} \ \hat{a}_{y} + A_{z} \ \hat{a}_{z}) + (B_{x} \ \hat{a}_{x} + B_{y} \ \hat{a}_{y} + B_{z} \ \hat{a}_{z})$$

= $A_{x} \ \hat{a}_{x} + B_{x} \ \hat{a}_{x} + A_{y} \ \hat{a}_{y} + B_{y} \ \hat{a}_{y} + A_{z} \ \hat{a}_{z} + B_{z} \ \hat{a}_{z}$
= $(A_{x} + B_{x}) \ \hat{a}_{x} + (A_{y} + B_{y}) \ \hat{a}_{y} + (A_{z} + B_{z}) \ \hat{a}_{z}$

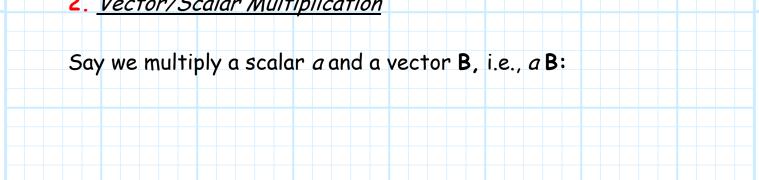
In other words, each component of the sum of two vectors is equal to the sum of each component.

Similarly, we find for subtraction:

$$\mathbf{A} - \mathbf{B} = (A_{x} \ \hat{a}_{x} + A_{y} \ \hat{a}_{y} + A_{z} \ \hat{a}_{z}) - (B_{x} \ \hat{a}_{x} + B_{y} \ \hat{a}_{y} + B_{z} \ \hat{a}_{z})$$

= $A_{x} \ \hat{a}_{x} - B_{x} \ \hat{a}_{x} + A_{y} \ \hat{a}_{y} - B_{y} \ \hat{a}_{y} + A_{z} \ \hat{a}_{z} - B_{z} \ \hat{a}_{z}$
= $(A_{x} - B_{x}) \ \hat{a}_{x} + (A_{y} - B_{y}) \ \hat{a}_{y} + (A_{z} - B_{z}) \ \hat{a}_{z}$

2. Vector/Scalar Multiplication



$$a\mathbf{B} = a(B_x, \hat{a}_x + B_y, \hat{a}_y + B_z, \hat{a}_z)$$

= $aB_x, \hat{a}_x + aB_y, \hat{a}_y + aB_z, \hat{a}_z$
= $(aB_x), \hat{a}_x + (aB_y), \hat{a}_y + (aB_z), \hat{a}_z$
In other words, each component of the product of a scalar and
a vector are equal to the product of the scalar and each
component.
3. Dot Product
Say we take the **dot product** of **A** and **B**:
$$\mathbf{A} \cdot \mathbf{B} = (A_x, \hat{a}_x + A_y, \hat{a}_y + A_z, \hat{a}_z) \cdot (B_x, \hat{a}_x + B_y, \hat{a}_y + B_z, \hat{a}_z)$$

= $A_x, \hat{a}_x \cdot (B_x, \hat{a}_x + B_y, \hat{a}_y + B_z, \hat{a}_z)$
+ $A_y, \hat{a}_y \cdot (B_x, \hat{a}_x + B_y, \hat{a}_y + B_z, \hat{a}_z)$
+ $A_y, \hat{a}_y \cdot (B_x, \hat{a}_x + B_y, \hat{a}_y + B_z, \hat{a}_z)$
+ $A_x, \hat{a}_x \cdot (B_x, \hat{a}_x + B_y, \hat{a}_y + B_z, \hat{a}_z)$
+ $A_y, \hat{a}_y \cdot (B_x, \hat{a}_x + B_y, \hat{a}_y + A_x, B_z, (\hat{a}_x, \hat{a}_x)$
+ $A_y, \hat{a}_x \cdot (B_x, \hat{a}_x + B_y, \hat{a}_y + A_x, B_z, (\hat{a}_x, \hat{a}_z))$
+ $A_x, \hat{a}_x \cdot (B_x, \hat{a}_x + B_y, \hat{a}_y + A_x, B_z, (\hat{a}_x, \hat{a}_z))$
+ $A_y, \hat{a}_y \cdot (A_x, \hat{a}_x) + A_x, B_y(\hat{a}_x, \hat{a}_y) + A_x, B_z(\hat{a}_x, \hat{a}_z)$
+ $A_y, B_x(\hat{a}_x \cdot \hat{a}_x) + A_x, B_y(\hat{a}_x, \hat{a}_y) + A_x, B_z(\hat{a}_x, \hat{a}_z)$
A: Be patient! Recall that these are orthonormal base
vectors, therefore:
 $\hat{a}_x, \hat{a}_x = \hat{a}_y, \hat{a}_y = \hat{a}_x, \hat{a}_x = 1$ and $\hat{a}_x \cdot \hat{a}_y = \hat{a}_y, \hat{a}_z = \hat{a}_z, \hat{a}_x = 0$

As a result, our **dot product** expression reduces to this simple expression:

$$\mathbf{A} \cdot \mathbf{B} = \mathbf{A}_{x} \mathbf{B}_{x} + \mathbf{A}_{y} \mathbf{B}_{y} + \mathbf{A}_{z} \mathbf{B}_{z}$$



We can apply this to the expression for determining the **magnitude** of a vector:

$$\left|\mathbf{A}\right|^{2} = \mathbf{A} \cdot \mathbf{A} = \mathbf{A}_{x}^{2} + \mathbf{A}_{y}^{2} + \mathbf{A}_{z}^{2}$$

Therefore:

$$\left|\mathbf{A}\right| = \sqrt{\mathbf{A} \cdot \mathbf{A}} = \sqrt{\mathbf{A}_{x}^{2} + \mathbf{A}_{y}^{2} + \mathbf{A}_{z}^{2}}$$

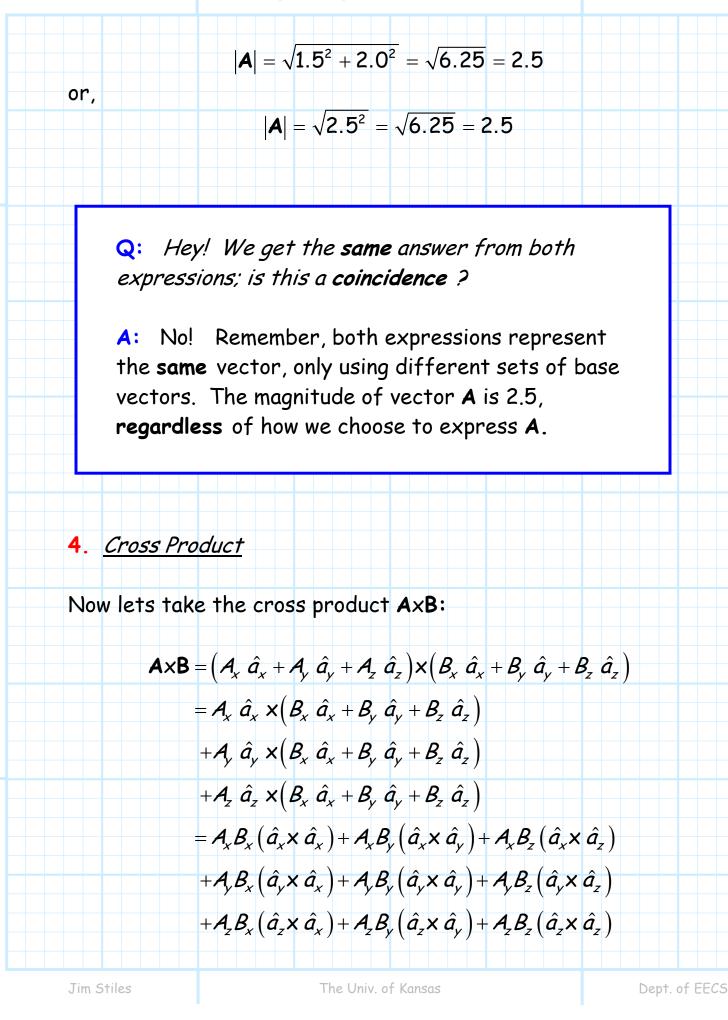
For example, consider a previous handout, where we expressed a vector using two different sets of basis vectors:

$$A = 2.0\hat{a}_{x} + 1.5\hat{a}_{y}$$

or,

$$A = 2.5\hat{b}_y$$

Therefore, the magnitude of **A** is determined to be:



Remember, we know that:

 $\hat{a}_x \times \hat{a}_x = \hat{a}_y \times \hat{a}_y = \hat{a}_z \times \hat{a}_z = 0$

also, since base vectors form a **right-handed** system:

$$\hat{a}_x \times \hat{a}_y = \hat{a}_z$$
 $\hat{a}_y \times \hat{a}_z = \hat{a}_x$ $\hat{a}_z \times \hat{a}_x = \hat{a}_y$

Remember also that $A \times B = -(B \times A)$, therefore:

$$\hat{a}_y \times \hat{a}_x = -\hat{a}_z$$
 $\hat{a}_z \times \hat{a}_y = -\hat{a}_x$ $\hat{a}_x \times \hat{a}_z = -\hat{a}_y$

Combining all the equations above, we get:

$$\mathbf{A} \times \mathbf{B} = \left(\mathbf{A}_{\mathbf{y}} \mathbf{B}_{\mathbf{z}} - \mathbf{A}_{\mathbf{z}} \mathbf{B}_{\mathbf{y}}\right) \hat{a}_{\mathbf{x}} + \left(\mathbf{A}_{\mathbf{z}} \mathbf{B}_{\mathbf{x}} - \mathbf{A}_{\mathbf{x}} \mathbf{B}_{\mathbf{z}}\right) \hat{a}_{\mathbf{y}} + \left(\mathbf{A}_{\mathbf{x}} \mathbf{B}_{\mathbf{y}} - \mathbf{A}_{\mathbf{y}} \mathbf{B}_{\mathbf{x}}\right) \hat{a}_{\mathbf{z}}$$

5. Triple Product

Combining the results of the dot product and the cross product, we find that the **triple product** can be expressed as:

 $\mathbf{A} \cdot \mathbf{B} \times \mathbf{C} = \left(\mathbf{A}_{x} \mathbf{B}_{y} \mathbf{C}_{z} + \mathbf{A}_{y} \mathbf{B}_{z} \mathbf{C}_{x} + \mathbf{A}_{z} \mathbf{B}_{x} \mathbf{C}_{y} \right) - \left(\mathbf{A}_{x} \mathbf{B}_{z} \mathbf{C}_{y} + \mathbf{A}_{y} \mathbf{B}_{x} \mathbf{C}_{z} + \mathbf{A}_{z} \mathbf{B}_{y} \mathbf{C}_{x} \right)$

IMPORTANT NOTES:

In addition to all that we have discussed here, it is critical that you understand the following points about vector algebra using orthonormal base vectors!



* The results provided in this handout were given for **Cartesian** base vectors ($\hat{a}_x, \hat{a}_y, \hat{a}_z$). However, they are equally valid for **any** right-handed set of base vectors $\hat{a}_1, \hat{a}_2, \hat{a}_3$ (e.g., $\hat{a}_{\rho}, \hat{a}_{\phi}, \hat{a}_z$ or $\hat{a}_r, \hat{a}_{\theta}, \hat{a}_{\phi}$).

* These results are **algorithms** for evaluating various vector algebraic operations. They are **not** definitions of the operations. The **definitions** of these operations were covered in **Section 2-3**.

* The scalar components A_x , A_y , and A_z represent **either** discrete scalar (e.g., $A_x = 4.2$) **or** scalar field quantities (e.g., $A_\theta = r^2 \sin\theta \cos\phi$.