

# Line Regulation

Since the Zener diode in a shunt regulator has some small (but non-zero) dynamic resistance  $r_Z$ , we find that the load voltage  $V_O$  will have a **small** dependence on source voltage  $V_S$ .

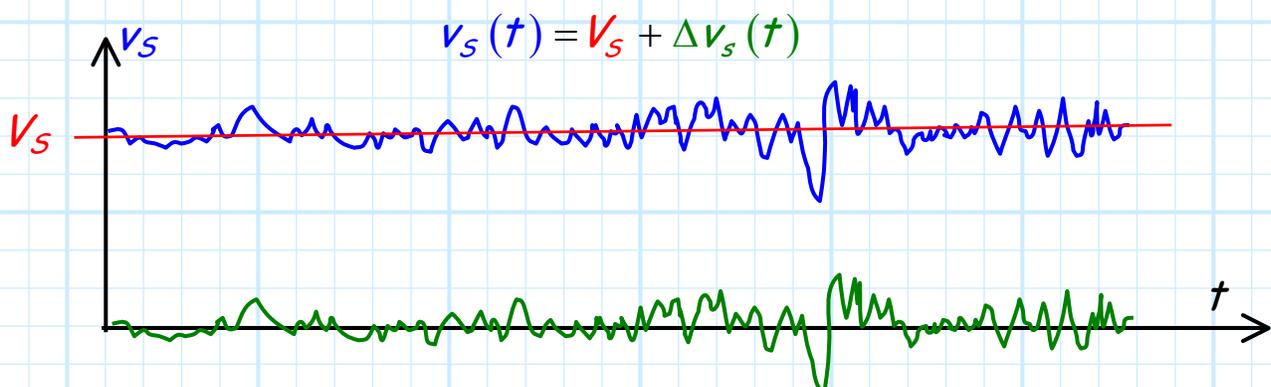
In other words, if the source voltage  $V_S$  **increases** (decreases), the load voltage  $V_O$  will **likewise** increase (decrease) by some very small amount.

**Q:** *Why would the source voltage  $V_S$  ever change?*

**A:** There are **many** reasons why  $V_S$  will not be a perfect constant with time. Among them are:

1. Thermal **noise**
2. Temperature **drift**
3. Coupled **60 Hz** signals (or digital clock signals)

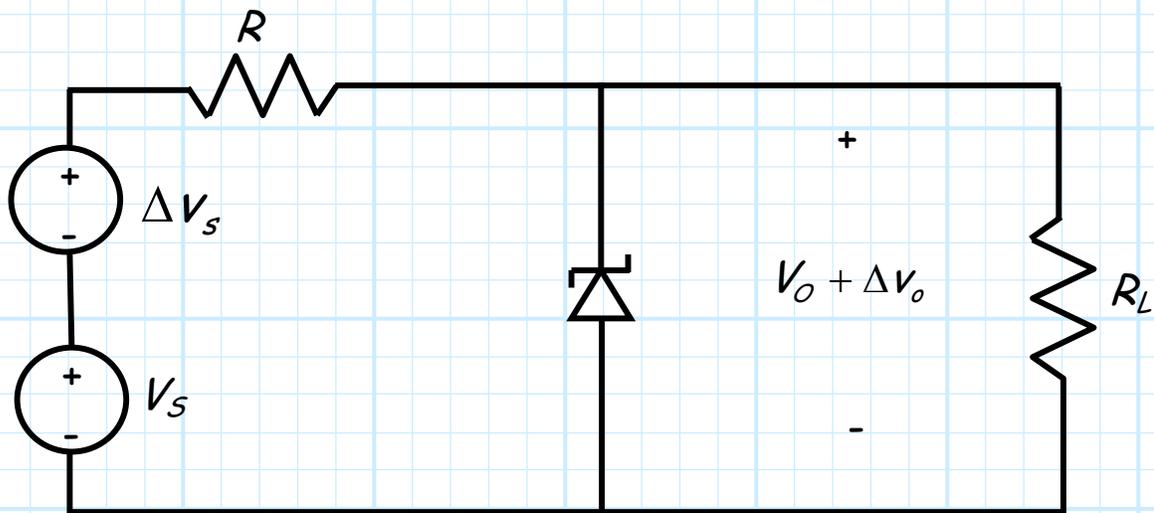
As a result, it is more appropriate to represent the **total** source voltage as a time-varying signal ( $v_S(t)$ ), consisting of both a **DC** component ( $V_S$ ) and a **small-signal** component ( $\Delta v_S(t)$ ):



As a result of the small-signal source voltage, the total load voltage is likewise time-varying, with both a DC ( $V_o$ ) and small-signal ( $\Delta v_o$ ) component:

$$v_o(t) = V_o + \Delta v_o(t)$$

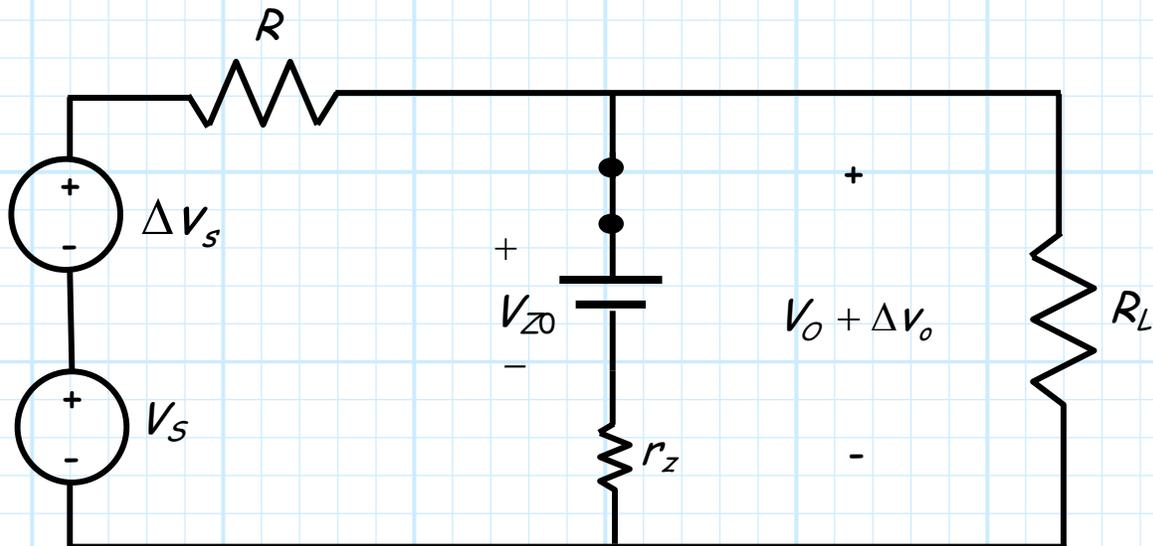
So, we know that the DC source  $V_s$  produces the DC load voltage  $V_o$ , whereas the small-signal source voltage  $\Delta v_s$  results in the small-signal load voltage  $\Delta v_o$ .



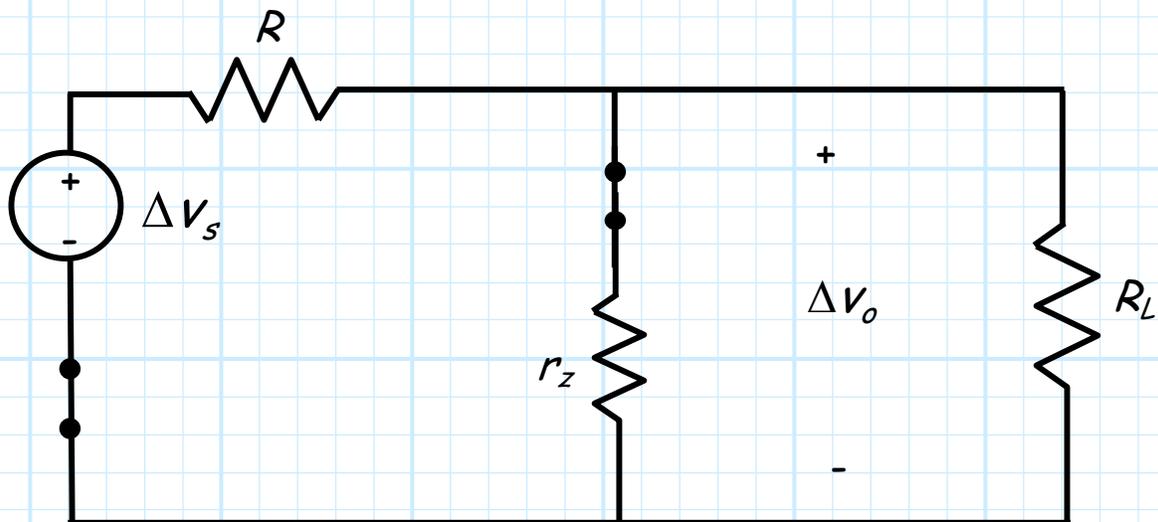
**Q:** Just how are  $\Delta v_s$  and  $\Delta v_o$  **related**? I mean, if  $\Delta v_s$  equals, say, **500 mV**, what will value of  $\Delta v_o$  be?

**A:** Determining this answer is **easy**! We simply need to perform a **small-signal analysis**.

In other words, we first replace the Zener diode with its **Zener PWL model**.



We then turn **off** all the DC sources (including  $V_{Z0}$ ) and analyze the remaining **small-signal circuit!**



From **voltage division**, we find: 
$$\Delta V_o = \Delta V_s \left( \frac{r_z \parallel R_L}{R + r_z \parallel R_L} \right)$$

However, recall that the value of a Zener dynamic resistance  $r_z$  is **very small**. Thus, we can assume that  $r_z \gg R_L$ , and therefore  $r_z \parallel R_L \approx r_z$ , leading to:

$$\Delta v_o = \Delta v_s \left( \frac{r_z \parallel R_L}{R + r_z \parallel R_L} \right)$$

$$\approx \Delta v_s \left( \frac{r_z}{r_z + R} \right)$$

Rearranging, we find:

$$\frac{\Delta v_o}{\Delta v_s} = \frac{r_z}{r_z + R} \doteq \text{line regulation}$$

This equation describes an important performance parameter for shunt regulators. We call this parameter the **line regulation**.

\* Line regulation allows us to determine the **amount** that the load voltage changes ( $\Delta v_o$ ) when the source voltage changes ( $\Delta v_s$ ).

\* For example, if line regulation is 0.002, we find that the load voltage will increase 1 mV when the source voltage increases 500mV

(i.e.,  $\Delta v_o = 0.002 \Delta v_s = 0.002(0.5) = 0.001 \text{ V}$ ).

\* **Ideally**, line regulation is **zero**. Since dynamic resistance  $r_z$  is typically very small (i.e.,  $r_z \ll R$ ), we find that the line regulation of most shunt regulators is likewise **small** (this is a **good thing!**).