

4.4 Operation in the Reverse Breakdown Region – Zener Diodes

Reading Assignment: *pp. 190-191*

A **Zener Diode** is simply a p-n **junction diode** that is meant to be operated in breakdown.

Understanding the **differences** between a **Zener diode** and a **junction diode** is **crucial**.

HO: THE ZENER DIODE

Since a Zener diode is **usually** operating in the breakdown or reverse bias regions, we alter the current/voltage **notation** (but this does **not** alter the device) for Zener diodes.

HO: ZENER DIODE NOTATION

Our junction diode models are **not accurate** if a diode is operating in **breakdown**. Since a Zener diode is often operating in the breakdown region, we require some **new diode models**.

HO: ZENER DIODE MODELS

Let's use these new models to **analyze** a Zener diode circuit!

EXAMPLE: FUN WITH ZENER DIODES

Q: *I'm tired of all these pointless academic exercises!*

*What's the point of diodes and diode circuits if they don't actually **do something useful**? Can't we get to the "practical" and "hands-on" portion of this course?*

A: That is exactly the place at which **we have arrived** in this course (or at least, with respect to diodes)! Note that **you** now:

- * understand the **operation** of junction and Zener diodes
- * understand how to **approximate** these devices using ideal diode **models** (e.g., the CVD model).
- * understand how to **analyze** junction and Zener diode circuits, implementing various ideal diode models.

Our **tool box** is now **full**—it's time to go **build something useful**!



The first useful application we will consider is **voltage regulation**. A Zener diode in breakdown acts somewhat like a **voltage source**—the voltage across it is **nearly independent** of the (positive) **current** through it. This makes a Zener diode in breakdown **very useful** for voltage regulation!

HO: THE SHUNT REGULATOR

Say your boss wants you to **design a shunt regulator**; be careful, engineering is not as **easy** as it looks!

EXAMPLE: THE SHUNT REGULATOR

In addition to good load and line regulation, another important parameter of voltage regulators is **efficiency**—we do not wish to **waste energy** by creating heat.

HO: REGULATOR POWER AND EFFICIENCY

Finally, we should note that the **shunt regulator** is far from the **only way** to provide voltage regulation. Not only can we use more efficient **switching** regulators, **better** linear regulator designs (i.e., better than the shunt regulator) are available in the form of **integrated circuit** linear regulators.

HO: LINEAR VOLTAGE REGULATORS

The Zener Diode

→ A **Zener** diode is simply a $p-n$ junction diode that is meant to be placed in breakdown!

Q: *Yikes!*

A whole new electronic device to learn about.

*I'm sure it's **completely different** than a junction diode; go ahead and start listing **all the differences** between a junction diode and a zener diode!*

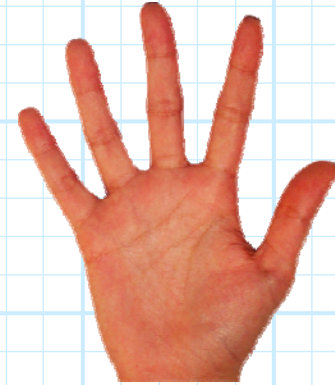
A: Um, OK.

Let's **contrast** the differences between **junction** diodes and **Zener** diodes!

The first difference

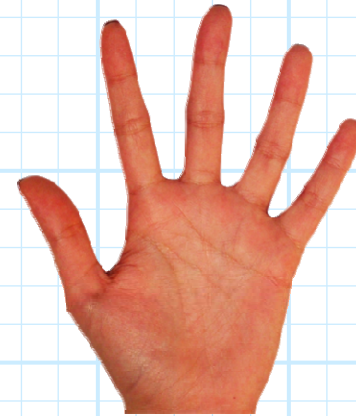
On the **one** hand, a **junction** diode is:

- * an **asymmetric** device
- * **non-linear** device
- * a device with **two** terminals, called the **anode** and the **cathode**.



On the **other** hand, a **Zener** diode is:

- * an **asymmetric** device
- * **non-linear** device
- * a device with **two** terminals, called the **anode** and the **cathode**.



The second difference

Three **device parameters** characterize a **junction** diode:

- * its **idealty factor**,
- * its **scale current**,
- * and its **zener breakdown voltage**.

However, three **device parameters** characterize a **Zener** diode:

- * its **idealty factor**,
- * its **scale current**,
- * and its **zener breakdown voltage**.

Now the third difference

Likewise, a **junction** diode has **three** operating "regions", called:

- * **forward** bias,
- * **reverse** bias,
- * and **breakdown**.

In **contrast**, a **Zener** diode has **three** operating "regions" ", called:

- * **forward** bias,
- * **reverse** bias,
- * and **breakdown**.

Yet another difference— I've lost track of which one

We know that a **junction** diode operating in the **forward** bias region will exhibit:

- * significant current will flow from **anode** to **cathode**,
- * and the **anode** voltage will be around **700 mV** higher than the **cathode** voltage.

But, we find **instead** that a **Zener** diode operating in the **forward** bias region will exhibit:

- * significant current will flow from **anode** to **cathode**,
- * and the **anode** voltage will be around **700 mV** higher than the **cathode** voltage.

So completely different!

And, we know that a **junction** diode operating in the **reverse** bias region will:

- * exhibit a **tiny current** flowing from **cathode to anode**,
- * and a **higher voltage** at the **anode** than at the **cathode**.

Whereas, we know that a **Zener** diode operating in the **reverse** bias region will:

- * exhibit a **tiny current** flowing from **cathode to anode**,
- * and a **higher voltage** at the **anode** than at the **cathode**.

The last difference—a really big one!

Finally, a **junction** diode in the **breakdown** region will show:

- * significant current flowing from **cathode** to **anode**,
- * and a **cathode** voltage that is a value V_{ZK} higher than the **anode** voltage.

Alternatively—in a stunning reversal—a **Zener** diode in the **breakdown** region will show:

- * significant current flowing from **cathode** to **anode**,
- * and a **cathode** voltage that is a value V_{ZK} higher than the **anode** voltage.

Sarcasm: it's so darn effective

Q: *What?*

This Zener diode sounds exactly the same as a junction diode!

A: That's correct!

I'll say it again:

"A Zener diode is simply a $p-n$ junction diode that is meant to be placed in breakdown!"

Q: *But if a Zener diode is a junction diode, then why give it a different name?*

A: Because a Zener diode is a junction diode that is meant to be placed in breakdown (I hope you're finally getting this)!

Speaking of annoying

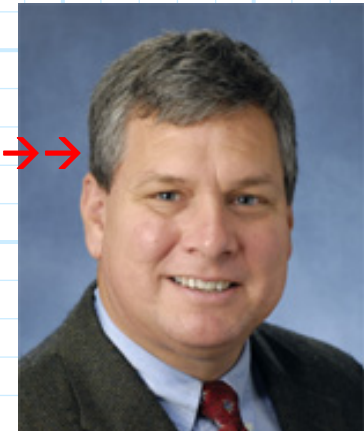
Q: *You seem to be suggesting that a junction diode is **not** meant to be placed in breakdown?*

A: That's exactly **correct!**

For **many** diode applications, breakdown is an **annoying and useless** → → operating mode that is not **at all** like an **IDEAL** diode.

For **these** applications, breakdown is to be **avoided**—we seek a junction diode with a **very large Zener breakdown voltage** V_{ZK} .

Thus, for these diode applications, the **ideal** value of V_{ZK} is **infinity** (i.e., making breakdown **impossible**)!



Thankfully, a badly receding hairline is no longer required for a job in engineering

Q: *Is that why our junction diode models did not consider breakdown?*

A: That's right—it is **implicitly assumed** in those models that V_{ZK} is sufficiently large, such that breakdown **cannot** happen.

The forward and reverse bias regions **only** are **modeled**.

But—and **here's the exciting part**—industrious and creative **electrical engineers** (as they are wont to do) discovered that the "useless" and "annoying" **breakdown** region actually has some especially **useful applications!**

So, there **are** some important **differences** between "normal" junction diodes, and the p - n junction diodes that we call **Zener diodes**.



The first real difference

On the **one** hand, the Zener breakdown voltage V_{ZK} of a **junction** diode:

- * is **typically large** (e.g., 50 V or greater).
- * The manufacturing **tolerance** associated with the breakdown voltage is also usually **large** (e.g., 20%),
- * so that V_{ZK} is often specified as an **inequality** (e.g., $V_{ZK} > 65\text{ V}$).

On the **other** hand, the Zener breakdown voltage V_{ZK} of a **Zener** diode:

- * varies over a **wide range** of values (e.g., 2 to 200 V), with some values quite **small**.
- * The manufacturing **tolerance** associated with the breakdown voltage is also **small** (e.g., $< 5\%$),
- * so that V_{ZK} is **precisely** specified as an **equality** (e.g., $V_{ZK} = 12\text{ V}$).

The second real difference

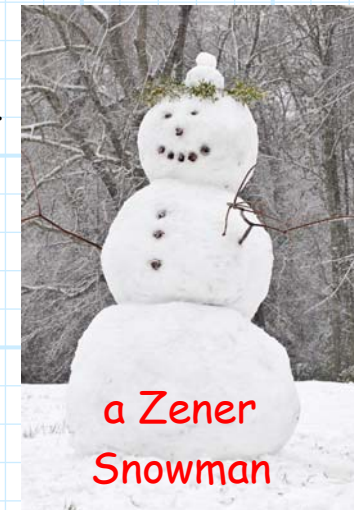
If a **junction** diode **does** happen to operate in the breakdown region, then it likely won't likely to operate at all for very long!

Recall that a diode in the breakdown region will **absorb** (and so must dissipate) **energy at a high rate**.



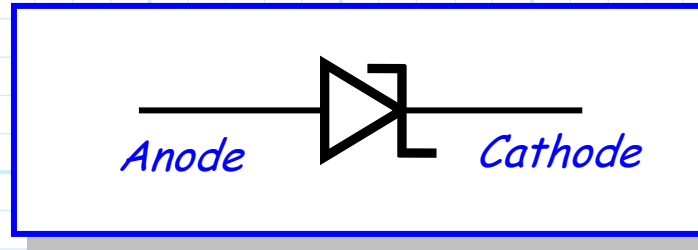
- * A "normal" junction diode is **not** designed to **thermodynamically** handle this event, as its designers assumed breakdown would **not occur**.
- * The junction diode in breakdown will likely be **destroyed!**

- * However, **Zener** diode manufacturers assume the **opposite**—that the diode **will** operate in the breakdown region.
- * As a result, Zener diodes **are designed** to efficiently **dissipate** this heat—thermal equilibrium can be achieved **before** the Zener temperature reaches its **melting point!**



Zener Diode Notation

To distinguish a **zener** diode from conventional junction diodes, we use a modified diode **symbol**:



Generally speaking, a **zener** diode will be operating in either **breakdown** or **reverse bias** mode.

For both these **two** operating regions, the cathode **voltage** will be greater than the anode voltage, i.e.;

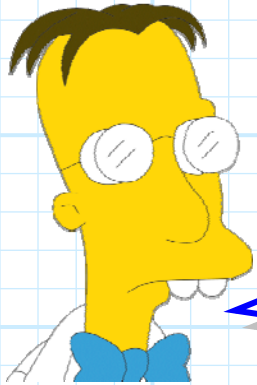
$$v_D < 0 \quad (\text{for r.b. and bd})$$

Likewise, the diode **current** (although often tiny) will flow from cathode to anode for these two modes:

$$i_D < 0 \quad (\text{for r.b. and bd})$$

We're trying to avoid negative numbers

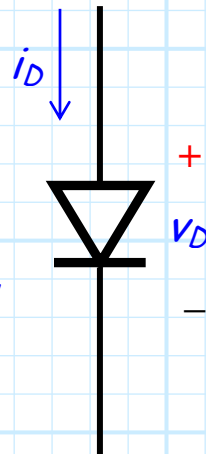
Q: *Yikes! Won't the the numerical values of both i_D and v_D be **negative** for a zener diode (assuming only rb and b.d. modes).*



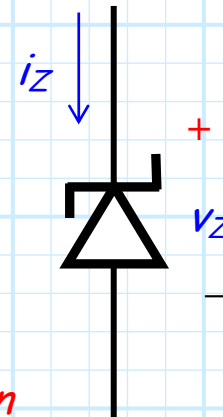
A: With the **standard** diode notation, this is true.

Thus, to **avoid** negative values in our circuit computations, we are going to **change the definitions** of diode current and voltage!

*Conventional
diode
notation*



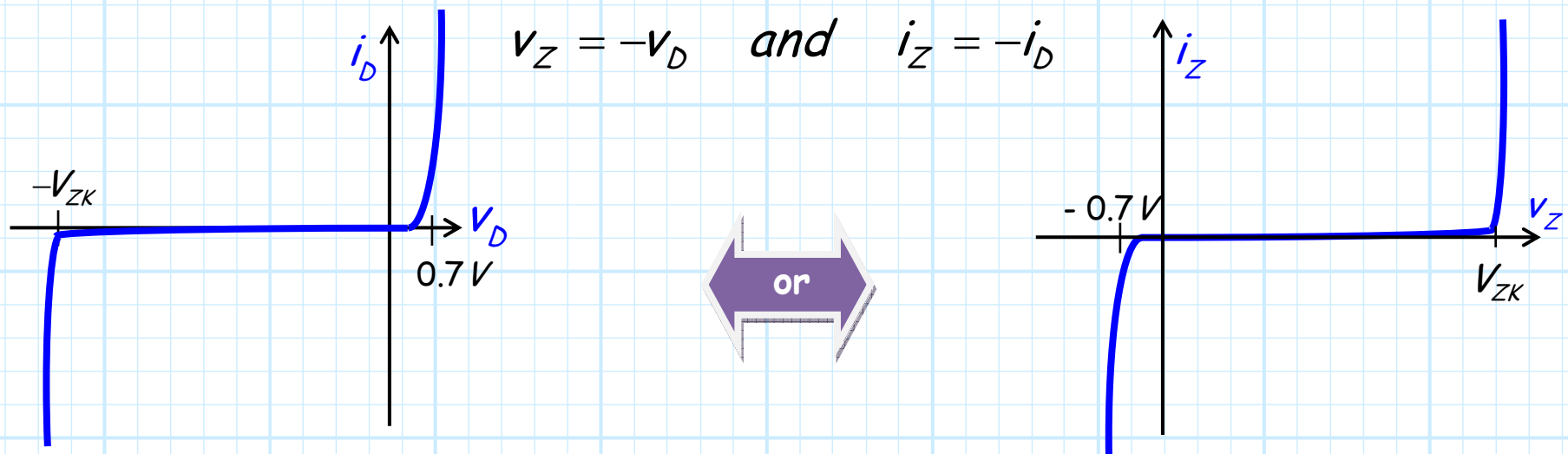
*Zener
diode
notation*



Stand on your head, and you will see that it is the same plot!

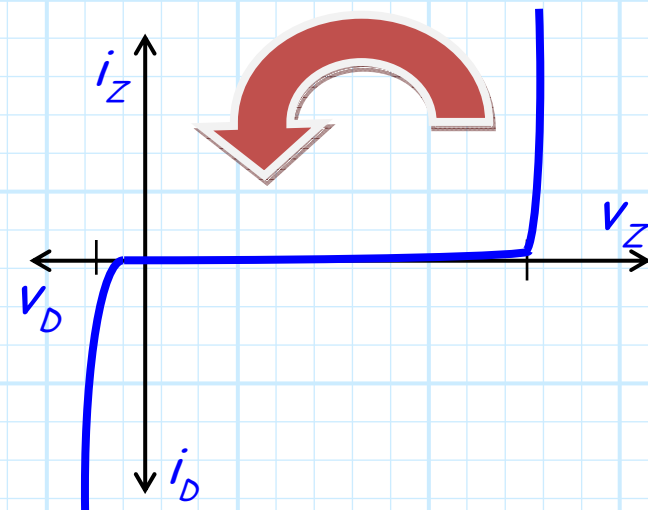
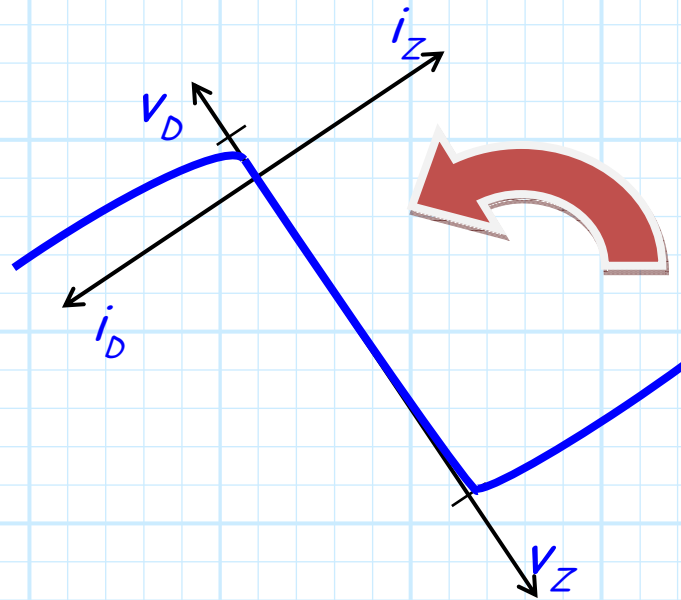
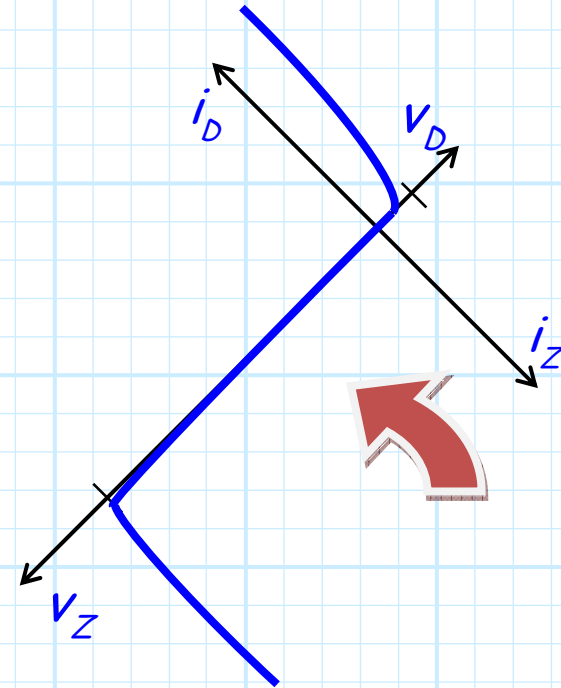
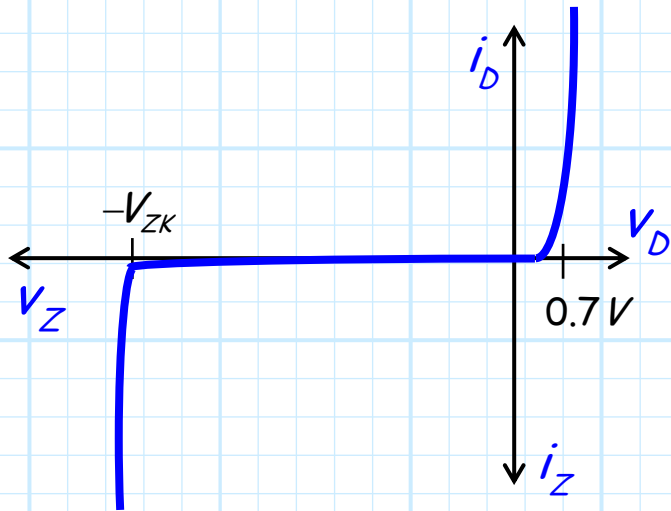
- * In other words, for a Zener diode, we denote current flowing from **cathode to anode** as **positive**.
- * Likewise, we denote diode voltage as the potential at the **cathode** with respect to the potential at the **anode**.

Note that each of the above two statements are precisely **opposite** to the "conventional" junction diode notation that we have used thus far:



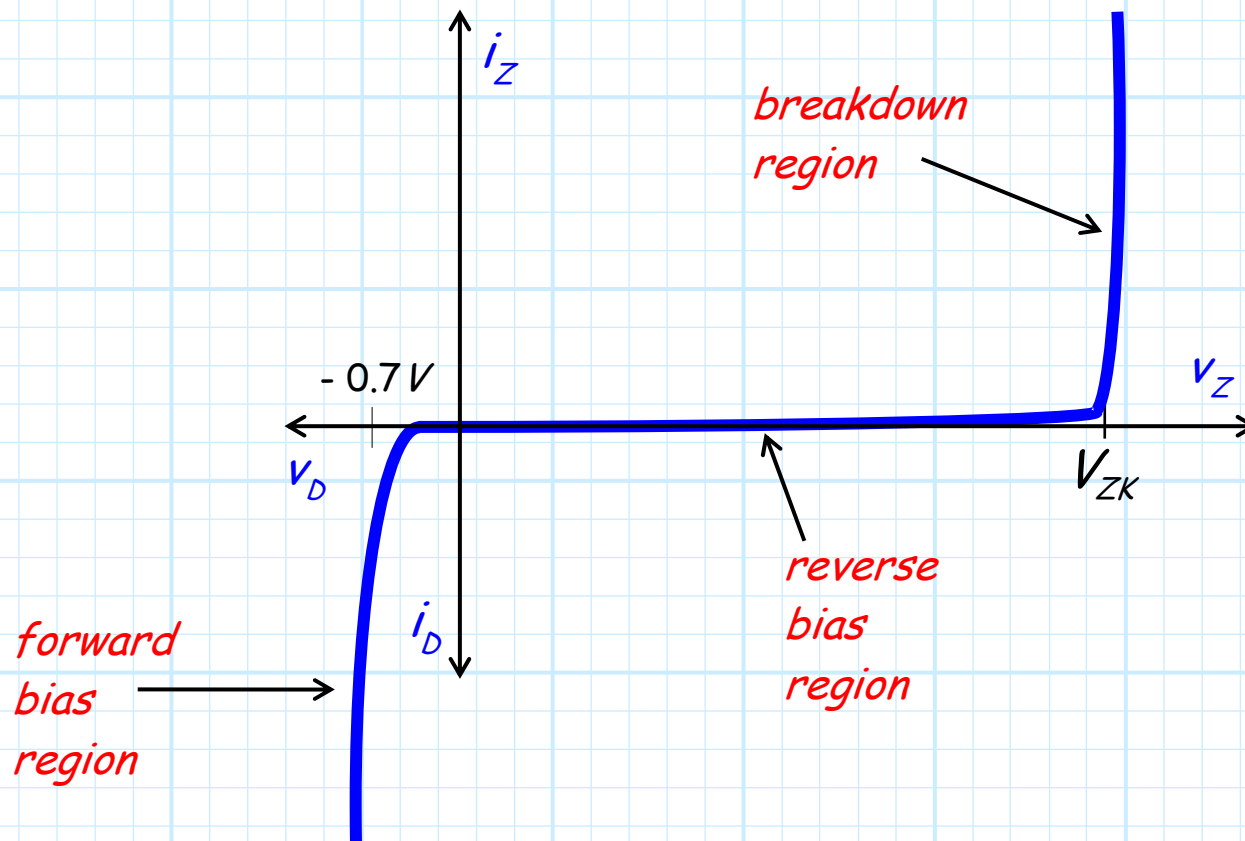
Two ways of expressing the **same** junction diode curve!

We're just rotating the plot



The Zener diode curve—same as the old curve (stand on head)

The i_Z versus V_Z curve for a Zener diode is therefore:



A mathematical statement of each region

Thus, in the **forward bias region** (as unlikely as this is):

$$i_Z = -I_s \exp\left(\frac{-v_Z}{nV_T}\right)$$

or approximately:

$$v_Z \approx -0.7 \text{ V and } i_Z < 0$$

Likewise, in **reverse bias region**:

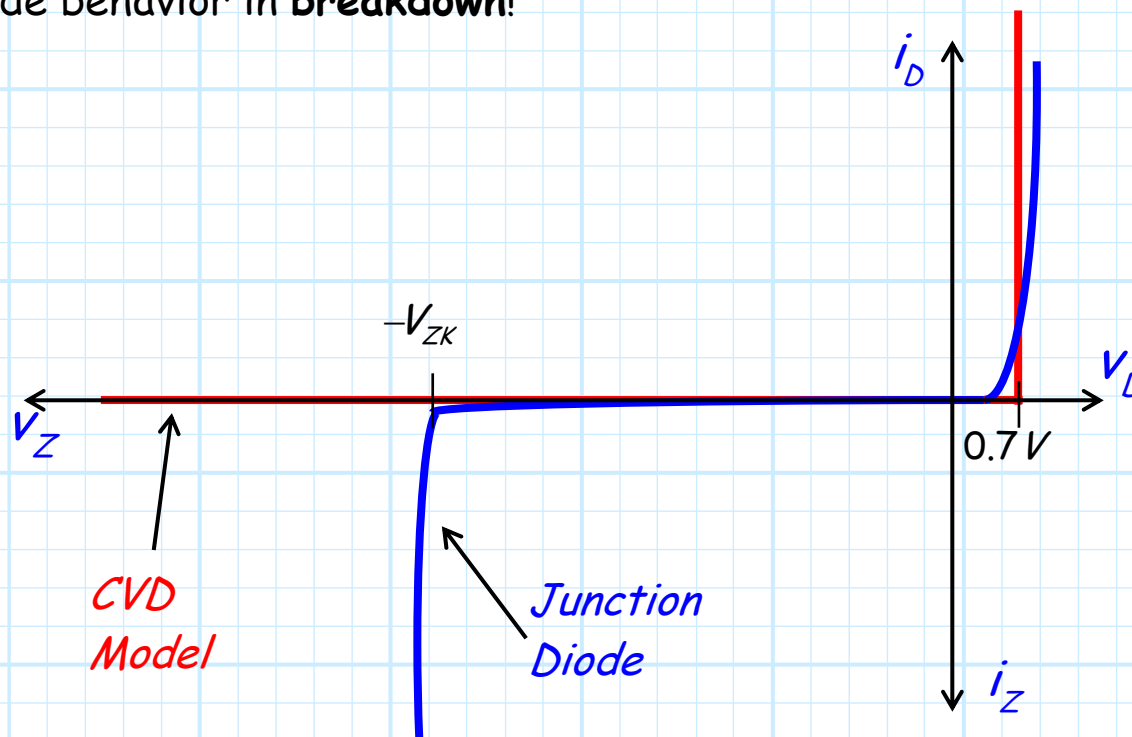
$$i_Z \approx I_s \quad \text{and} \quad 0 < v_Z < V_{ZK}$$

And finally, for **breakdown region**:

$$i_Z > 0 \quad \text{and} \quad v_Z \approx V_{ZK}$$

Zener Diode Models

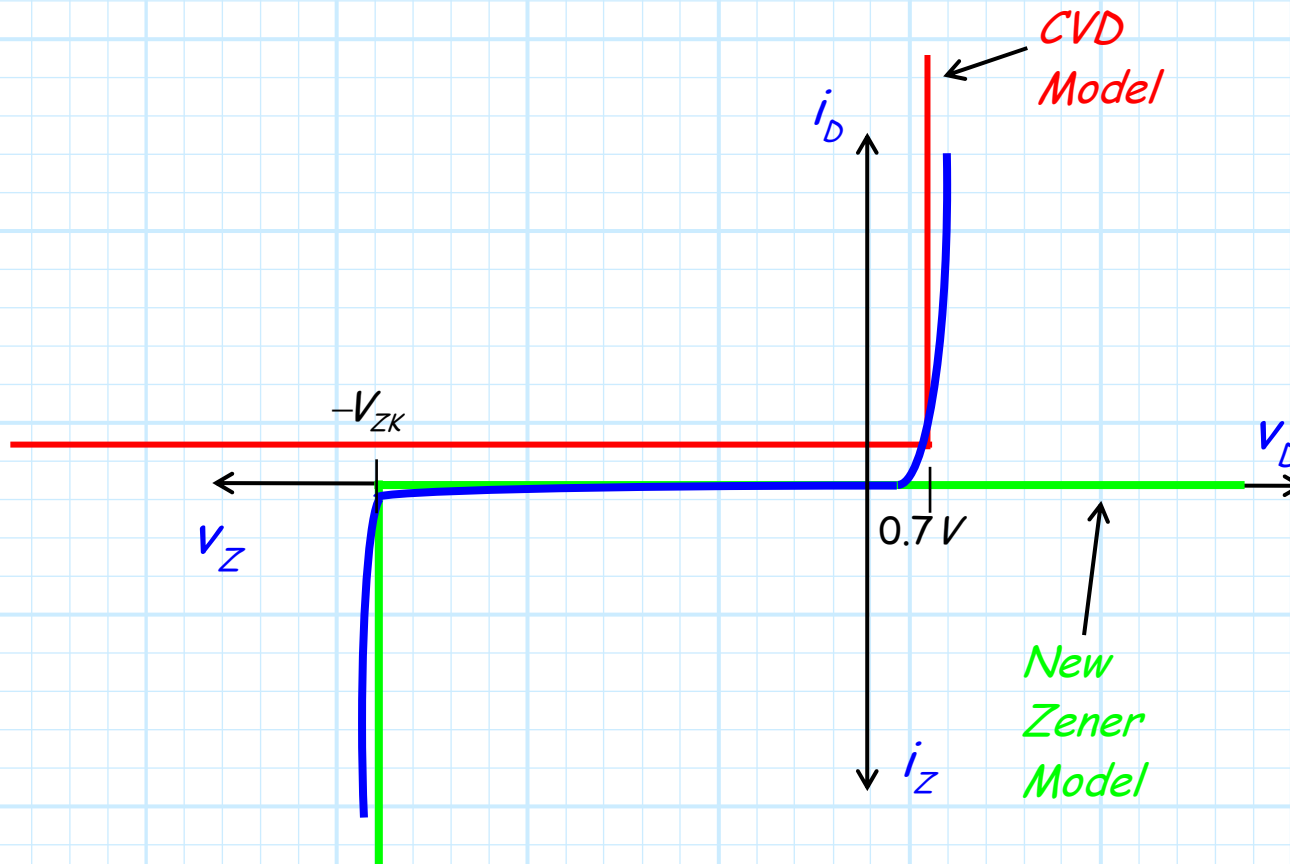
The conventional diode models we studied earlier were based on junction diode behavior in the **forward** and **reverse** bias regions—they did **not** “match” the junction diode behavior in **breakdown**!



However, we assume that **Zener** diodes most often operate in **breakdown**—we need **new** diode models!

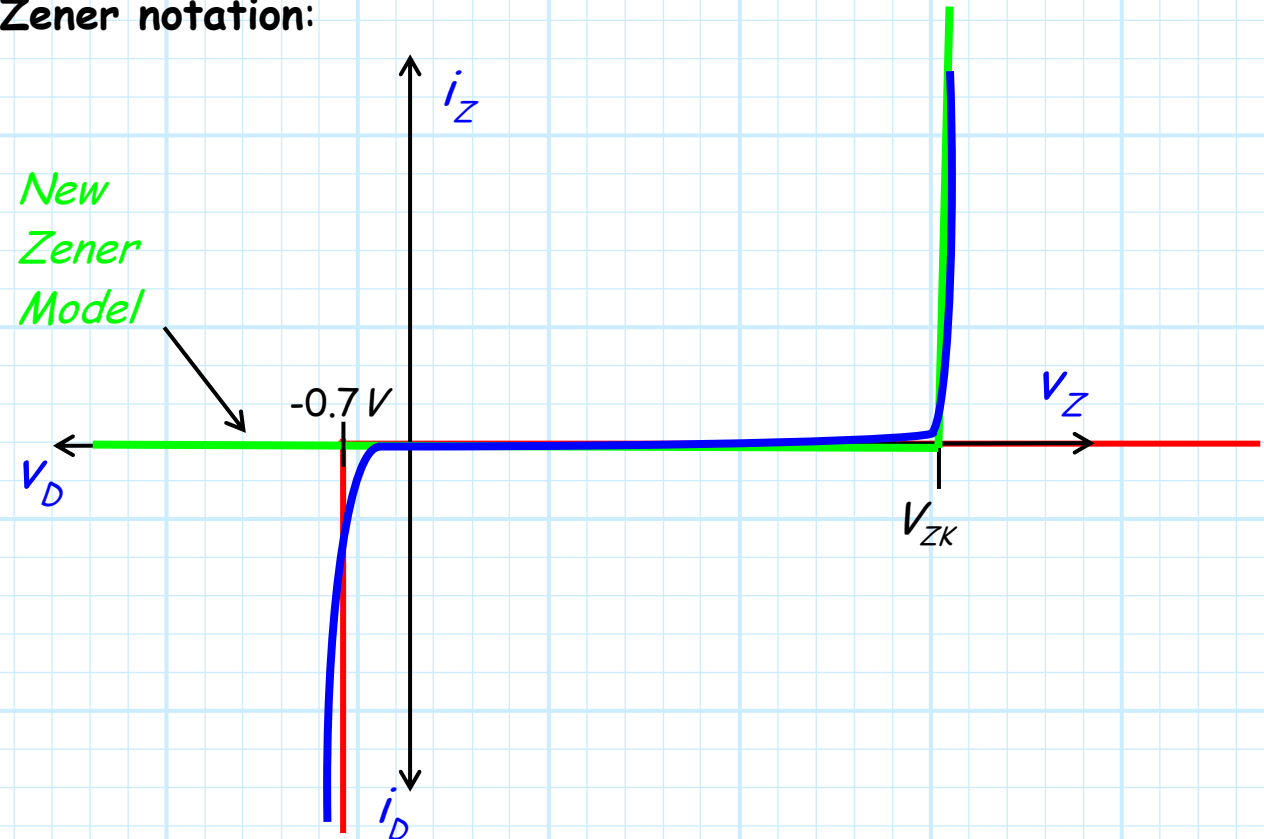
We need to match in the breakdown and reverse bias regions

Specifically, we need **new Zener models**, ones that matches junction/Zener diode behavior in the **reverse bias** and **breakdown** regions.



In terms of Zener notation

Or, "rotating" into the Zener notation:



We will study **two** important zener diode models, each with **familiar** names!

1. The **Constant Voltage Drop (CVD) Zener** model
2. The **Piece-Wise Linear (PWL) Zener** model

Here's an accurate model!

Let's see, we know that a Zener Diode in the **reverse** bias region can be described as:

$$i_Z \approx I_s \approx 0 \quad \text{if} \quad v_Z < V_{ZK}$$

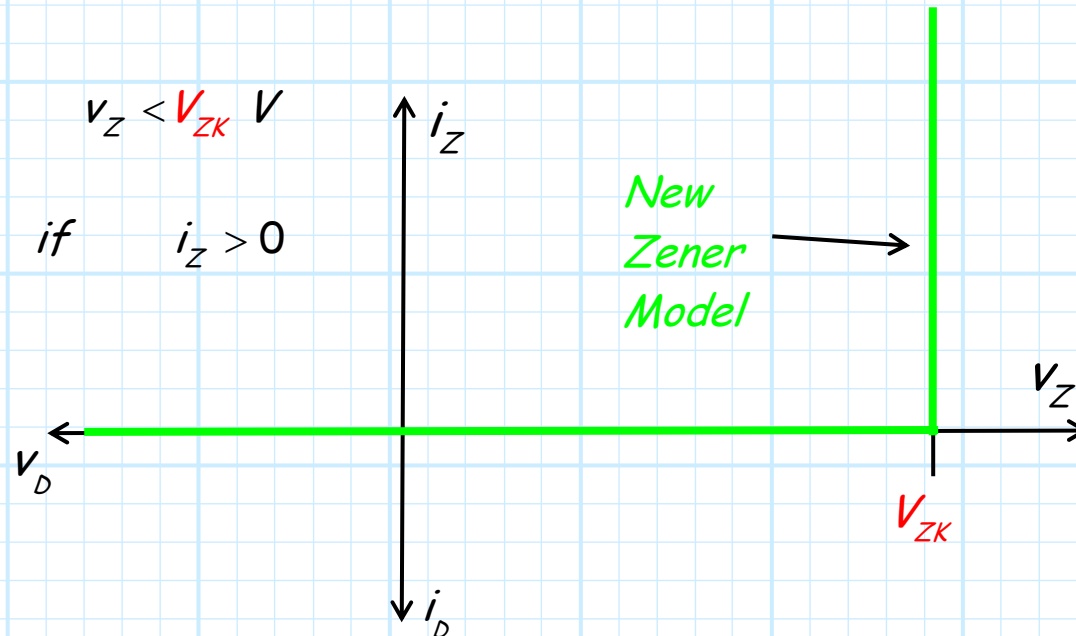
Whereas a Zener in the **breakdown** region is approximately stated as:

$$i_Z > 0 \quad \text{if} \quad v_Z \approx V_{ZK}$$

Thus, an accurate Zener model would have this "curve":

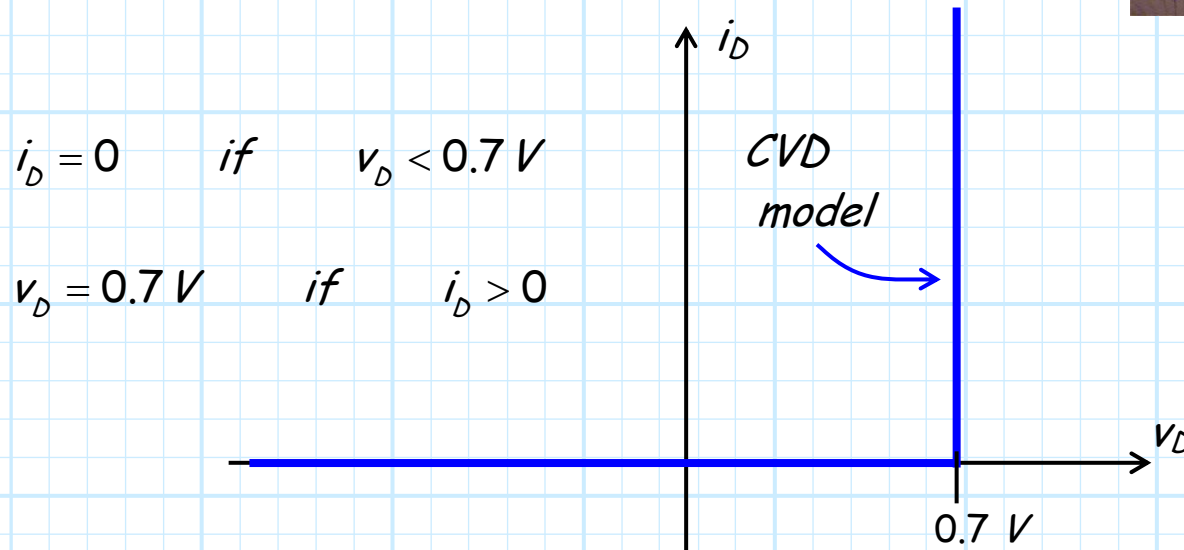
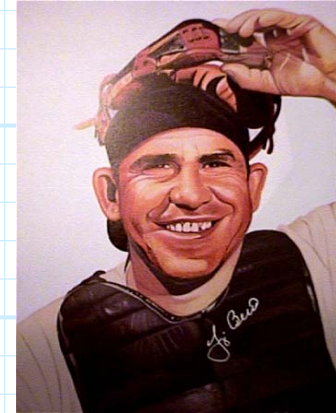
$$i_Z = 0 \quad \text{if} \quad v_Z < V_{ZK}$$

$$v_Z = V_{ZK} \quad \text{if} \quad i_Z > 0$$



Déjà vu all over again

Q: Hey, this is very similar to the CVD model we studied earlier:



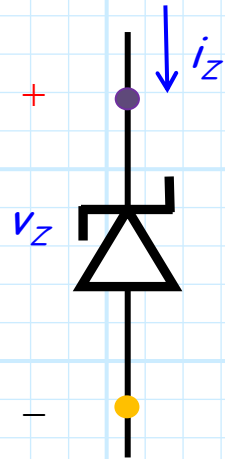
We've just sort of changed 0.7 into V_{ZK} !

Can we just change the 0.7 V battery in the CVD model into a voltage source of V_{ZK} ?

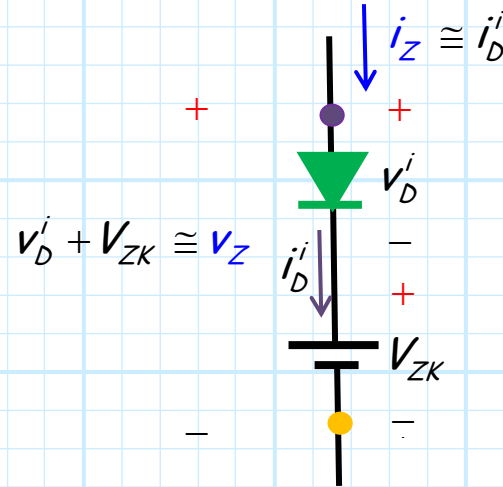
So many lost points because of this

A: That's exactly correct!

Replace:



with:



Zener
CVD
Model

Q: Hey wait!

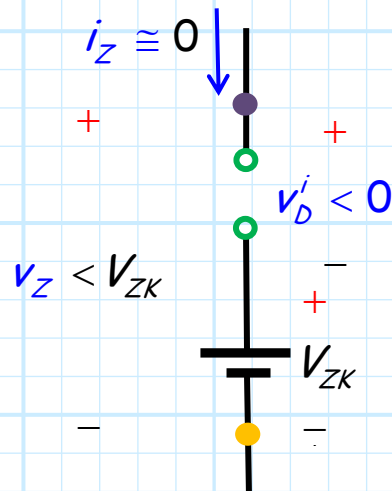
*The cathode of the Zener diode is oriented **upward** (i.e., at the purple node) while the ideal diode cathode is oriented **downward** (i.e., the anode is at the purple node).*

Is that correct?

A: Absolutely! Make sure **you** get this **right!**



Ideal is reverse biased, Zener is reverse biased, but...



Analyzing this Zener CVD model, we find that if the model voltage v_Z is less than V_{ZK} (i.e., $v_Z < V_{ZK}$), then:

- * the **ideal** diode will be in **reverse** bias,
- * and thus the model current i_Z will equal **zero**.

In other words:

$$i_Z = 0 \quad \text{and} \quad v_Z < V_{ZK}$$

Just like a **Zener** diode in operating in the **reverse bias region!**

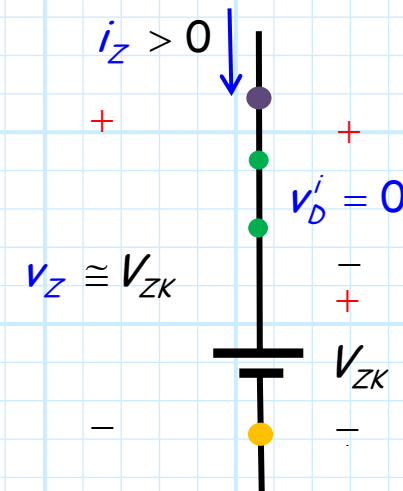
...if Ideal is forward biased, Zener is in breakdown!

Likewise, we find that if the model current is positive ($i_Z > 0$), then:

- * the **ideal** diode must be **forward** biased, and
- * the model voltage must be $v_Z = V_{ZK}$.

In other words:

$$i_Z > 0 \quad \text{and} \quad v_Z = V_{ZK}$$



Just like a **Zener** diode in operating in the **breakdown region!**

→ Carefully consider this case—if the **IDEAL** diode is **forward biased**, the model estimates the **Zener** diode voltage and current when operating in the **breakdown region**—this is **not a contradiction!**



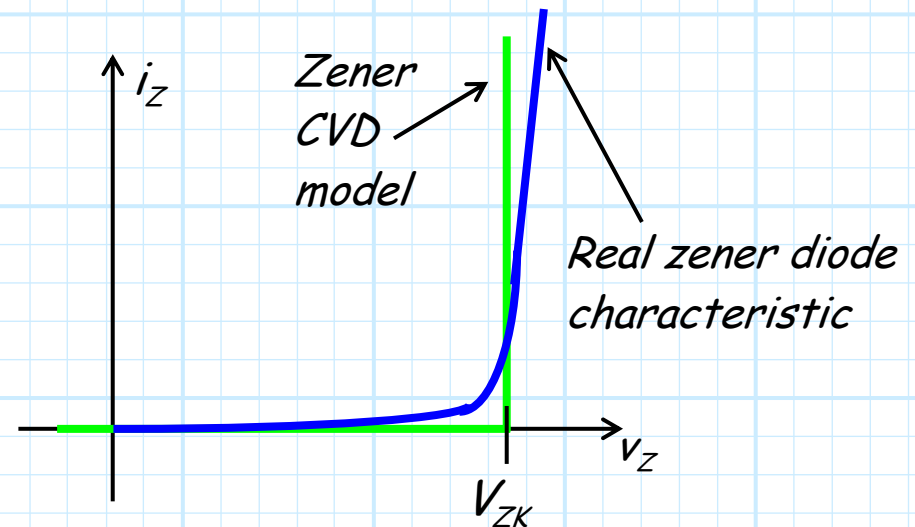
The voltage is not *quite* constant

Q: *So how accurate is the Zener CVD model?*

A: **Quite** accurate! But it is **not** exact.

Here's the **problem**: the voltage across a zener diode in breakdown is not **exactly** equal to V_{ZK} for all $i_z > 0$.

In **reality**, v_z **increases** a very small (**tiny**) amount as i_z increases.



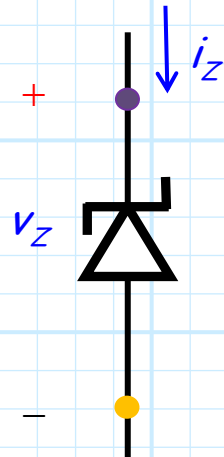
Thus, the CVD model causes a **small** error, usually acceptable—but for some cases **not!**

For these cases, we require a **better** model:

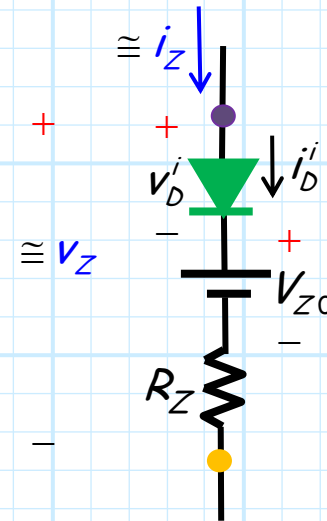
→ The Zener (PWL) Piece-Wise Linear model.

The Zener Piecewise Linear model

Replace:



with:



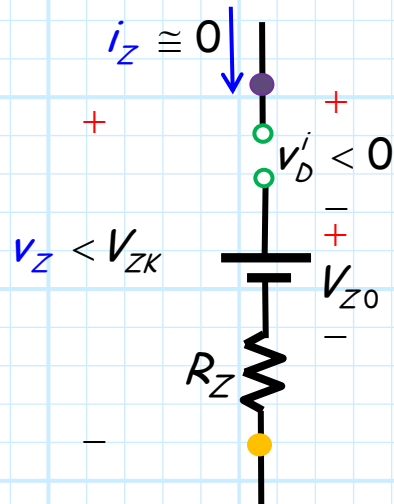
*Zener
PWL
Model*

Please Note:

- * The PWL model includes a **very small** (e.g., 0.01Ω) series resistor, such that the voltage across the model v_Z **increases slightly** with increasing i_Z .
- * This **small** resistance R_Z is called the **dynamic resistance** of the Zener diode.
- * The voltage source V_{Z0} is **not** precisely equal to the Zener breakdown voltage V_{ZK} , however, it is typically **very close**!

Smells like reverse bias region

Analyzing this Zener PWL model, we find that if the model voltage v_Z is less than V_{Z0} (i.e., $v_Z < V_{Z0}$), then:



- * the ideal diode will be in reverse bias, and
- * the model current i_Z will equal zero.

In other words:

$$i_Z = 0 \quad \text{and} \quad v_Z < V_{Z0} \cong V_{ZK}$$

Just like a Zener diode operating in the reverse bias region!

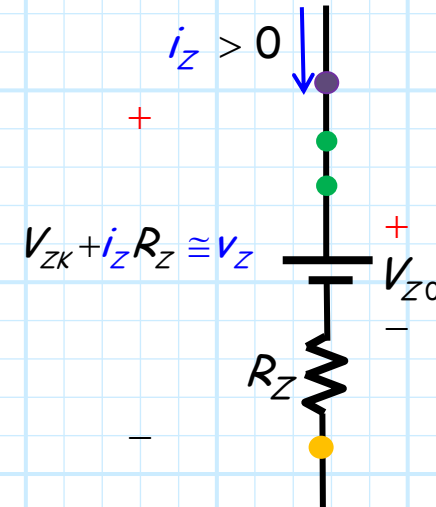
Smells like breakdown region

Likewise, we find that if the model current is positive ($i_Z > 0$), then:

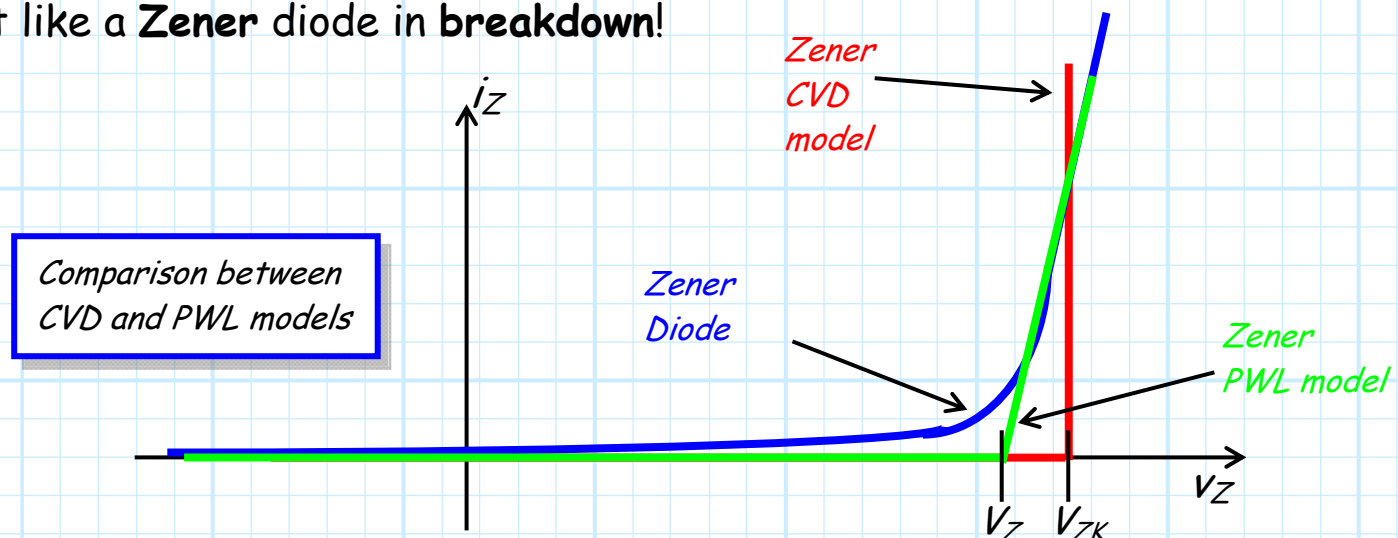
- * the **ideal** diode must be **forward** biased,
- * and thus the model **voltage** is:

$$v_Z = V_{Z0} + i_Z r_Z$$

Note that the model voltage v_Z will be near V_{ZK} , but will increase **slightly** as the model current increases.



→ Just like a **Zener** diode in **breakdown**!

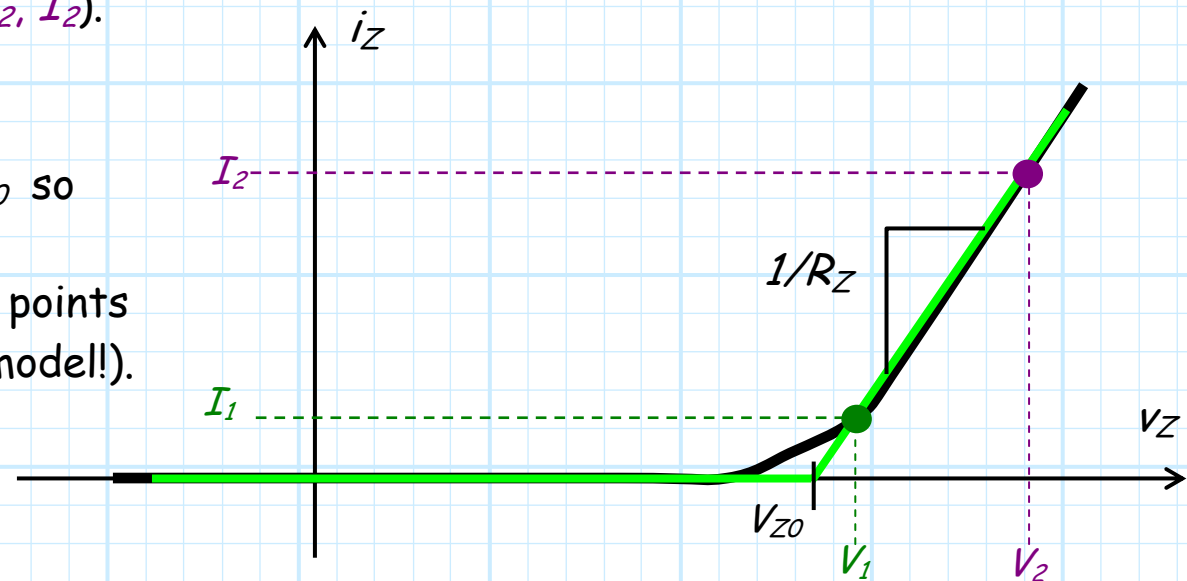


Thank your middle school math teacher

Q: But how do we *construct* this PWL model; how do we determine the values of V_{Z0} and R_Z ?

A: Typically, the manufacturer will provide **two** or more test points on the zener diode curve (V_1, I_1) and (V_2, I_2).

We then select R_Z and V_{Z0} so that the PWL model line **intersects** these two test points (just like the other PWL model!).



Specifically, the dynamic resistance is:

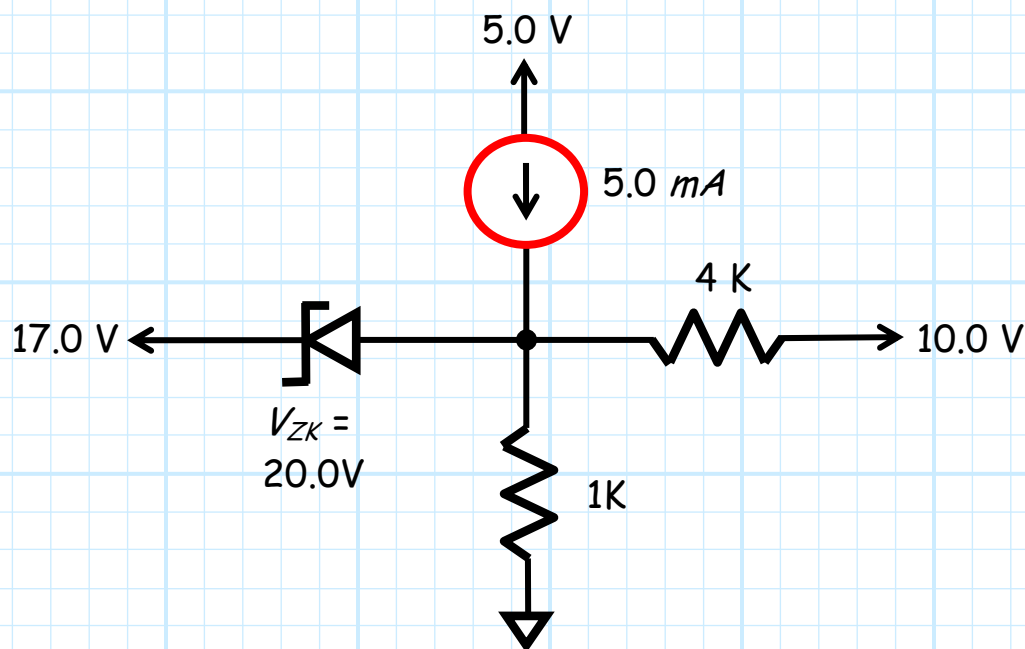
$$R_Z = \frac{V_2 - V_1}{I_2 - I_1} \quad (\text{a very small value!})$$

and

$$V_{Z0} = V_1 - I_1 R_Z \quad \text{or} \quad V_{Z0} = V_2 - I_2 R_Z$$

Example: Fun with Zener Diode Models

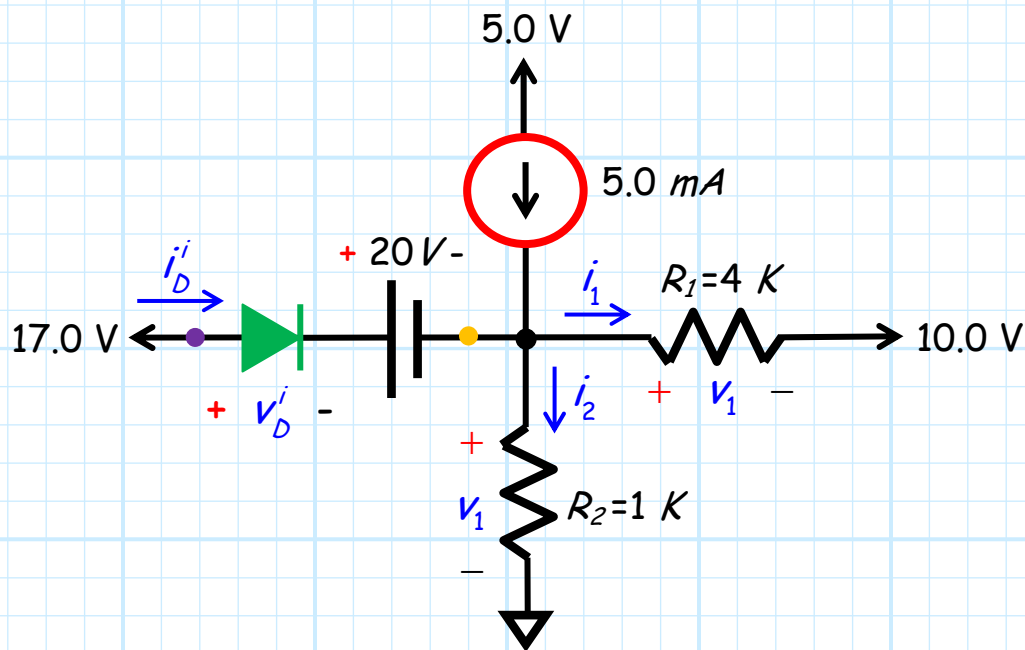
Consider **this** circuit, which includes a **Zener** diode:



Let's see if we can determine the **voltage** across and **current** through the Zener diode!

First, we must replace the Zener diode with an appropriate **model**. Assuming that the Zener will either be in breakdown or reverse bias, a good choice would be the **Zener CVD model**.

Carefully replacing the Zener diode with this model, we find that we are left with an **IDEAL** diode circuit:



Since this is an **IDEAL** diode circuit, we know how to analyze it!



Q: *But wait! The ideal diode in this circuit is part of a **Zener** diode model. Don't we need to thus **modify** our ideal diode circuit analysis procedure in some way?*

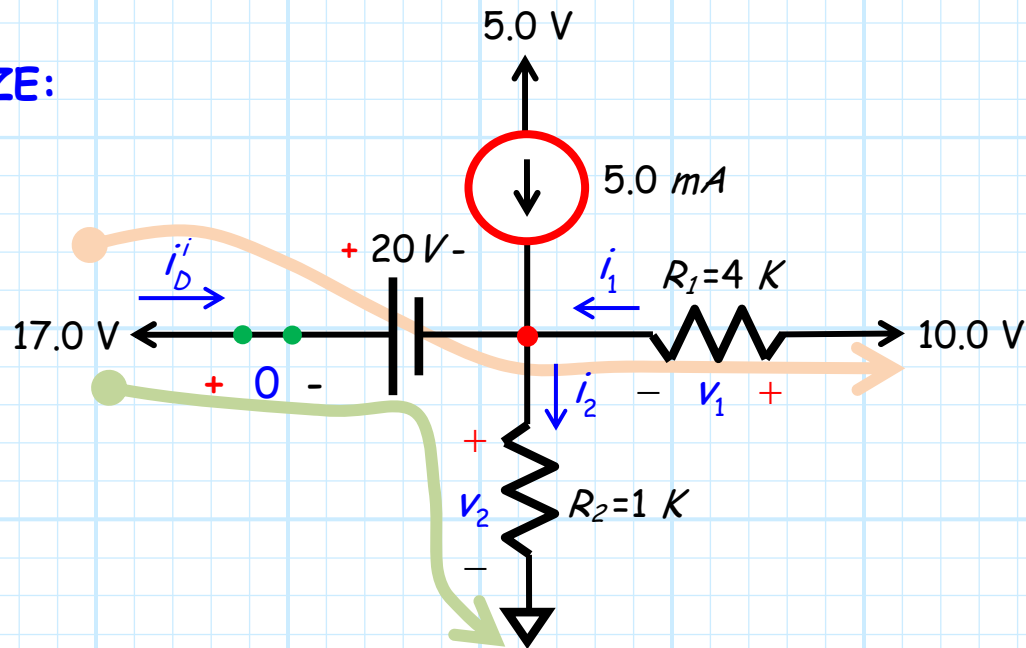
*In order to account for the **Zener** diode behavior, shouldn't we **alter** what we assume, or what we enforce, or what we check?*

A: **NO!** There are **no Zener diodes** in the circuit above! We must analyze this **ideal** diode circuit in **precisely** the same way as we have **always** analyzed ideal diode circuits (i.e., section 3.1).

ASSUME: Ideal diode is **forward biased**.

ENFORCE: $v_D' = 0$

ANALYZE:



From **KVL**:

$$17 - v_D' - 20 - v_2 = 0$$

$$\therefore v_2 = 17 - 0 - 20 = -3.0 \text{ V}$$

Likewise from **KVL**:

$$17 - v_D' - 20 + v_1 = 10$$

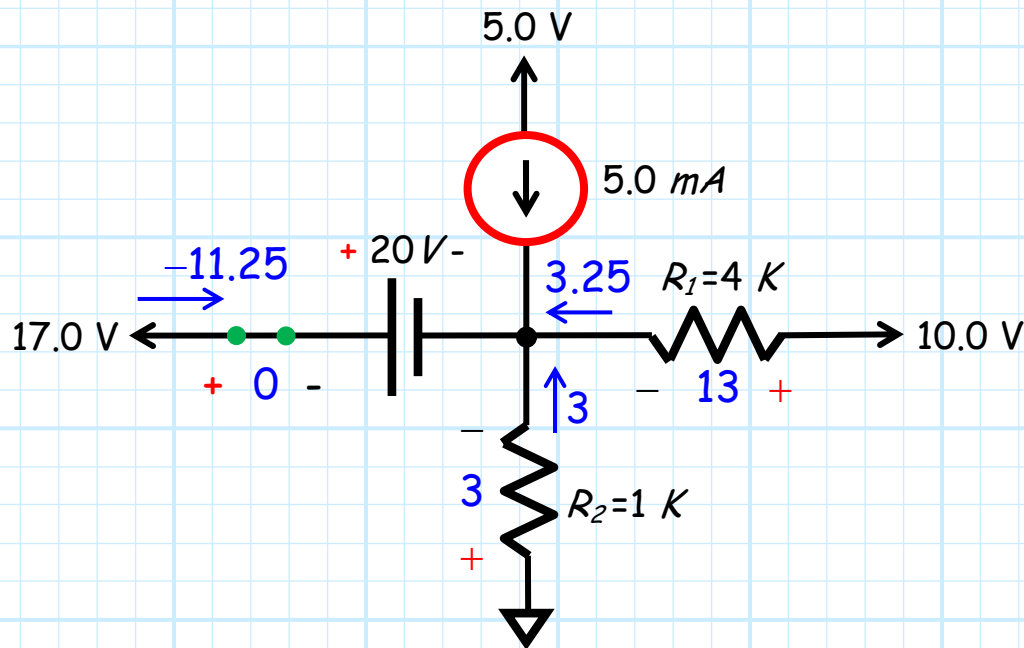
$$v_1 = 10 + 20 + 0 - 17 = 13.0 \text{ V}$$

Now from **Ohm's Law**:

$$i_1 = \frac{v_1}{R_1} = \frac{13}{4} = 3.25 \text{ mA} \quad \text{and} \quad i_2 = \frac{v_2}{R_2} = \frac{-3}{1} = -3.0 \text{ mA}$$

Finally, from **KCL**:

$$\begin{aligned} i_D^i &= i_2 - i_1 - 5.0 \\ &= -3.0 - 3.25 - 5.0 = -11.25 \text{ mA} \end{aligned}$$



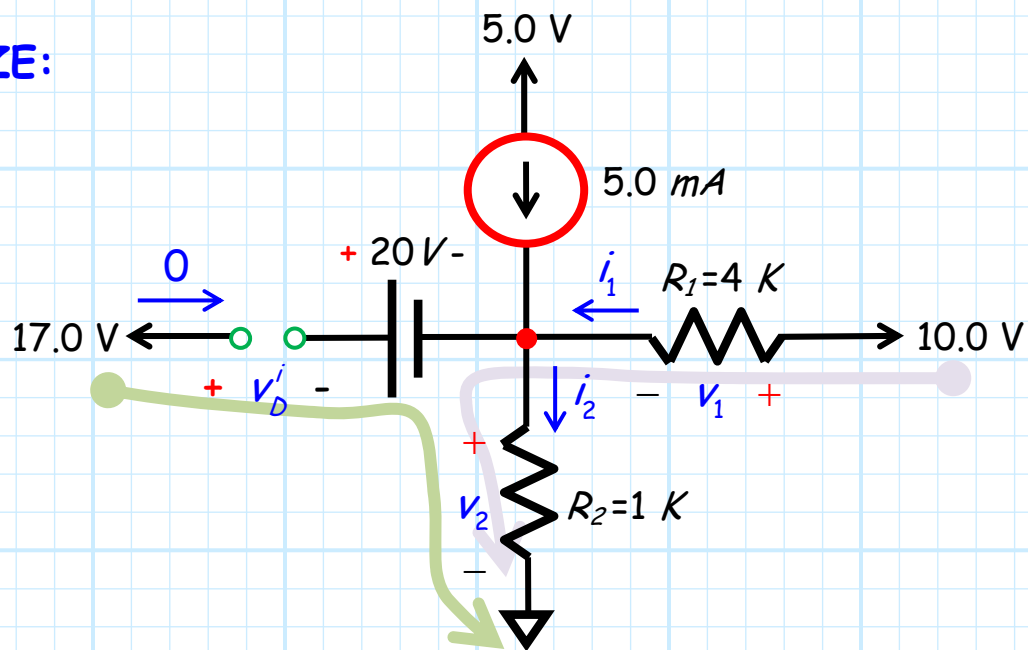
CHECK: $i_D^i = -11.25 \text{ mA} > 0$ **X**

Yikes! We must **MODIFY** our **ideal** diode assumption and try again.

ASSUME: Ideal diode is **reverse** biased.

ENFORCE: $i_D^i = 0$

ANALYZE:



From **KCL**:

$$i_2 = i_1 + 5 + i_D^i = i_1 + 5$$

Now from **Ohm's Law**:

$$v_1 = i_1 R_1 = 4 i_1 \quad \text{and} \quad v_2 = i_2 R_2 = (i_1 + 5)(1) = i_1 + 5$$

From **KVL**:

$$10.0 - v_1 - v_2 = 0$$

$$\therefore 10.0 - 4i_1 - (i_1 + 5) = 0$$

Now solving for i_1 :

$$i_1 = \frac{10 - 5}{4 + 1} = 1.0 \text{ mA}$$

Therefore:

$$i_2 = i_1 + 5 = 1 + 5 = 6.0 \text{ mA}$$

And:

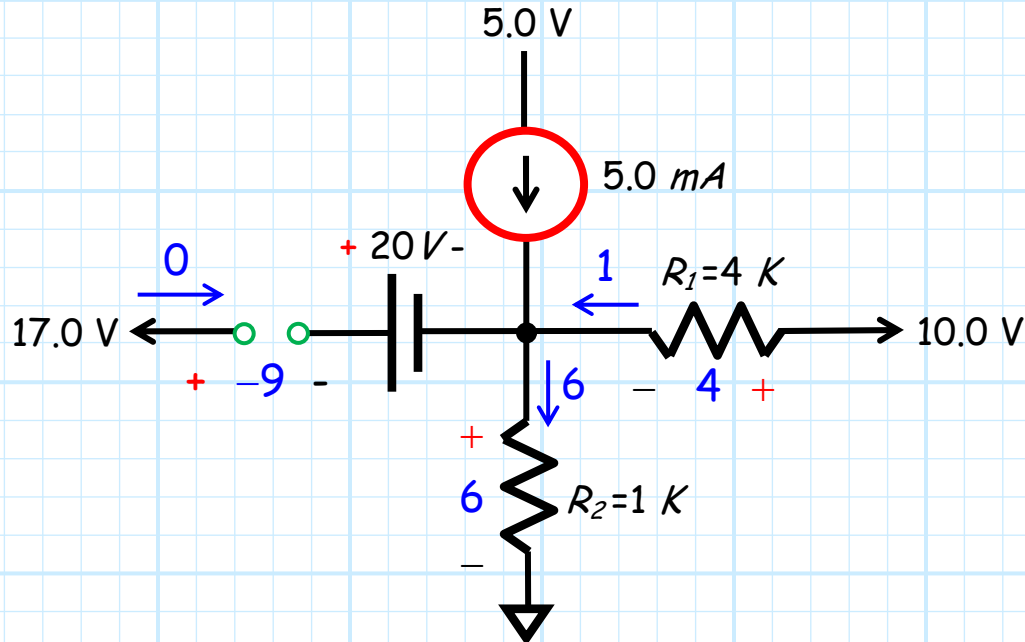
$$v_1 = 4i_1 = 4(1) = 4.0 \text{ V} \quad \text{and} \quad v_2 = i_1 + 5 = 1 + 5 = 6.0 \text{ V}$$

Now, again using **KVL**:

$$17 - v_D^i - 20 - v_2 = 0$$

Therefore

$$\begin{aligned} v_D^i &= 17 - 20 - v_2 \\ &= 17 - 20 - 6 \\ &= -9.0 \text{ V} \end{aligned}$$



CHECK: $v_D^i = -11.0\text{ V} < 0$ ✓

Q: *Our assumption is good!*

*Since our analysis is **complete**, can we move on to something else?*



A: Not so fast! Remember, we are attempting to find the voltage across, and current through, the **Zener diode**.

To (approximately) determine these values, we find the voltage across, and current through, the Zener diode **model**.

So,

$$\begin{aligned} v_Z &\cong v_D^i + V_{ZK} \\ &= -11 + 20 \\ &= 9.0\text{ V} \end{aligned}$$

and

$$i_Z = i_D^i = 0$$

We're done!



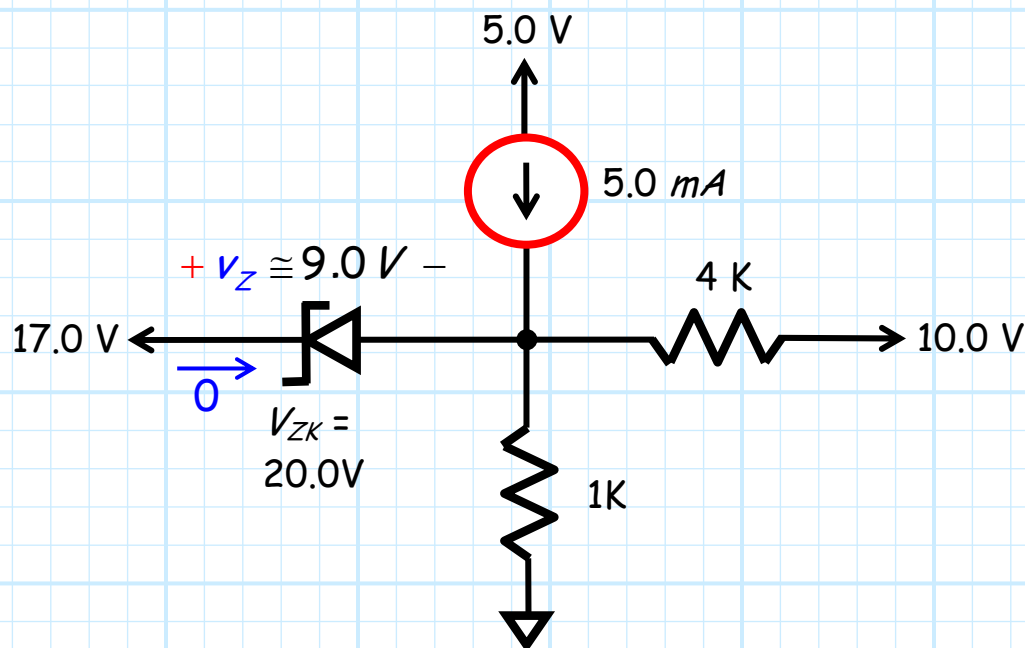
Q: *Wait! Don't we have to somehow **CHECK** these values?*

A: **NO!** We assumed **nothing** about the zener diode, we enforced **nothing** about the zener diode, and thus there is **nothing** to explicitly check in regards to the zener diode solutions.

However—like all engineering analysis—we should perform a “sanity check” to see if our answer makes physical sense.

So, let me ask you the question **Q:** Does this answer make physical sense?

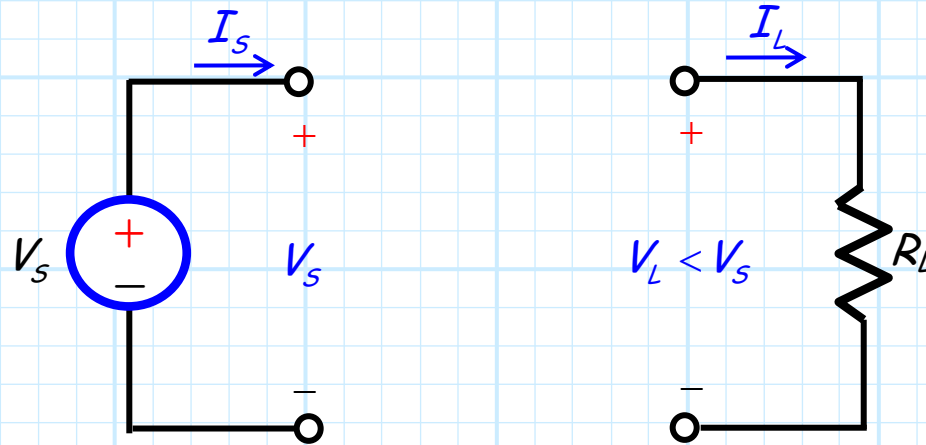
A:



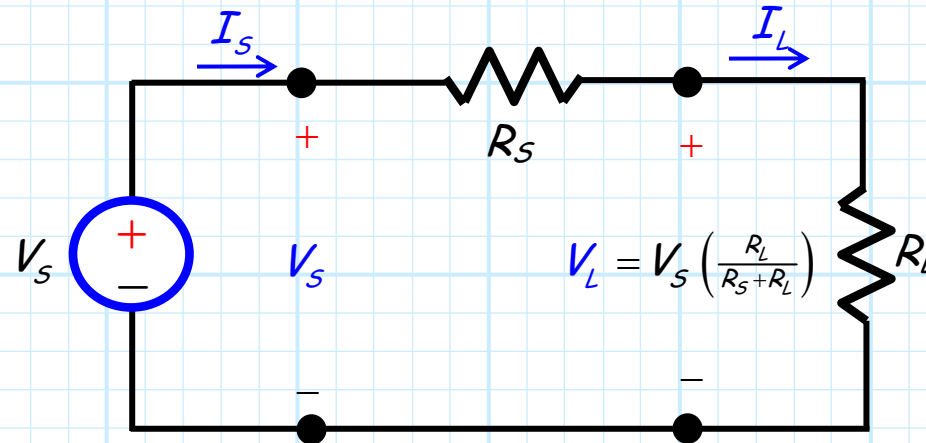
The Shunt Regulator

Say that we have some **source** voltage V_S , but our **load** requires a lower voltage

V_L :



Q: Piece of cake! We just insert the proper series resistor R_S to form a **voltage divider**, right?



A: This in fact is a very **bad solution**—we need a **regulated** voltage across the load.

He's been like that since 1863



A **regulated voltage** is one that is **constant**; it never, **ever** changes—period.

For example, the voltage V_L across the load must be **independent** of the load itself.

If R_L increases or decreases, then the **load current** I_L will decrease or increase—but the voltage V_L should remain **unchanged**.

→ This is know as a **load regulation**.

Or maybe you start watching Netflix

Q: *Why would the load current I_L ever change?*

A: You must realize that the load resistor R_L simply **models** a more **useful** device.

The "load" may in fact be an amplifier, or a component of a **cell phone**, or a circuit board in a digital computer.



These are all **dynamic** devices, such that they may require **more** current at some times than at others (e.g., the **computational** load increases, or the cell phone begins to **transmit**).

Thus, modeling the load as a **resistor** R_L is often not especially accurate; the load instead is **defined by the current** I_L that it "draws".

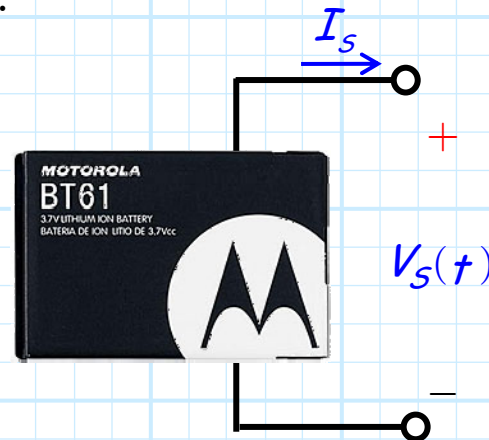
The source voltage changes

Likewise, a regulated voltage **must** remain constant, even if the source voltage V_S changes—this is known as **line regulation**.

Q: *Why would the source voltage V_S ever change?*

A: There are **many** reasons why V_S will not be a perfect constant with **time**.

For example, the energy for an electrical system, such as a “smart phone”, often is supplied by a **chemical battery**.

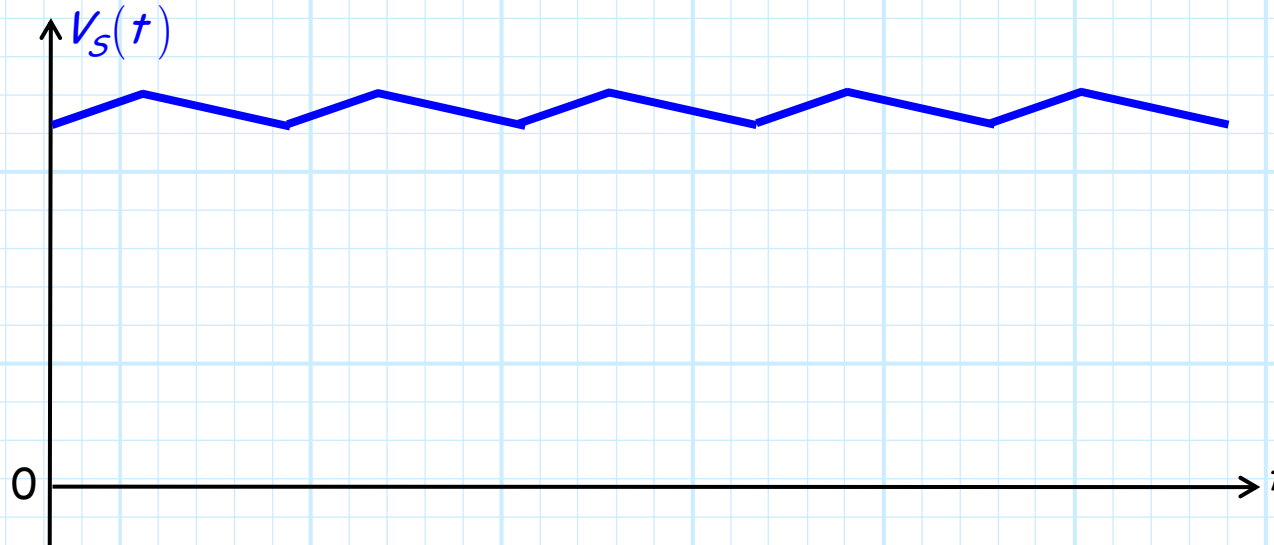


As this battery delivers energy, the voltage across it will slowly **diminish**—it “**runs down**”.

Yet, we need the **regulated** voltage to remain **constant**!

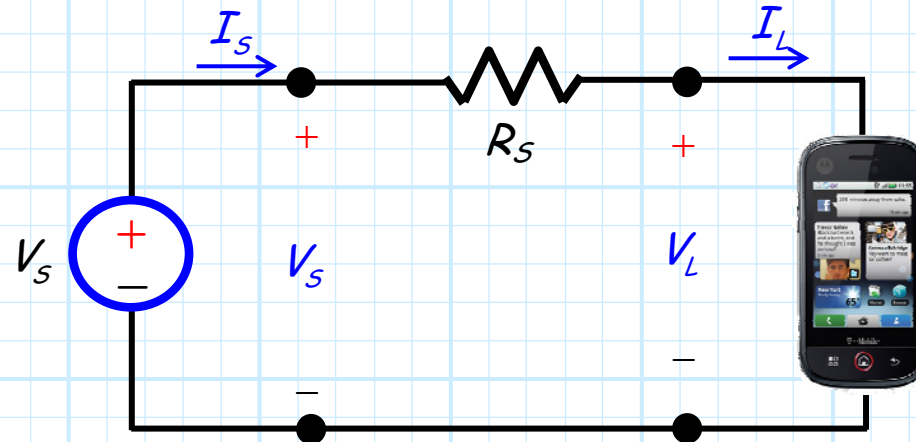
Ripple voltage

Likewise—as we shall learn later—if the source voltage V_S is the output of an **AC** to **DC** power supply, it will likely include an **AC** component—a time-varying (not constant!) signal that we call the **ripple voltage**.



Yikes, the load voltage is unregulated

Let's return to **original** circuit:



From **KVL**, circuit analysis, it is apparent that the difference between the source voltage V_S and load voltage V_L is simply the voltage drop across the **series** resistor R_S

$$V_L = V_S - I_L R_S$$

Clearly, the load voltage V_L depends on **both** source voltage V_S and load current I_L —the load voltage V_L will **change** when V_S and/or I_L change (this is **bad!**).

Calculus: Is there anything it can't do?

To quantify this, we simply take the derivative of V_L with respect to V_S and I_L :

$$\frac{\partial V_L}{\partial V_S} = \frac{\partial (V_S - I_L R_S)}{\partial V_S} = 1.0$$

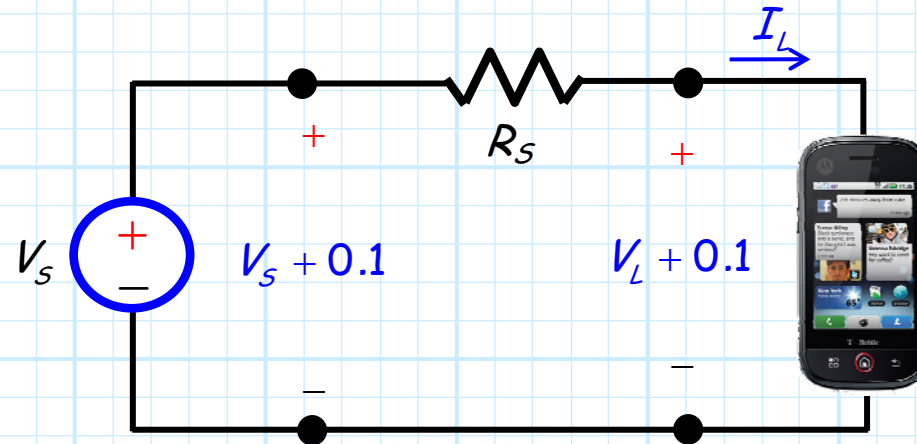
$$\frac{\partial V_L}{\partial I_L} = \frac{\partial (V_S - I_L R_S)}{\partial I_L} = -R_S$$

The first of these derivatives quantifies the **line regulation**.

Since the value is 1.0, the load voltage changes **directly** with the source voltage (provided load current I_L remains **unchanged**).

Line regulation: stinky

For **example**, if the source voltage increases by **100 mV**, the load voltage will increase by **100 mV** as well (again, if I_L remains constant).



This is **very poor** line regulation!

Contrast this with the **ideal** case, wherein the derivative is equal to zero,

This means that a source voltage increase of **100 mV** (or any value, for that matter) results in **no change** in the load voltage.

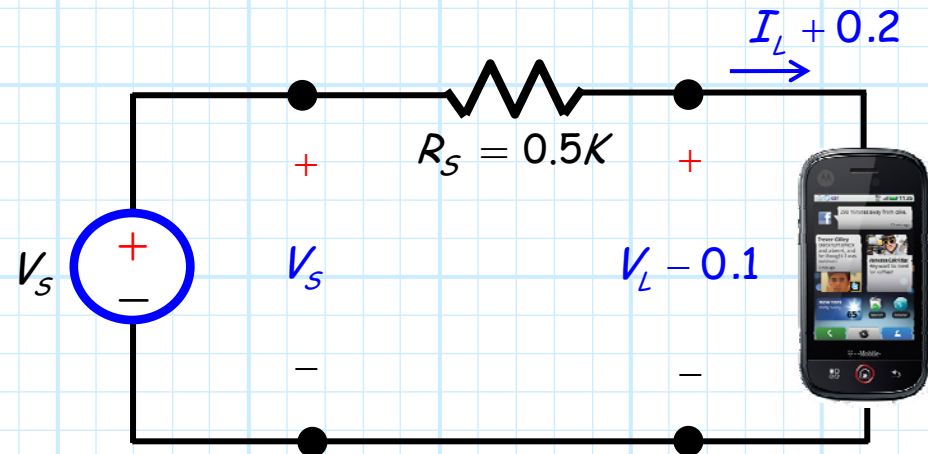
Load regulation: stinky

The second of the derivatives quantifies **load regulation**:

$$\frac{\partial V_L}{\partial I_L} = \frac{\partial (V_S - I_L R_S)}{\partial I_L} = -R_S$$

The **minus** sign in this case means that an **increasing** load current I_L will result in a **decreasing** load voltage (and vice versa).

For **example**, if the series resistor R_S has a value of 500 Ohms ($R_S = 0.5K$), an increase in the load current of **0.2 mA** will cause a **100mV** reduction in the load voltage V_L .



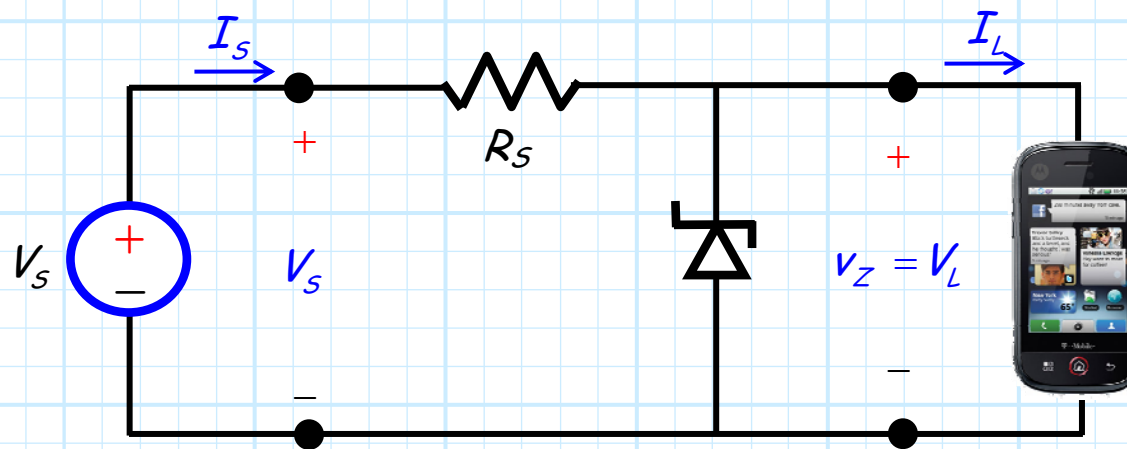
This is **very poor** load regulation!

Contrast this with the **ideal** case, wherein this derivative is equal to zero, meaning that a load current increase of **0.2 mA** (or any value, for that matter) results in **no change** in the load voltage.

Zener diodes to the rescue!

Q: *So what do we do? How do we achieve voltage regulation?*

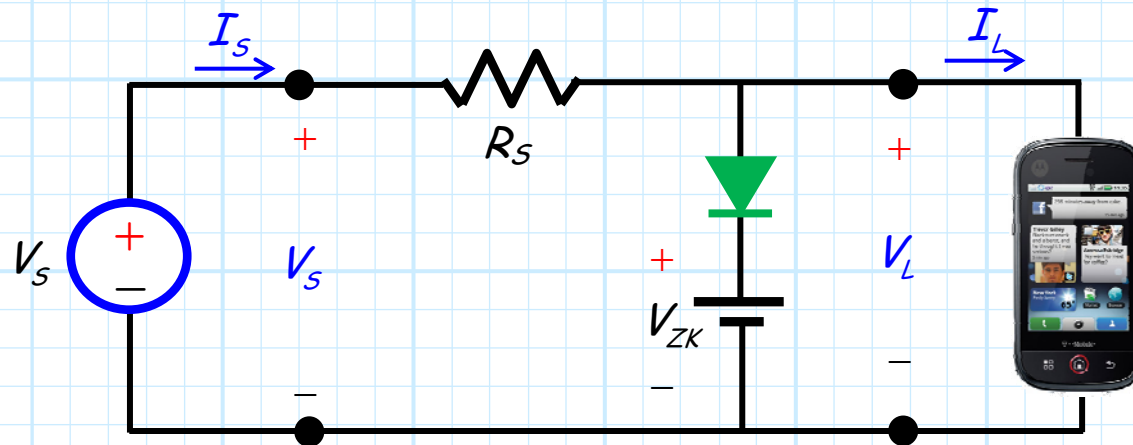
A: One solution is very **simple**—we just add a shunt **Zener diode**!



Q: *Huh? What good would **this** do?*

A: Let's replace the Zener with the **Zener CVD model** and find out!

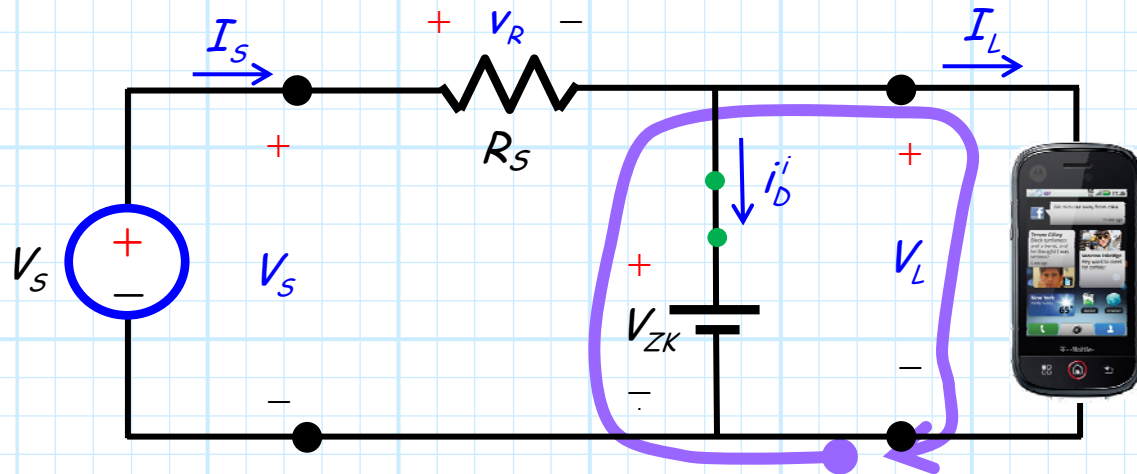
Be careful!



Now let's:

- * ASSUME the **ideal** diode is forward biased,
- * ENFORCE the assumption with a short,
- * and then ANALYZE the resulting circuit.

$$\underline{V_L = V_{ZK} \text{ !!!!!!!!!!!!!!!}}$$



From **KVL**, we arrive at an important result:

$$V_L = V_{ZK} \text{ !!!!!!!}$$

→ The load voltage is equal to the Zener breakdown voltage!!!

Q: *Wow! Is this always true?*

A: It is if the ideal diode forward bias **ASSUMPTION** is correct!

We need to find the ideal diode current

Q: *Is the ASSUMPTION correct?*

A: Let's determine the **ideal diode current** and **find out!**

First, from **KCL**:

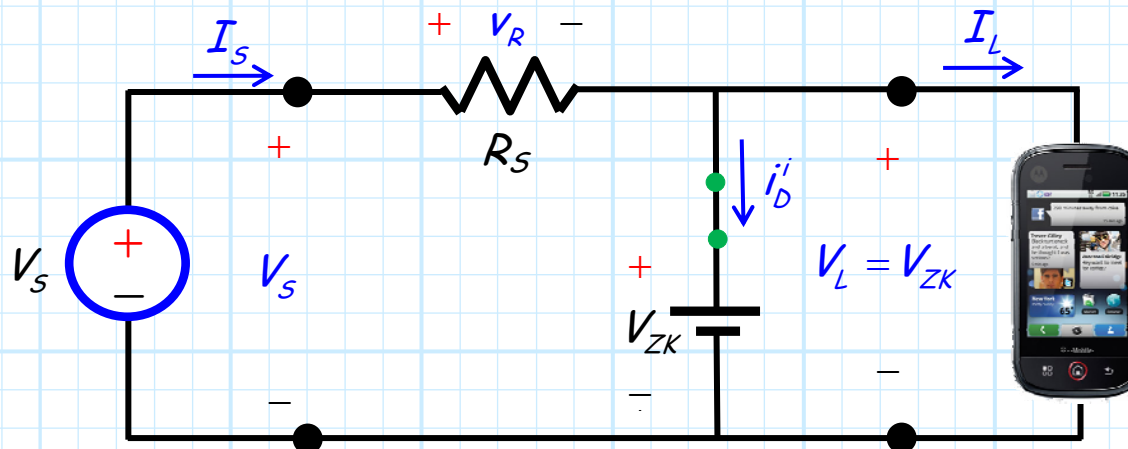
$$i_D^i = I_S - I_L$$

And from Ohm's Law:

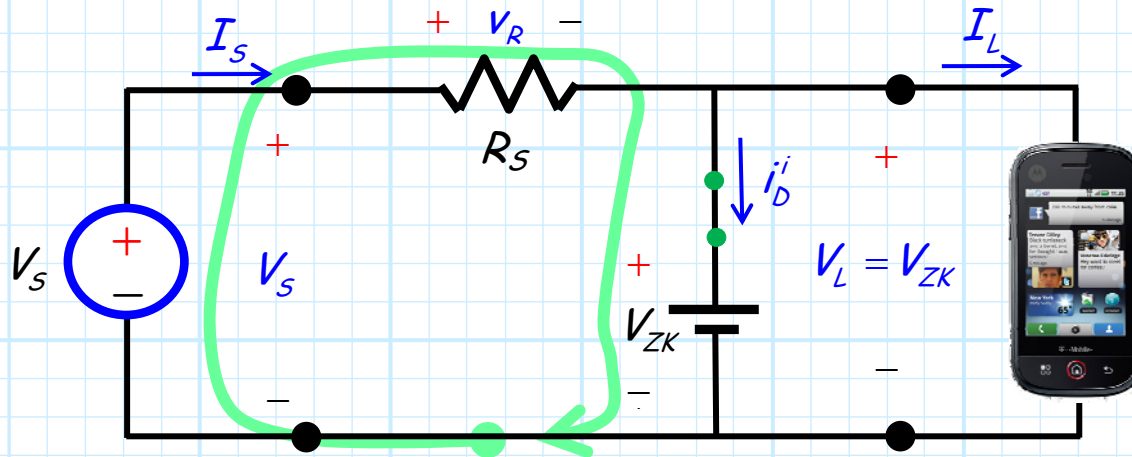
$$I_S = \frac{V_R}{R_S}$$

Therefore:

$$i_D^i = I_S - I_L = \frac{V_R}{R_S} - I_L$$



We found the ideal diode current!



Finally, from **KVL**:

$$V_S - V_R - V_{ZK} = 0 \quad \Rightarrow \quad V_R = V_S - V_{ZK}$$

Therefore, the **ideal** diode current is:

$$i_D^i = \frac{V_R}{R_S} - I_L = \frac{V_S - V_{ZK}}{R_S} - I_L = \frac{V_S}{R_S} - \left(\frac{V_{ZK}}{R_S} + I_L \right)$$

Not if, but when!

Q: So how do we **CHECK** to see if this is positive?

A: Since there are **no numeric values** given to the variable names, we cannot in this case determine **if** the current is positive.

Rather, we can determine **when** the current is positive!

In other words, we can determine the **conditions** that will make this ideal diode current positive. I.E., if:

$$i_D^i = \frac{V_S}{R_S} - \left(\frac{V_{ZK}}{R_S} + I_L \right) > 0$$

we find that:

$$\frac{V_S}{R_S} > \frac{V_{ZK}}{R_S} + I_L$$

$$\Rightarrow V_S > V_{ZK} + R_S I_L$$

They better be true...

Thus, the source voltage V_S **must** be at least $R_S I_L$ **larger** than the load voltage $V_L = V_{ZK}$.

Or rearranging, we equivalently find that the **load** current I_L has a maximum value—it **must** be **less** than the **source** current I_S :

$$I_L < \frac{V_S - V_{ZK}}{R_S} = I_S$$

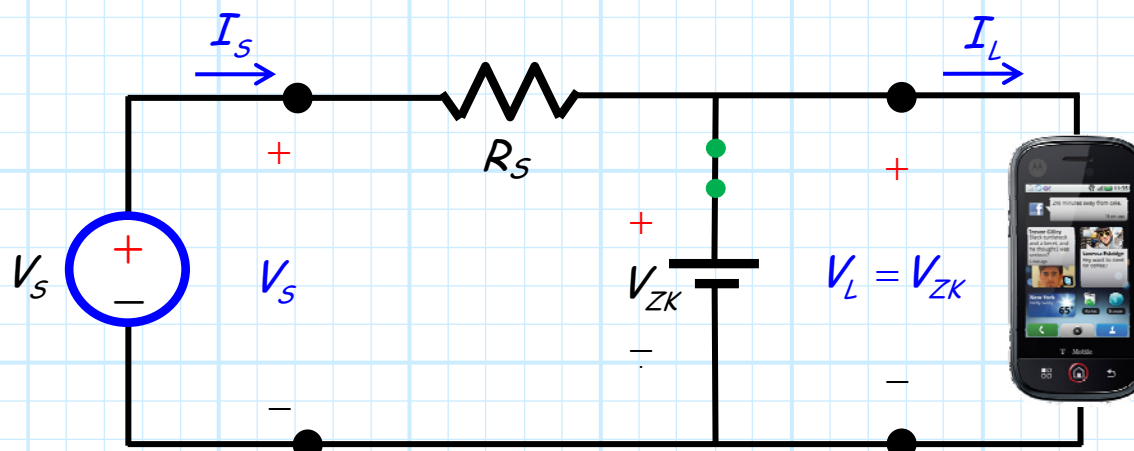
Q: *I'm confused; why **must** these things be true?*

A: They **must** be true in order for the **ideal** diode current in the Zener CVD model to be **positive** (i.e., $i_D^i > 0$)—they **must** be true in order for our **ASSUMPTION** to be correct.

...or else we have no regulation!

And as a result, they **must** be true in order for the load voltage V_L to be equal to the Zener breakdown voltage:

$$V_L = V_{ZK} \quad \text{if} \quad V_S > V_{ZK} + R_S I_L \quad \text{!!!!!!}$$



Since 1863

Q: *Why do you keep putting exclamation points (!!!!!) after $V_L = V_{ZK}$?*

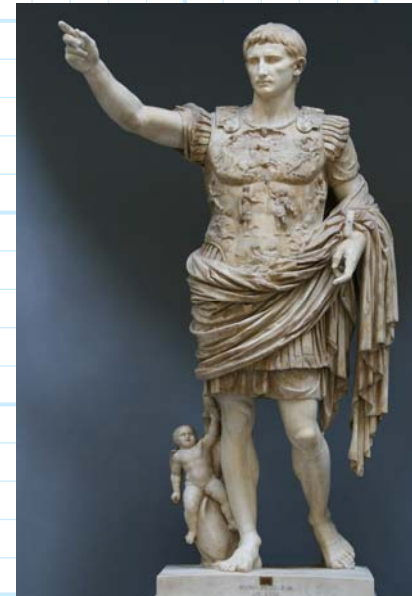
Why is this result such a "big deal"?

A: Because the Zener breakdown voltage V_{ZK} is a **device parameter**—it is a **constant**.

→ It never, **ever** changes—period.

Thus, since the load voltage V_L is equal to V_{ZK} , the load voltage is a constant.

→ It never, **ever** changes—period.



That's what I call regulation!

The line regulation is thus:

$$\frac{\partial V_L}{\partial V_S} = \frac{\partial V_{ZK}}{\partial V_S} = 0.0$$

And the load regulation is:

$$\frac{\partial V_L}{\partial I_L} = \frac{\partial V_{ZK}}{\partial I_L} = 0.0$$

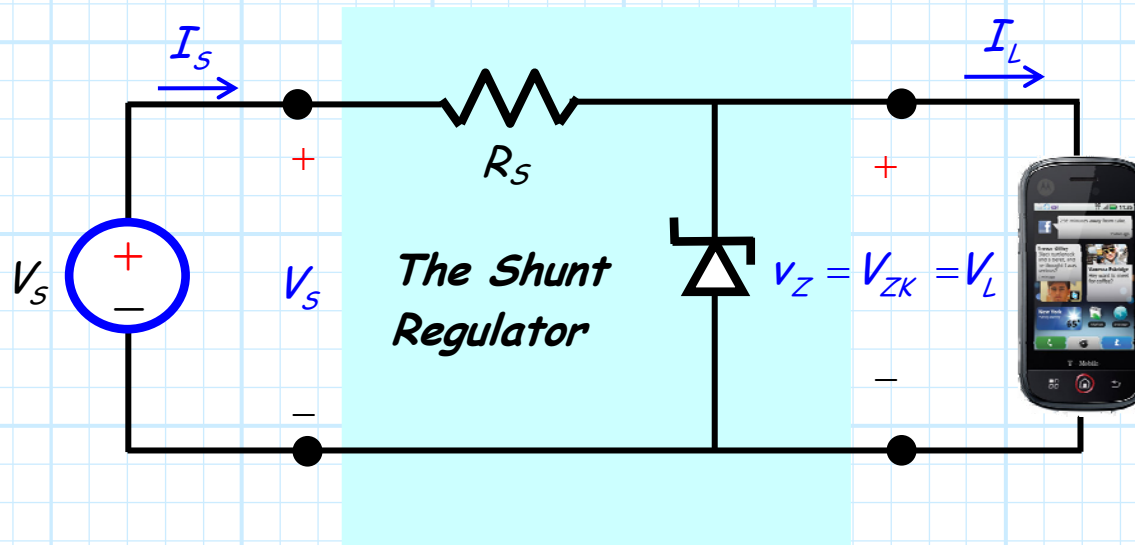
They're both **zero!**

This means that the load voltage will **not change**—it will **remain at V_{ZK}** —even if the source voltage V_S and/or load current I_L **change value** (provided that $V_S > V_{ZK} + R_S I_L$).

→ Now **that's** voltage regulation!

The shunt regulator

This two-port circuit is known as the shunt regulator.



A summary

Summarizing, we find that if:

$$V_S > V_{ZK} + R_S I_L$$

then:

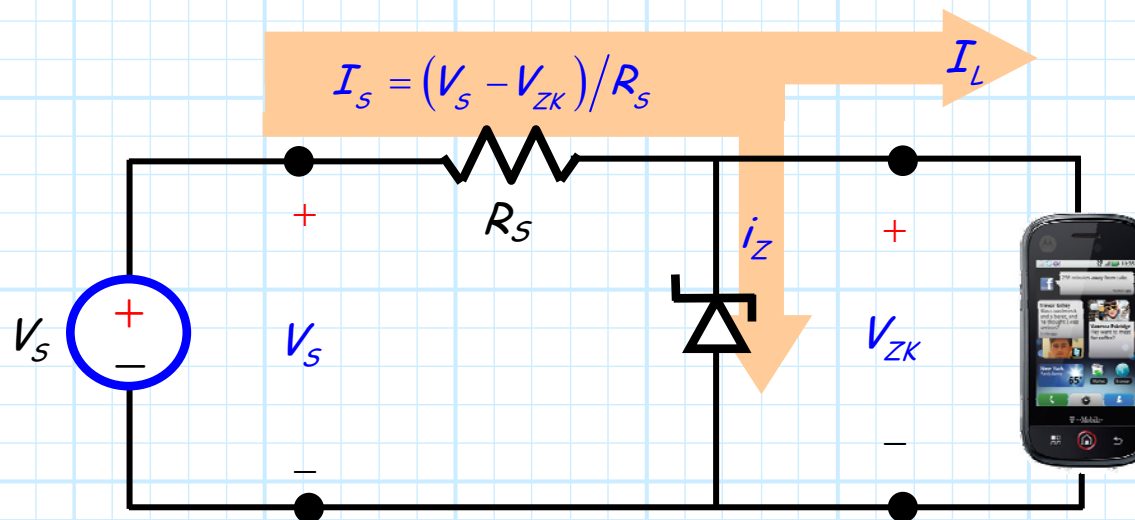
1. The Zener diode will be operating in the **breakdown** region (i.e., $v_Z = V_{ZK}$ and $i_Z > 0$).
2. The **load voltage** is therefore equal to the Zener breakdown voltage (i.e., $V_L = v_Z = V_{ZK}$).
4. The **source current** I_S is $I_S = (V_S - V_{ZK}) / R_S$.
5. The the Zener diode current is less than the source current (i.e., $0 < i_Z < I_S$).

Source current must be larger than the load current

In a shunt regulator, the **source current** $I_S = (V_S - V_{ZK})/R_S$ must be **larger** than the **load current** I_L .

From KCL, we see that the **extra** source current—the current not “used” by the load—must pass through the **Zener diode**.

This causes the Zener to operate in the **breakdown** region.



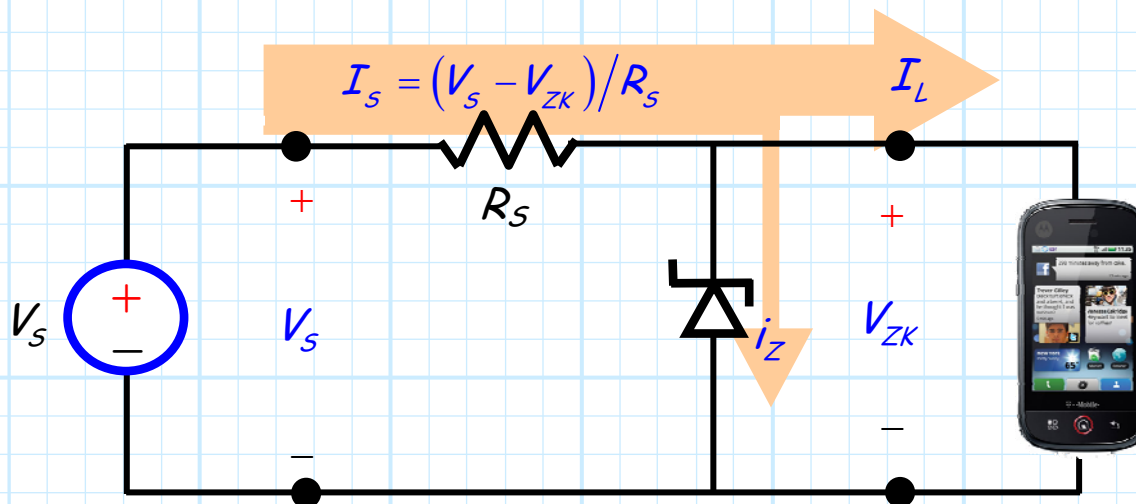
The Zener takes the extra current...

Now, say the **load changes**, such that it draws **more load current** I_L (e.g., the radio transmitter turns on).

Note though, that the source current I_S does not change—if it did, we would see a different load voltage!

Instead, some of the “extra” current from the Zener diode now goes to **load**—the load current increases, but the **source** current remains **the same ol' value**

$$I_S = (V_S - V_{ZK}) / R_S.$$



...but the Zener voltage remains unchanged!

Q: *Hey wait!*

If there is less current flowing through the Zener diode, won't the voltage $v_Z = V_L$ drop as well?

A: Not really!

That's the great thing about the Zener in breakdown—the voltage V_{ZK} across the device is **practically independent** of the current through it.

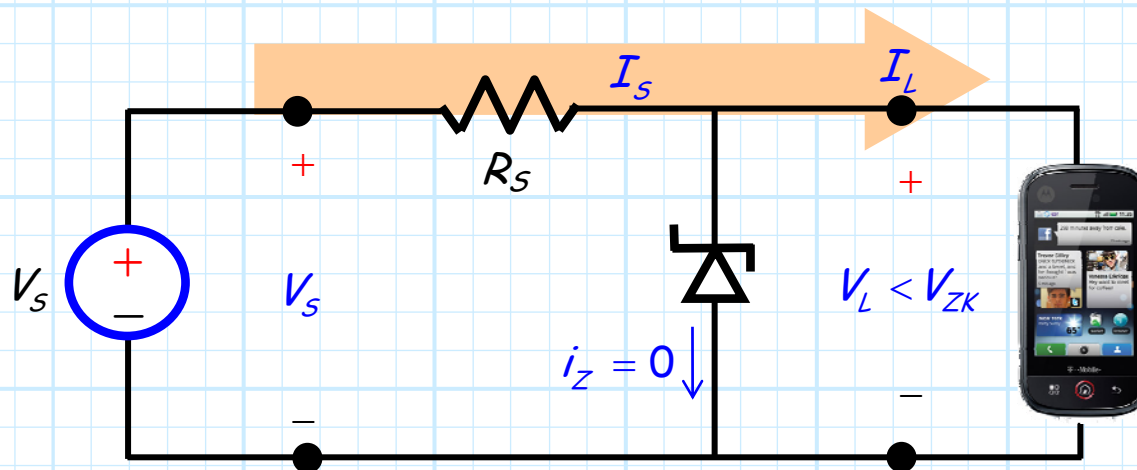
→ This is why the **load regulation** is (practically) **zero!**



The load current can only go so high

Of course, this is true **only** if the Zener diode is operating in the **breakdown** region.

Note that as load current I_L **increases** to a value **equal** to the source current, the **Zener current** will approach **zero**:

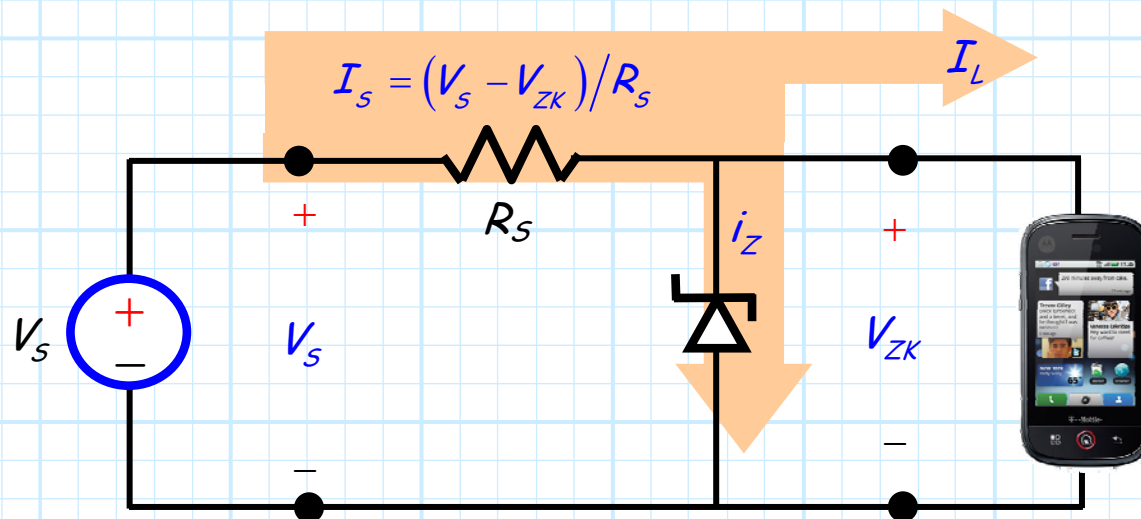


Thus, the Zener will **no longer** be in breakdown (reverse bias instead!), and so the **load voltage** will no longer be equal to V_{ZK} ! I.E.:

$$\text{If } I_L \geq \frac{V_S - V_{ZK}}{R_S} \text{ then } V_L \leq V_{ZK}$$

It also provides line regulation!

Likewise, if the source voltage increases, then the source current will increase as well.

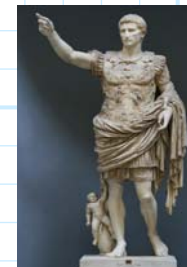


But, the load current does not increase, as this "extra" source current simply results in greater Zener diode current.

Remember, greater Zener diode current will not increase Zener diode voltage \rightarrow

$$V_Z = V_{ZK} = V_L !$$

\rightarrow This is why the line regulation is (practically) zero!



Example: The Shunt Regulator



Your boss rushes in and excitedly asks/demands that you design a **voltage regulator** for a new **gizmo** the company is about to manufacture.

The gizmo requires a voltage of precisely **6.0 Volts**, and at a **maximum** will require power of **1.2 Watts**.

The gizmo will require a **standard battery(s)** as a source (the kind you buy at **Quick Trip**), with as high a voltage as possible.



However, **at least 60%** of this battery power must be delivered to the gizmo.

The regulator must likewise be **simple and cheap**.

→ You decide to design a **shunt regulator** to **meet these criteria!**

This of course means that you must select the **Zener diode**, the **series resistor**, and the **source** (i.e., **battery**) voltage.

The Zener diode is pretty simple, its **breakdown voltage** must be equal to the widget voltage of **6.0 volts**:

$$V_{ZK} = 6.0 V$$

Likewise, the **efficiency** of this regulator must be greater than 60%, therefore:

$$\eta = \frac{V_{ZK}}{V_S} > 0.6 \quad \Rightarrow \quad V_S < \frac{V_{ZK}}{0.6}$$

Since the **battery voltage** should also be as **high as possible**, you decide to make it the largest value that **still satisfies the efficiency** requirement:

$$V_S = \frac{V_{ZK}}{\eta} = \frac{6.0}{0.6} = 10.0 V$$

Now, the **maximum power** that the gizmo will draw is **1.2 Watts**, which corresponds to a **maximum current** of:

$$I_L^{\max} = \frac{P_L^{\max}}{V_{ZK}} = \frac{1.2}{6.0} = 200 \text{ mA}$$

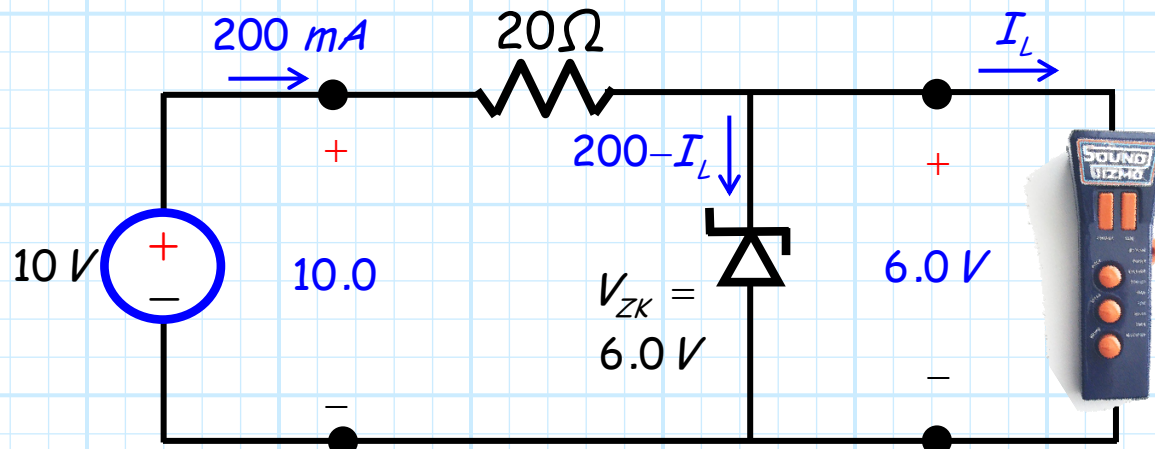
The **source current** should be made **equal** to this maximum **load current** value:

$$I_S = \frac{V_S - V_{ZK}}{R_S} = I_L^{\max}$$

so that the **series resistance** should be:

$$R_S = \frac{V_S - V_{ZK}}{I_L^{\max}} = \frac{10 - 6}{200} = 0.02 \text{ K} = 20 \Omega$$

Thus, your **design is complete!**



You **eagerly** present this design to your **boss**. Your heart thumps as you anticipate both **praise and reward**. Will you get a raise? a bonus? a promotion? **stock options?**



Instead, your boss looks at you with **derision and disgust**.

Your palms begin to **sweat** as you consider what might have **gone wrong**. You checked all the math; **KCL** and **KVL** are verified.

Most of all:

You are sure that you used the "right equations" !

Finally, your boss breaks the **awkward silence** with this question:

"Where are *we*—or our customers for that matter—supposed to get a **10 volt battery**?"

Yikes! Batteries—at least the kind you can buy at **Quick Trip**—are typically **1.5 Volts**. The standard AAA, AA, B, C, and D-cell batteries are all **1.5 volts**.



Of course we can create a **higher voltage** by "**stacking**" them in **series**, but the result would be an **integer multiple** of 1.5 V.

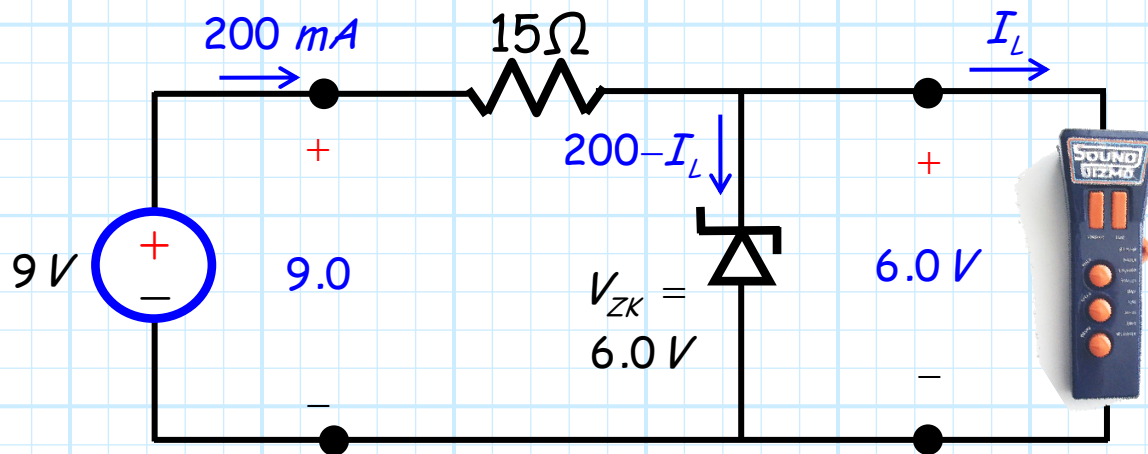
Of course **10 Volts** (*i.e.*, your embarrassing solution) is **not** an integer multiple of 1.5 Volts!

The closest multiples to 10 Volts are **10.5 Volts** and **9.0 Volts**.

The problem with the 10.5 Volt solution is that the regulator efficiency would be **less than 60%**. Thus, the **9.0 Volt** solution appears to be the best—**6 batteries connected in series**.



Therefore, modifying your design for this 9.0 Volt source:



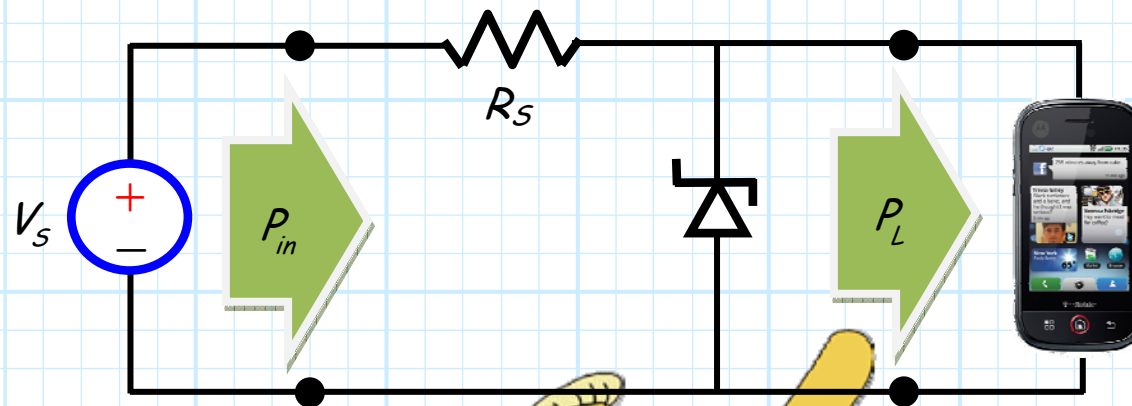
Your job is **safe** (at least for **one more day!**).

Be **aware**: circuit design is **not** a academic exercise; you must provide a design that is **producible** and **maintainable**—you must create a design with components and parts that **actually exist!**

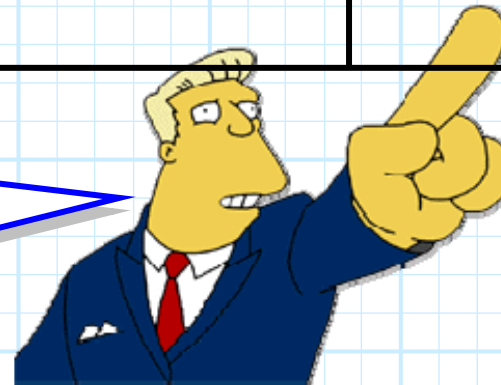
Regulator Power and Efficiency

Consider now the shunt regulator in terms of **power**.

The **source** V_s delivers energy at a rate P_{in} (J/sec) to the regulator, and then the regulator in turn delivers energy at a rate P_L (J/sec) to the **load**.



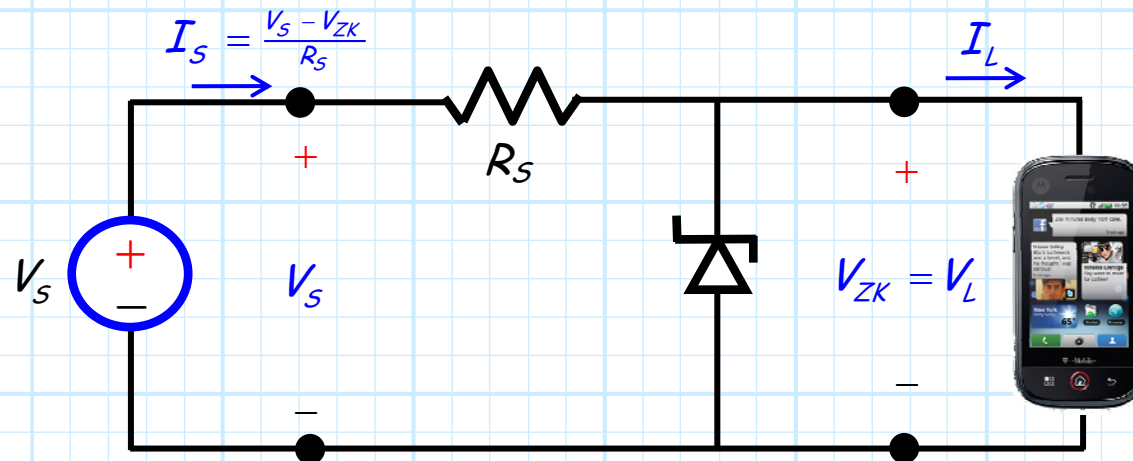
Q: So, is the power delivered by the source is **equal** to the power absorbed the load ?



Power goes to the resistor and diode also

A: Not hardly!

The power delivered by the **source** is distributed to **three** devices—the **load**, the **Zener diode**, and the **series** resistor R_S .



We can determine the rate at which **power** is delivered and absorbed, in terms of the **device parameters** of this regulator circuit—we have **four** devices, we have **four device parameters**.

There are four circuit parameters

Specifically, those devices/parameters are:

1. **Source** voltage V_S
2. **Series resistance** R_S
3. **Zener** breakdown voltage V_{ZK}
4. **Load** current I_L

First we determine the rate at which energy is **absorbed** by the **load**:

$$P_L = V_L I_L = V_{ZK} I_L$$

Note, as load **current** I_L decreases, the load **power** likewise **decreases**.

As I_L approaches **zero** (the load is an open circuit), the load power also becomes **zero**.

The source delivers energy— whether the load uses it or not

Now, energy is **delivered** by the **source** at a rate:

$$P_{in} = V_S I_S = V_S \left(\frac{V_S - V_{ZK}}{R_S} \right)$$



Q: *Wait! It appears that the input power is **independent** of the load current I_L !*

Doesn't that mean that P_{in} is independent of P_L ?

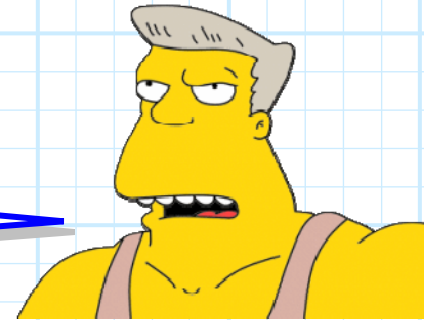
A: That's correct!

The energy flowing **into** the shunt regulator is **independent** of the rate at which energy is being delivered to the load.

Some goes to resistor, some to the diode

In fact, **even** if the load is drawing no current (i.e., $P_L=0$), the input power is **still** the same value shown above.

Q: *But where does this input power go, if not delivered to the load?*



A: The Zener diode also absorbs energy, at a rate:

$$\begin{aligned}
 P_Z &= v_Z i_Z \\
 &= V_{ZK} (I_S - I_L) \\
 &= V_{ZK} I_S - V_{ZK} I_L \\
 &= V_{ZK} \left(\frac{V_S - V_{ZK}}{R_S} \right) - V_{ZK} I_L \\
 &= \frac{V_{ZK}}{R_S} (V_S - V_{ZK}) - V_{ZK} I_L
 \end{aligned}$$

And, the **series resistor** absorbs energy at a rate:

$$\begin{aligned}
 P_R &= I_S^2 R_S \\
 &= \left(\frac{V_S - V_{ZK}}{R_S} \right)^2 R_S \\
 &= \frac{(V_S - V_{ZK})^2}{R_S}
 \end{aligned}$$

Energy comes from the source, but then is absorbed by the load, resistor and diode

Remember, the source V_S is an **active** device—it is a **source** of energy.



In contrast, the series resistor, Zener diode, and load are **passive** devices—they can only **absorb** the energy that the source provides.

Energy is conserved...

By conservation of energy, we conclude then that the power **delivered** by source must be **equal** to all **absorbed** power:

$$P_{in} = P_R + P_Z + P_L$$

Now, using the results above, this **absorbed power** can be specified in terms of regulator **circuit parameters**:

$$\begin{aligned} P_R + P_Z + P_L &= \frac{(V_S - V_{ZK})^2}{R_S} + \left(\frac{V_{ZK}}{R_S} (V_S - V_{ZK}) - V_{ZK} I_L \right) + V_{ZK} I_L \\ &= \frac{(V_S - V_{ZK})^2}{R_S} + \frac{V_{ZK}}{R_S} (V_S - V_{ZK}) \\ &= \frac{(V_S - V_{ZK})}{R_S} (V_S - V_{ZK} + V_{ZK}) \\ &= \left(\frac{V_S - V_{ZK}}{R_S} \right) V_S \end{aligned}$$

...and it better be!

But of course, we found earlier that:

$$P_{in} = V_S \left(\frac{V_S - V_{ZK}}{R_S} \right) = P_R + P_Z + P_L$$



And so, we have verified that **conservation of energy is indeed correct** (I can't **begin** to tell you what trouble we'd be in if we had determined **otherwise!**).

Q: *So who cares? Why are you telling us this?*

A: This analysis shows the relative **inefficiency** of the shunt regulator.

Let's say the source is powering your phone

Ideally, all the power **delivered** by the source would be **absorbed** by the load:

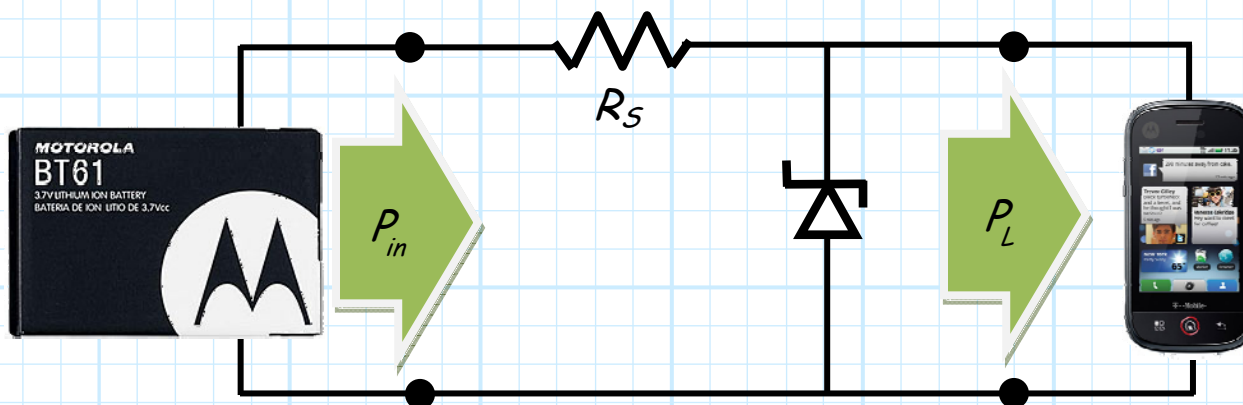
$$P_L = P_{in} \quad \therefore P_{in} - P_L = 0$$

But alas, we find for the **shunt regulator**:

$$P_{in} - P_L = P_R + P_Z \quad \therefore P_L < P_{in}$$

Q: *You've not answered my question—again, who cares?*

A: Let's say the source is in fact the battery to **your** phone—I bet then **you** would be the one who **cares!**

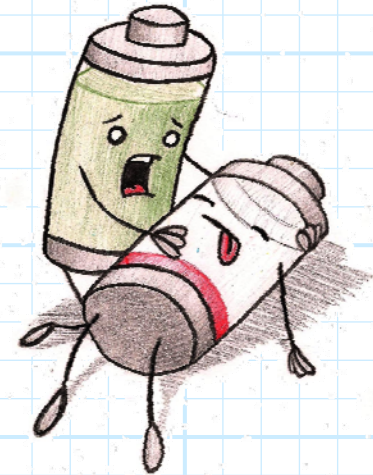


Sarcasm alert!

The energy **not** delivered to the load (your phone) is **wasted**—it simply **heats up** the series **resistor** and the Zener **diode**.

This **wasted** energy causes your **battery** to “run down” jiffy quick, and your phone soon **stops operating!**

GrimStarable, Matt Grimmer



As a result, you might **miss** one of those lucid, erudite, fascinating, and otherwise **life-altering** text/twitter messages that you apparently receive with **astonishing frequency**.

→ And wouldn't **that** be a horrible tragedy!

Got milk? No! We wasted it all!

Thus, voltage regulators need to be **efficient**; the **difference** between P_{in} and P_L should be as **small as possible**.

Note that the ratio P_L/P_{in} provides the **percentage** of the source power that is delivered to the load.

For **example**, if $P_L/P_{in} = 0.6$, then **60%** of the source power is delivered to the load—the other **40%** is **wasted** as heat in the regulator circuit.

For the **shunt regulator**, we find this ratio to be:

$$\frac{P_L}{P_{in}} = \frac{R_S}{V_S} \left(\frac{1}{V_S - V_{ZK}} \right) V_{ZK} I_L = \frac{V_{ZK}}{V_S} \left(\frac{R_S I_L}{V_S - V_{ZK}} \right)$$



Remember, there is a maximum I_L

Q: Huh? According to this equation, if the load current is **really big**, then then 100%—or even more—of the source power is delivered the load!?

$$\frac{P_L}{P_{in}} = \frac{V_{ZK}}{V_S} \left(\frac{R_S I_L}{V_S - V_{ZK}} \right)$$

A: But remember, the load current has a **maximum possible** value:

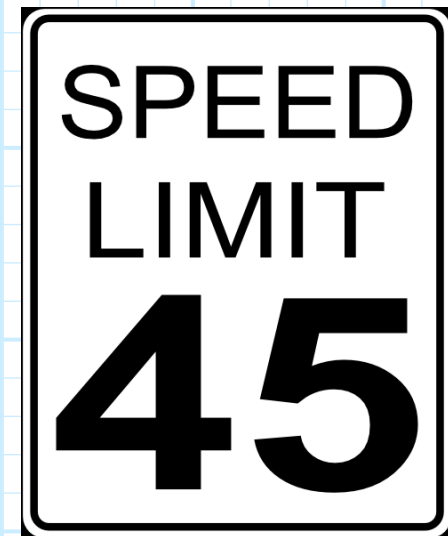
$$I_L < I_S = \frac{V_S - V_{ZK}}{R_S}$$

Thus, we can define a **maximum load current** for a shunt regulator—a **upper limit** on the load current:

$$I_L^{\max} = \frac{V_S - V_{ZK}}{R_S}$$

And thus likewise an **upper limit** on load power:

$$P_L^{\max} = V_{ZK} I_L^{\max}$$



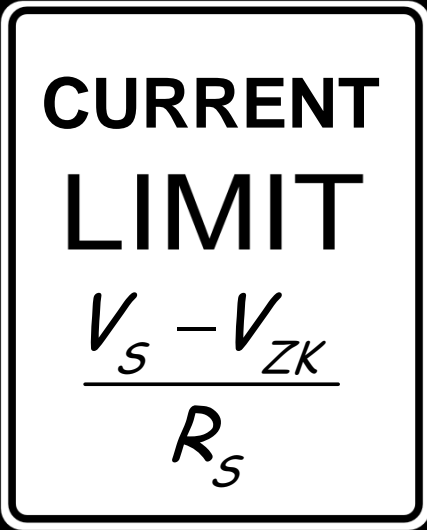
And bad things happen when unregulated

Q: *Why is this a limit?*

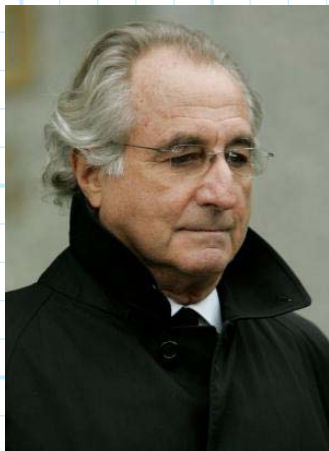
Why can't the load current exceed this values?

A: Remember, if the load draws more current than this maximum value, the Zener diode will **leave** the breakdown region and instead will be **reverse biased!**

Q: ???



CURRENT
LIMIT
$$\frac{V_S - V_{ZK}}{R_S}$$



A: As a result, the voltage $v_z = V_L$ will be some value less than breakdown voltage V_{ZK} —the load voltage will be **completely unregulated!**

Definition: Regulator efficiency

The ratio of this **maximum load power** to the **source power** is a specific **numerical** value know as regulator efficiency η :

$$\eta = \frac{P_L^{\max}}{P_{in}}$$

Obviously(?), regulator efficiency can theoretically be any value between **zero** (the worst) and **one** (the best):

$$0 \leq \eta \leq 1$$

Specifically for the **shunt** regulator, where:

$$I_L^{\max} = \frac{V_S - V_{ZK}}{R_S}$$

$$\begin{aligned} \eta &= \frac{P_L^{\max}}{P_{in}} \\ &= \frac{V_{ZK}}{V_S} \left(\frac{R_S I_L^{\max}}{V_S - V_{ZK}} \right) \\ &= \frac{V_{ZK}}{V_S} \left(\frac{R_S}{V_S - V_{ZK}} \right) \left(\frac{R_S}{V_S - V_{ZK}} \right)^{-1} \\ &= \frac{V_{ZK}}{V_S} \end{aligned}$$

we find that **regulator efficiency** is:

$$= \frac{V_{ZK}}{V_S}$$

Efficiency is a problem if V_s is way bigger than V_L

Recall that $V_s > V_{ZK} > 0$, so that as we would **expect** for efficiency:

$$0 \leq \frac{V_{ZK}}{V_s} \leq 1$$

Thus, is apparent that the **closer** the source voltage is to the load voltage ($V_L = V_{ZK}$), the **higher** the efficiency will be.

But be careful, this likewise will **reduce** the maximum load current:

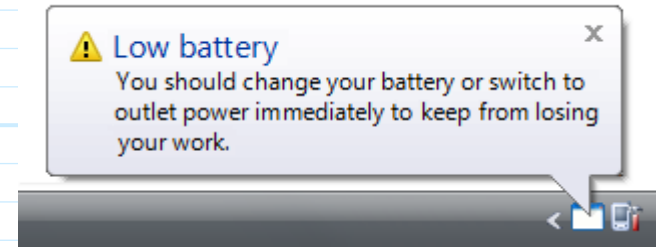
$$I_L^{\max} = \frac{V_s - V_{ZK}}{R_s}$$

Regulators are either linear or switching

For **example**, say the source voltage is $V_S = 10V$, and the load voltage is $V_L = V_{ZK} = 6.0V$.

The efficiency of **this** shunt regulator is:

$$\eta = \frac{V_{ZK}}{V_S} = \frac{6.0}{10.0} = 0.6$$



This shunt regulator is **60% efficient!**

7.



I hate when I'm on a flight and I wake up with a water bottle next to me like oh great now I gotta be responsible for this water bottle

18 Oct via web · Favorite · Retweet · Reply

Q: *Doh! That means **40%** of the source energy is **wasted**; isn't there some way to do **better** than that—I might miss an important **tweet!***

A: Voltage regulators essentially come in **two** types—the **linear** regulator and the **switching** regulator.

→ The **shunt** regulator is an example of a **linear** regulator.

Switching regulators: complex but efficient

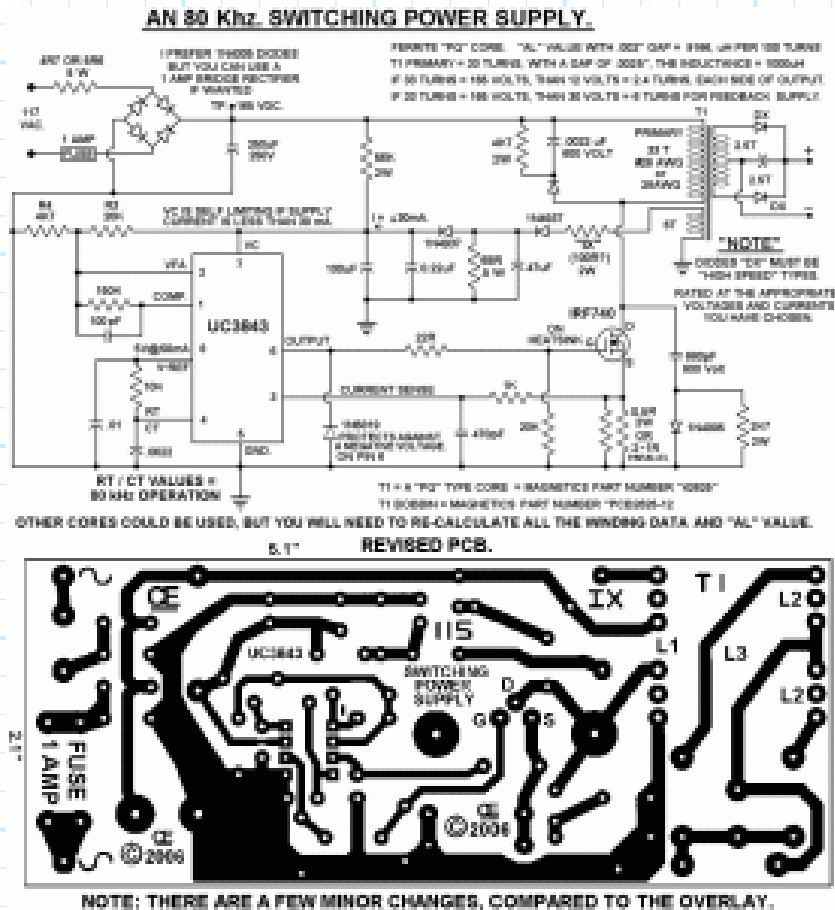
Both the linear and switching regulator exhibit excellent line **and** load regulation.

But, the **linear** regulator is typically much **less efficient** than the **switching** regulator.

Q: *So why don't we just always use the switching regulator?*

A: Switching regulators are typically more **complex** and **costly** than linear regulators, and they likewise generate **Electromagnetic Interference (EMI)**.

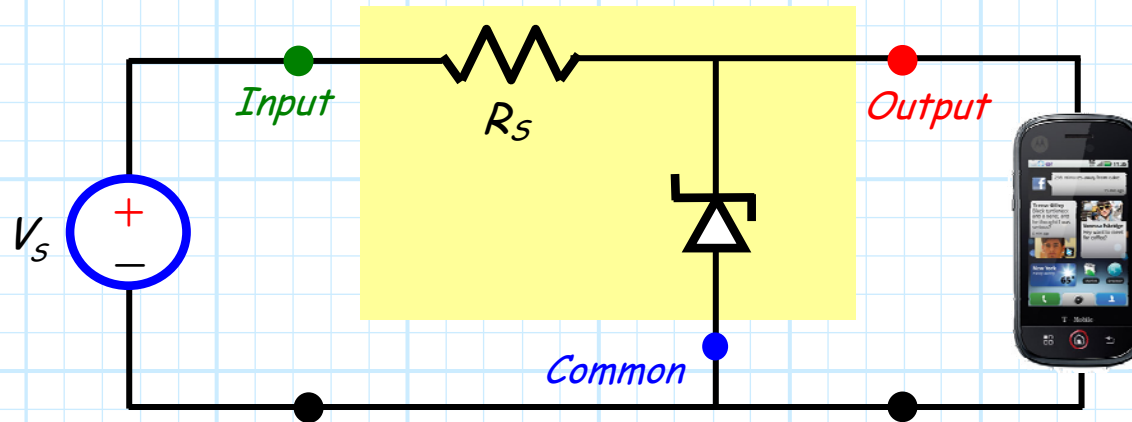
Linear regulators are typically used if an engineer can stand the relative inefficiency—but **often** the engineer **cannot!**



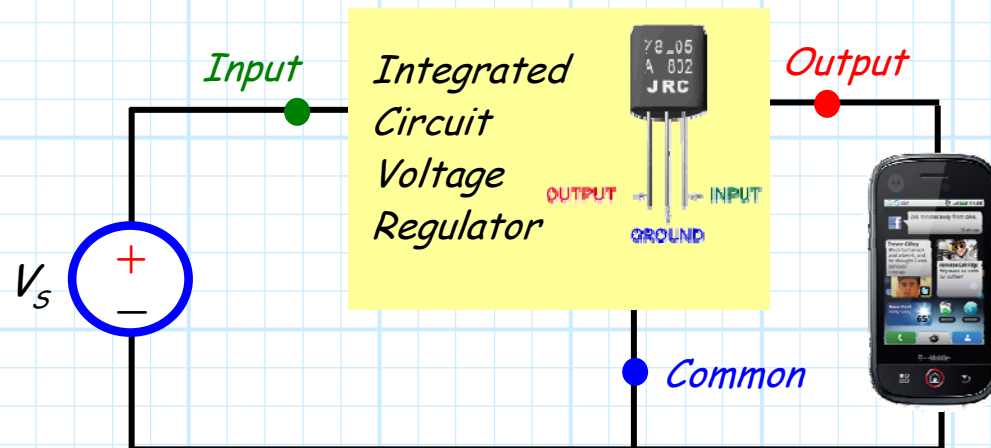
<http://electronic-circuit.net/acdc-switching-power-supply/>

Linear Voltage Regulators

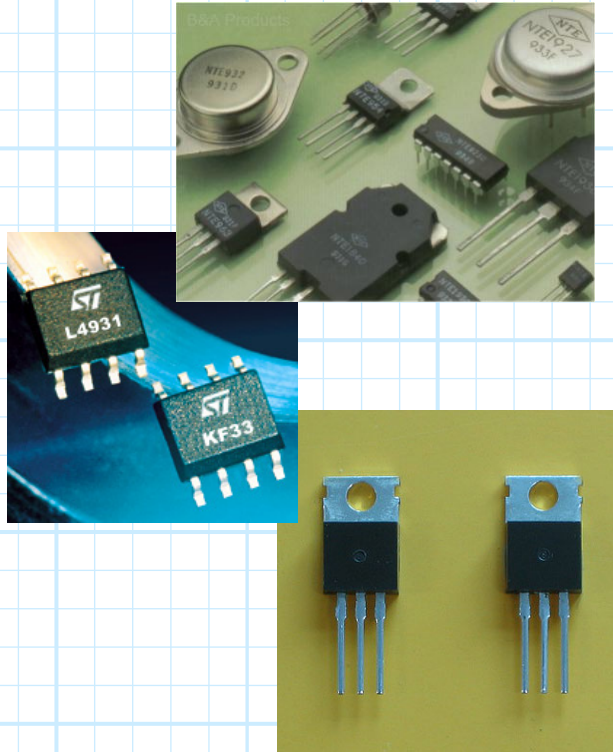
Note that we can view a shunt regulator as a **three-terminal** device, inserted **between** a voltage source and a load:



Integrated circuit technology has resulted in the creation of **other three terminal linear voltage regulator designs**:



Sometimes you're just unlucky



These integrated circuit voltage regulators are **small** and relatively **inexpensive**.

In addition, these IC regulators typically have **better** load regulation, line regulation, and/or efficiency than the zener diode **shunt** regulator!

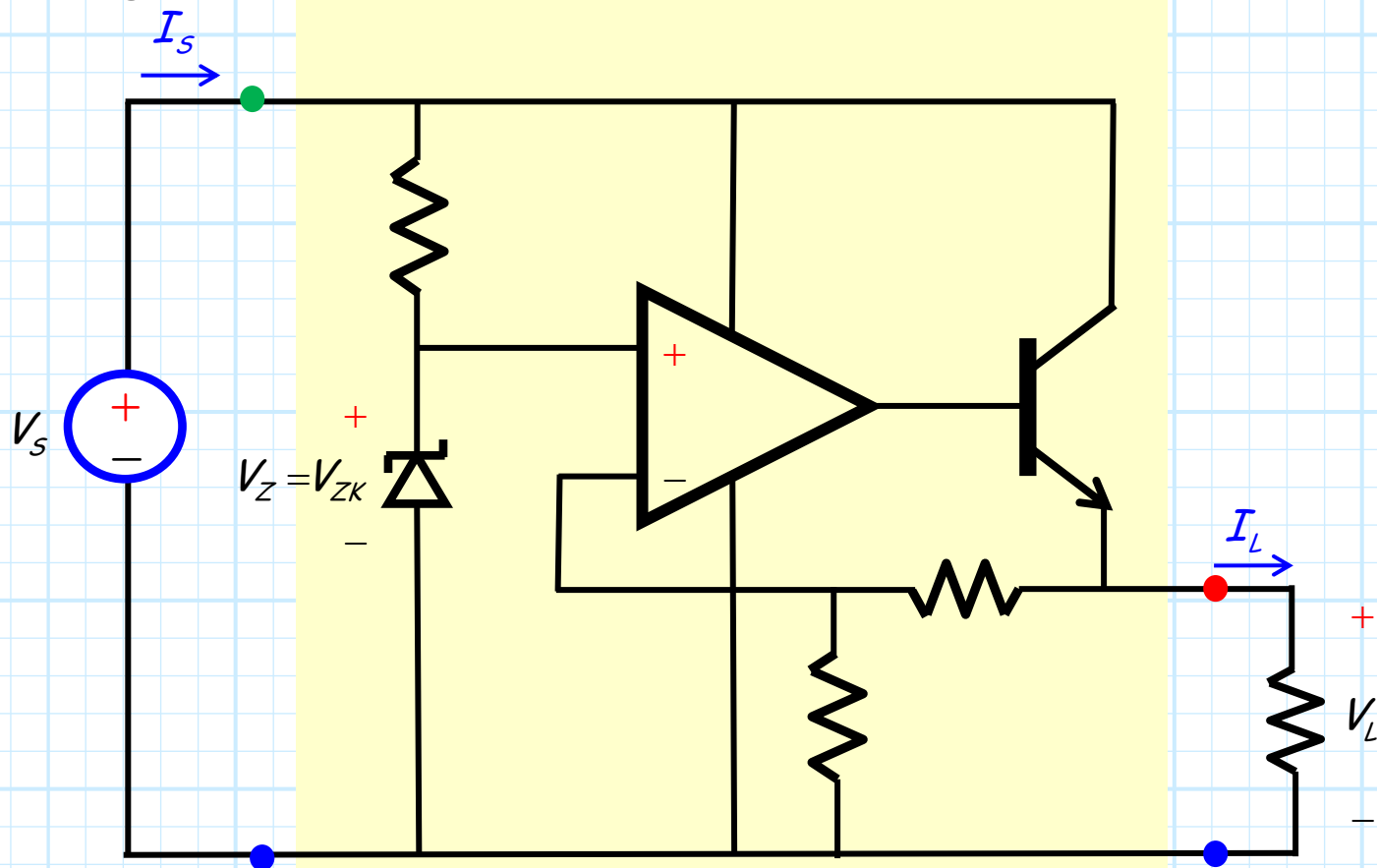


Q: *Wow! The **designers** of these IC regulators obviously had a **much** better electronics professor than the **dope** we got stuck with!*

A: Undoubtedly so!

An improved voltage regulator

However, these integrated circuit design engineers did **not** simply create a **better shunt regulator**.



Instead, they **replaced** the entire shunt regulator design with a **complex circuit** requiring many **transistor** components.

That op-amp requires many transistors

Integrated circuit technology then allows this complex circuit to be manufactured in a *very small space* and at *very small cost!*

The LM341 linear voltage regulator schematic.

