

Factory Roaming Robot

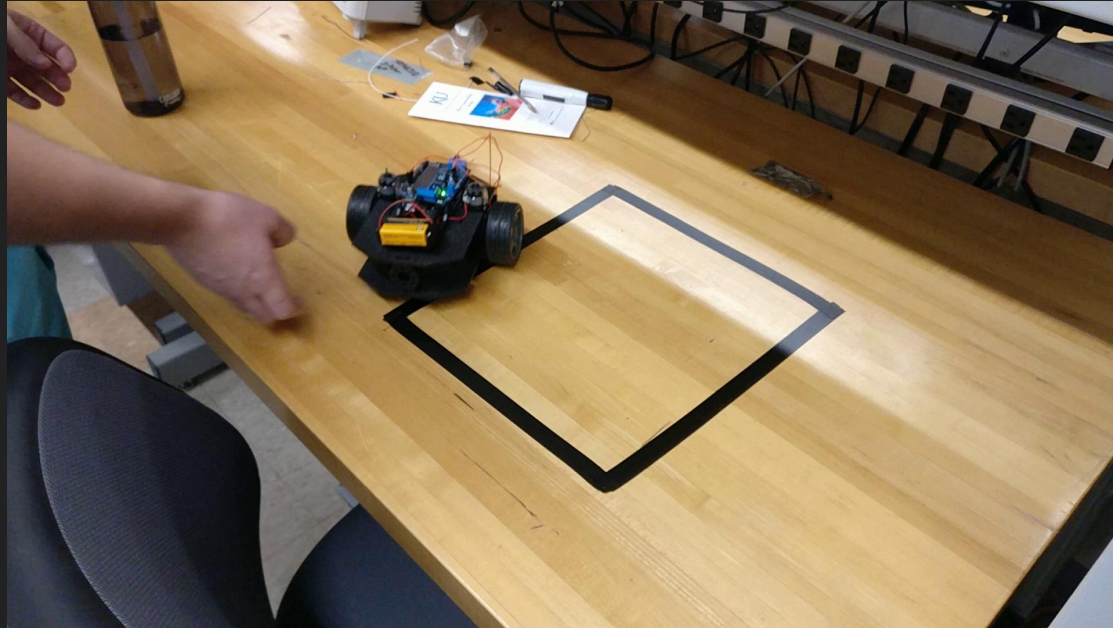
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Overview

- Create a robot that “delivers parts” to a given destination
 - User specifies destination (via web application)
 - Calculates best route to take from start to finish
 - Automatically return to start point
- Runs utilizing these main components
 - Arduino Uno's
 - Raspberry Pi
 - PiCam
 - Motors + encoders

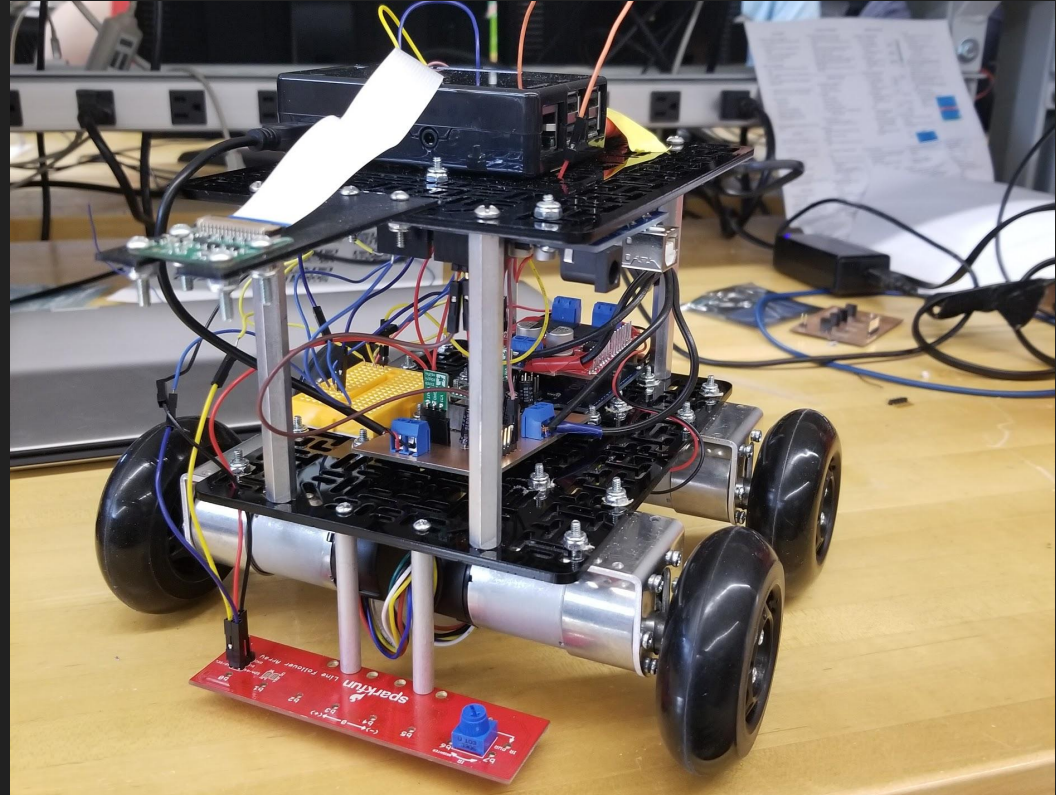
Where we started

- Robot simply followed a line and self corrected when it left the line



Bot Improvements

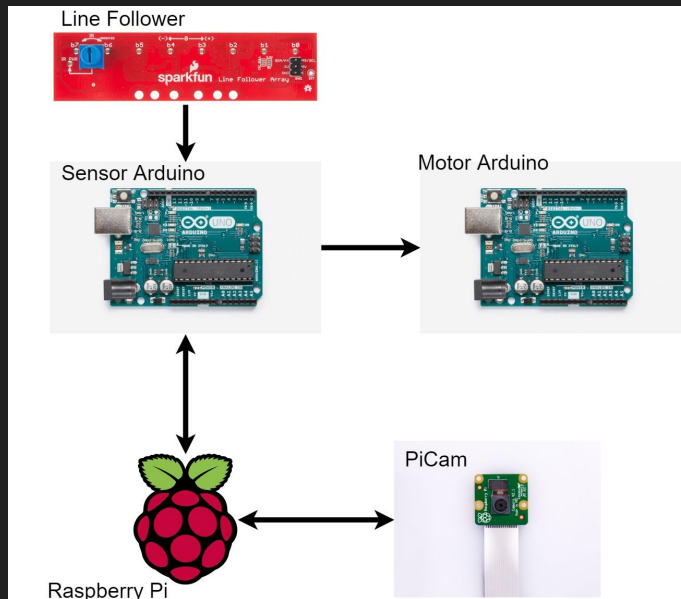
- New Chassis
- New Motors
- New Wheels
- Raspberry Pi + PiCamera
- 2x Custom PCB's
 - Power distribution
 - Motor connections
- Additional Arduino Uno
- Custom Pi Camera Mount
- 12V LiPo Battery



- Simple Script utilizing GPIO callbacks is started with prepopulated route and destination
- Sends start signal to sensor arduino

- Receives signal to begin
 - Utilizes State Machine to send signals to the motors (left, right, etc.)
 - Also maintains positioning on line using line follower
- When a node is detected, interrupt is sent to Pi

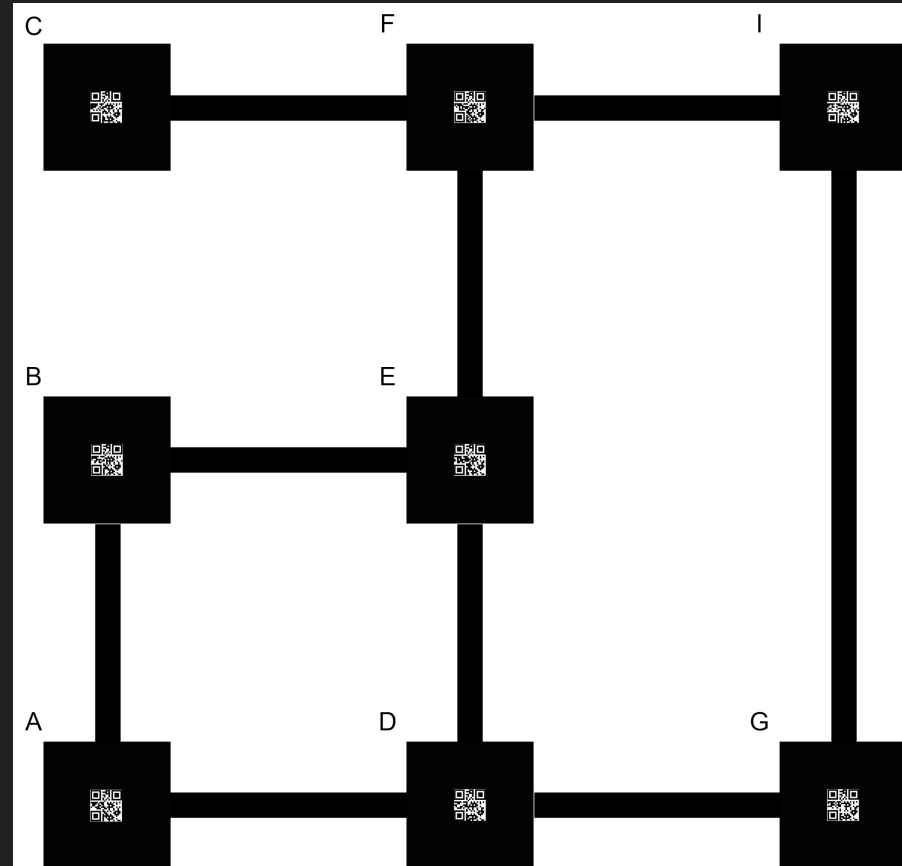
- On interrupt, the PiCam is signalled and takes a picture and decodes the QR code using the zbar library
- Compares the code with the expected node and proceeds to send the next direction



The Map

- Each Junction is wide enough to trigger the line follower
- QR code is centered to ensure accurate camera pickup from each direction
- Robot starts and returns to A

Note: This map is a very small representation of an actual deployment.



Web Features

- Basic sign up and login
- Send confirmation emails to user
- Add/remove users within a company
- Add/edit/remove facilities within a company
- Add layout in a facility

Incompletions

- Ultrasonic Sensor for Collision Detection/Avoidance
 - Setup standalone sensor
 - Code was implemented and works but impractical in our small scale test
- Web to Robot connection
 - Created independent wireless network
 - MQTT Queue base communication
 - Cloud hosted application
- Account management
 - Ability to update added users' information
 - Role-based access control system
 - Add/Edit/Delete Robots from account as well as assign/unassign bots to layouts

HomeLoginSign Up

Login

Email

Password

Login

[Reset Password](#)

Please fill out this field.

LoginSign Up

Signup

Company Name

First Name

Last Name

Email Address

Password

Repeat Password

Sign Up

HomeDashboardLogout

Your account is still not verified. [Resend](#)

Login Successful

Dashboard

Add Facility

Name	Layouts	Admin
Factory	4	

Add Facility

Name

Close

Save Facility

Dashboard

Add Facility

Name	Layouts	Admin
Factory	4	

Layouts for Factory

Add Layout

ID	Name	Node Count	Admin
1	test	0	ADMIN
2	test12	1	ADMIN
3	test3	0	ADMIN
4	test5	1	ADMIN

Layouts for Factory

Add Layout

ID

1

2

3

4

Name

Layout

nodes:

- connections:

- direction: ''

name: ''

name: ''

Close

Create layout

Final Demonstration

