<u>The Insertion</u> <u>Loss Method</u>

Recall that a **lossless** filter can be described in terms of either its power transmission coefficient $T(\omega)$ or its power reflection coefficient $\Gamma(\omega)$, as the two values are completely **dependent**:

$$\mathbf{T}(\omega) = \mathbf{1} - \mathbf{T}(\omega)$$

Ideally, these functions would be quite simple:

1. $T(\omega) = 1$ and $\Gamma(\omega) = 0$ for all frequencies within the passband.

2. $T(\omega) = 0$ and $\Gamma(\omega) = 1$ for all frequencies within the stopband.

For example, the ideal low-pass filter would be:



Add to this a **linear phase** response, and you have the **perfect** microwave filter!

There's just one small problem with this **perfect** filter \rightarrow It's **impossible** to build!

Now, if we consider only possible (i.e., **realizable**) filters, we must limit ourselves to filter functions that can be expressed as **finite polynomials** of the form:

$$\mathbf{T}(\omega) = \frac{a_0 + a_1 \omega + a_2 \omega^2 + \cdots}{b_0 + b_1 \omega + b_2 \omega^2 + \cdots + b_N \omega^{2N}}$$

The order Nof the (denominator) polynomial is likewise the order of the filter.

Instead of the power transmission coefficient, we often use an equivalent function (assuming lossless) called the **power loss ratio** P_{LR} :

$$P_{LR} = \frac{P_{1}^{+}}{P_{2}^{-}} = \frac{1}{1 - \Gamma(\omega)}$$

Note with this definition, $P_{LR} = \infty$ when $\Gamma(\omega) = 1$, and $P_{LR} = 0$ when $\Gamma(\omega) = 0$.

We likewise note that, for a lossless filter:

$$P_{LR} = \frac{1}{1 - \Gamma(\omega)} = \frac{1}{\Gamma(\omega)}$$

Therefore
$$P_{LR}(dB)$$
 is :

$$P_{LR}(dB) = 10 \log_{10} P_{LR} = -10 \log_{10} T(\omega) \doteq \text{Insertion Loss}$$

The power loss ratio in dB is simply the insertion loss of a lossless filter, and thus filter design using the power loss ratio is also called the Insertion Loss Method.

We find that realizable filters will have a power loss ratio of the form:

$$P_{LR}(\omega) = 1 + \frac{\mathcal{M}(\omega^2)}{\mathcal{N}(\omega^2)}$$

where $\mathcal{M}(\omega^2)$ and $\mathcal{N}(\omega^2)$ are polynomials with terms $\omega^2, \omega^4, \omega^6, etc.$

By specifying these polynomials, we specify the frequency behavior of a realizable filter. Our job is to first choose a desirable polynomial!

There are many different **types** of polynomials that result in good filter responses, and each type has its own set of **characteristics**.

The type of **polynomial** likewise describes the type of microwave **filter**. Let's consider **three** of the most popular types:

1. Elliptical

Elliptical filters have three primary characteristics:

a) They exhibit very steep "roll-off", meaning that the transition from pass-band to stop-band is very rapid.
b) They exhibit ripple in the pass-band, meaning that the value of T will vary slightly within the pass-band.

c) They exhibit ripple in the **stop**-band, meaning that the value of **T** will vary slightly within the stop-band.

 $\mathbf{\Lambda T}(\omega)$

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We find that we can make the roll-off **steeper** by accepting more **ripple**.

2. Chebychev

Chebychev filters are also known as **equal-ripple** filters, and have two primary characteristics

a) Steep roll-off (but not as steep as Elliptical).



We likewise find that the roll-off can be made steeper by **accepting** more ripple.

We find that Chebychev **low-pass** filters have a power loss ratio equal to:

$$P_{LR}(\omega) = 1 + k^2 T_N^2 \left(\frac{\omega}{\omega_c}\right)$$

where k specifies the passband **ripple**, $T_N(x)$ is a Chebychev polynomial of **order** N, and ω_c is the low-pass **cutoff frequency**.

3. Butterworth

Also known as **maximally flat** filters, they have two primary characteristics

a) Gradual roll-off.

Jim Stiles



We find that Butterworth **low-pass** filters have a power loss ratio equal to:

$$\mathcal{P}_{LR}(\omega) = 1 + \left(\frac{\omega}{\omega_c}\right)$$

where ω_c is the low-pass cutoff frequency, and N specifies the order of the filter.

Q: So we always chose **elliptical** filters; since they have the steepest roll-off, they are **closest** to ideal—**right**?

A: Ooops! I forgot to talk about the **phase response** $\angle S_{21}(\omega)$ of these filters. Let's examine $\angle S_{21}(\omega)$ for each filter type **before** we pass judgment.

Butterworth $\angle S_{21}(\omega) \rightarrow Close$ to linear phase.

Chebychev $\angle S_{21}(\omega) \rightarrow \text{Not}$ very linear.



Now, for any **type** of filter, we can **improve** roll-off (i.e., increase stop-band attenuation) by **increasing the filter order** N. However, be aware that increasing the filter order likewise has these **deleterious** effects:

- **1**. It makes **phase response** $\angle S_{21}(\omega)$ worse (i.e., more nonlinear).
- 2. It increases filter cost, weight, and size.

3. It increases filter **insertion loss** (this is bad).

4. It makes filter performance more **sensitive** to temperature, aging, etc.

From a **practical** viewpoint, the **order** of a filter should typically be kept to N < 10.

Q: So how do we take these polynomials and make real filters?

A: Similar to matching networks and couplers, we:

1. Form a general circuit structure with **several** degrees of design freedom.

2. Determine the **general form** of the power loss ratio for these circuits.

3. Use our degrees of design freedom to **equate terms** in the general form to the terms of the **desired** power loss ratio polynomial.