

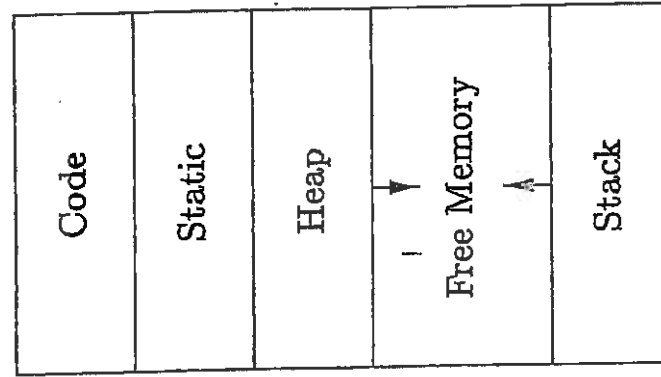


Figure 7.1: Typical subdivision of run-time memory into code and data areas

```

int a[11];
void readArray() { /* Reads 9 integers into a[1], ..., a[9]. */
    int i;
    ...
}
int partition(int m, int n) {
    /* Picks a separator value  $v$ , and partitions  $a[m..n]$  so that
        $a[m..p-1]$  are less than  $v$ ,  $a[p] = v$ , and  $a[p+1..n]$  are
       equal to or greater than  $v$ . Returns  $p$ . */
    ...
}
void quicksort(int m, int n) {
    int i;
    if (n > m) {
        i = partition(m, n);
        quicksort(m, i-1);
        quicksort(i+1, n);
    }
}
main() {
    readArray();
    a[0] = -9999;
    a[10] = 9999;
    quicksort(1,9);
}

```

Figure 7.2: Sketch of a quicksort program

```
enter main()  
  enter readArray()  
  leave readArray()  
  enter quicksort(1,9)  
    enter partition(1,9)  
    leave partition(1,9)  
    enter quicksort(1,3)  
      ...  
    leave quicksort(1,3)  
    enter quicksort(5,9)  
      ...  
    leave quicksort(5,9)  
  leave quicksort(1,9)  
leave main()
```

Figure 7.3: Possible activations for the program of Fig. 7.2

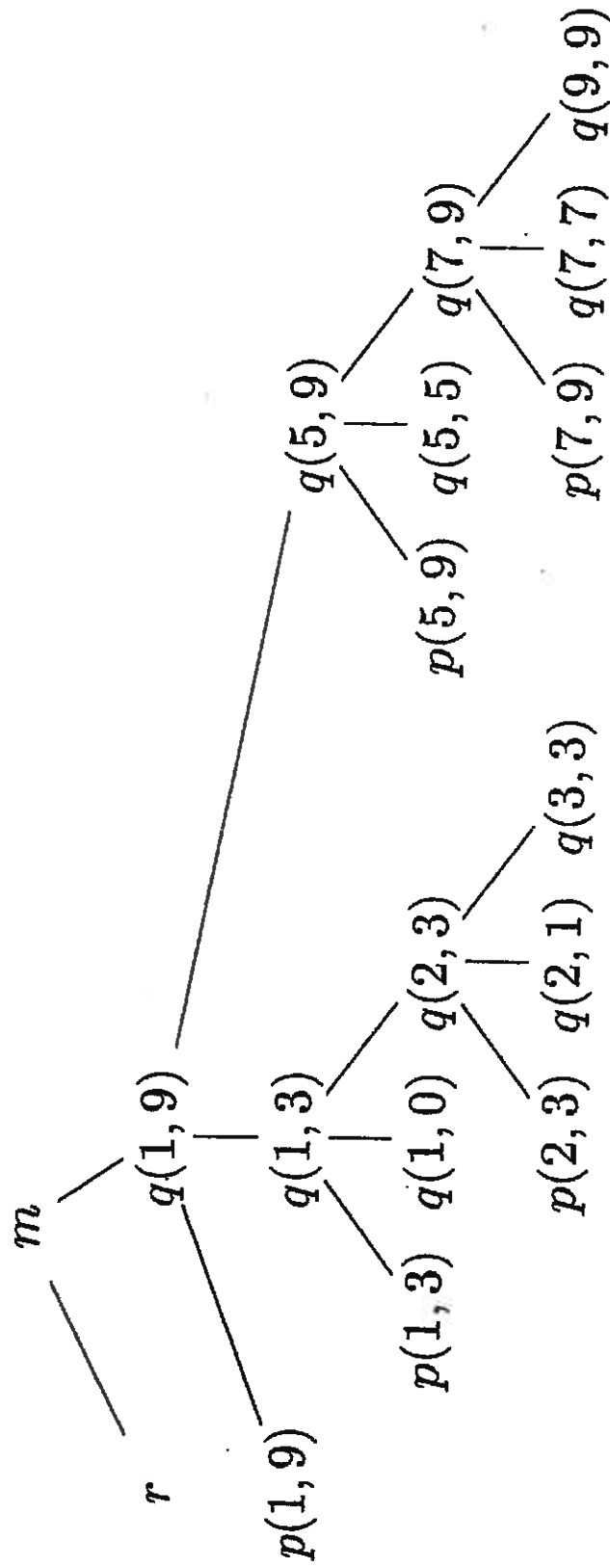


Figure 7.4: Activation tree representing calls during an execution of *quicksort*

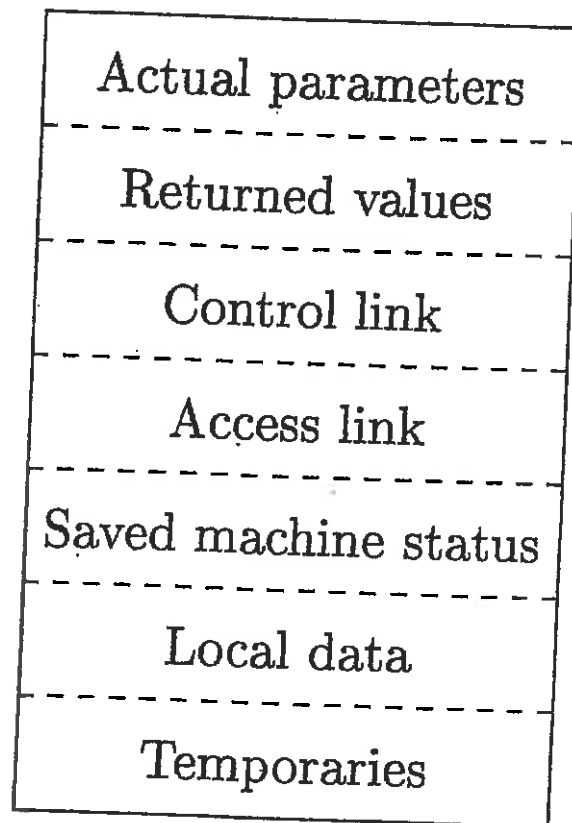
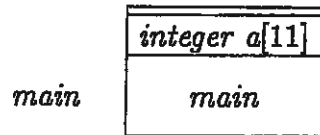
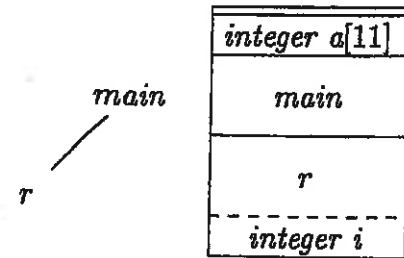


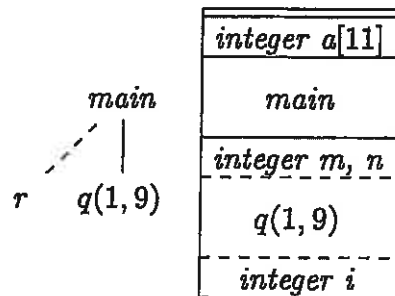
Figure 7.5: A general activation record



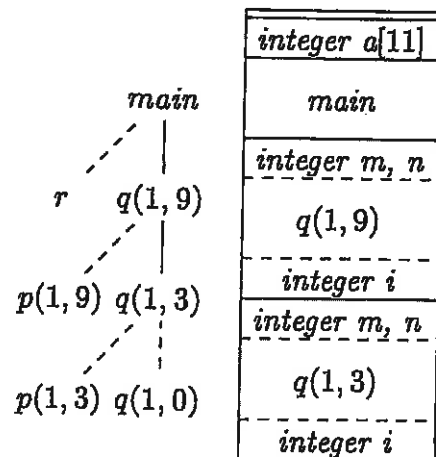
(a) Frame for *main*



(b) *r* is activated



(c) *r* has been popped and *q*(1,9) pushed



(d) Control returns to *q*(1,3)

Figure 7.6: Downward-growing stack of activation records

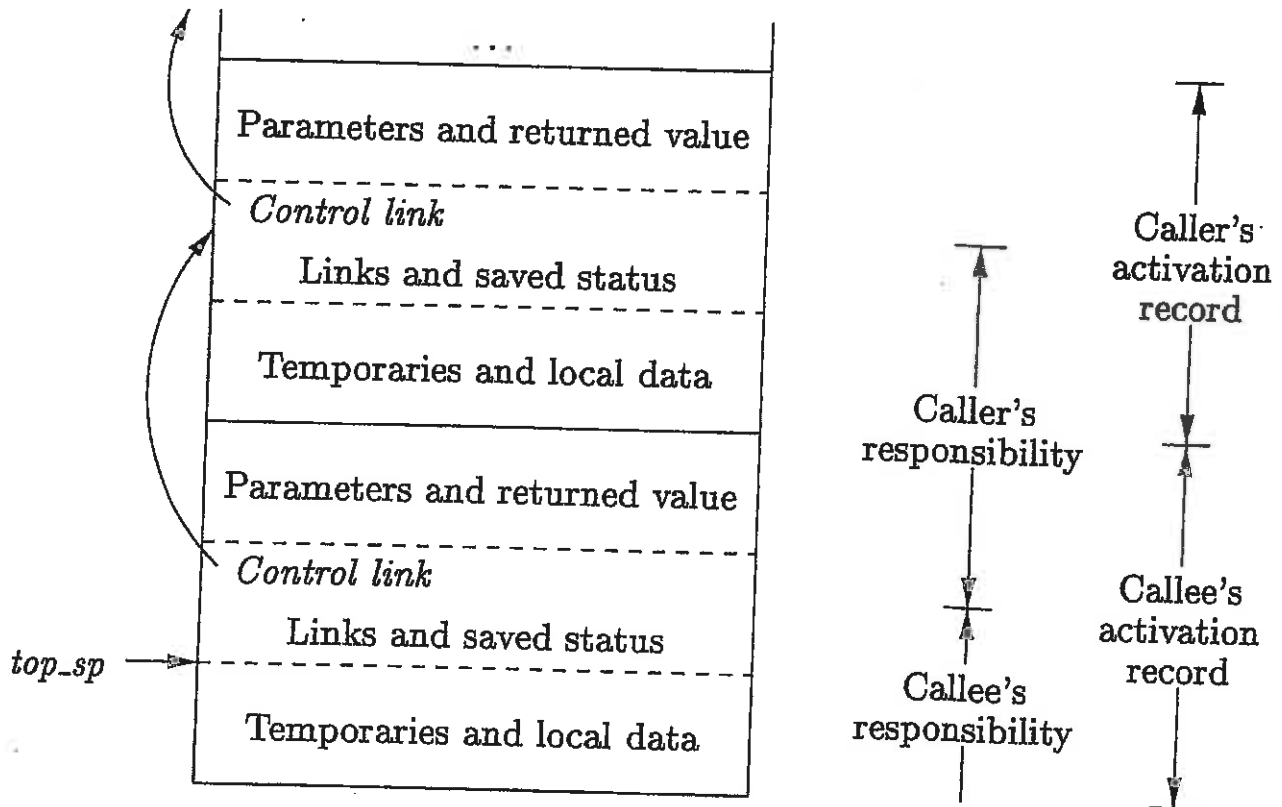


Figure 7.7: Division of tasks between caller and callee

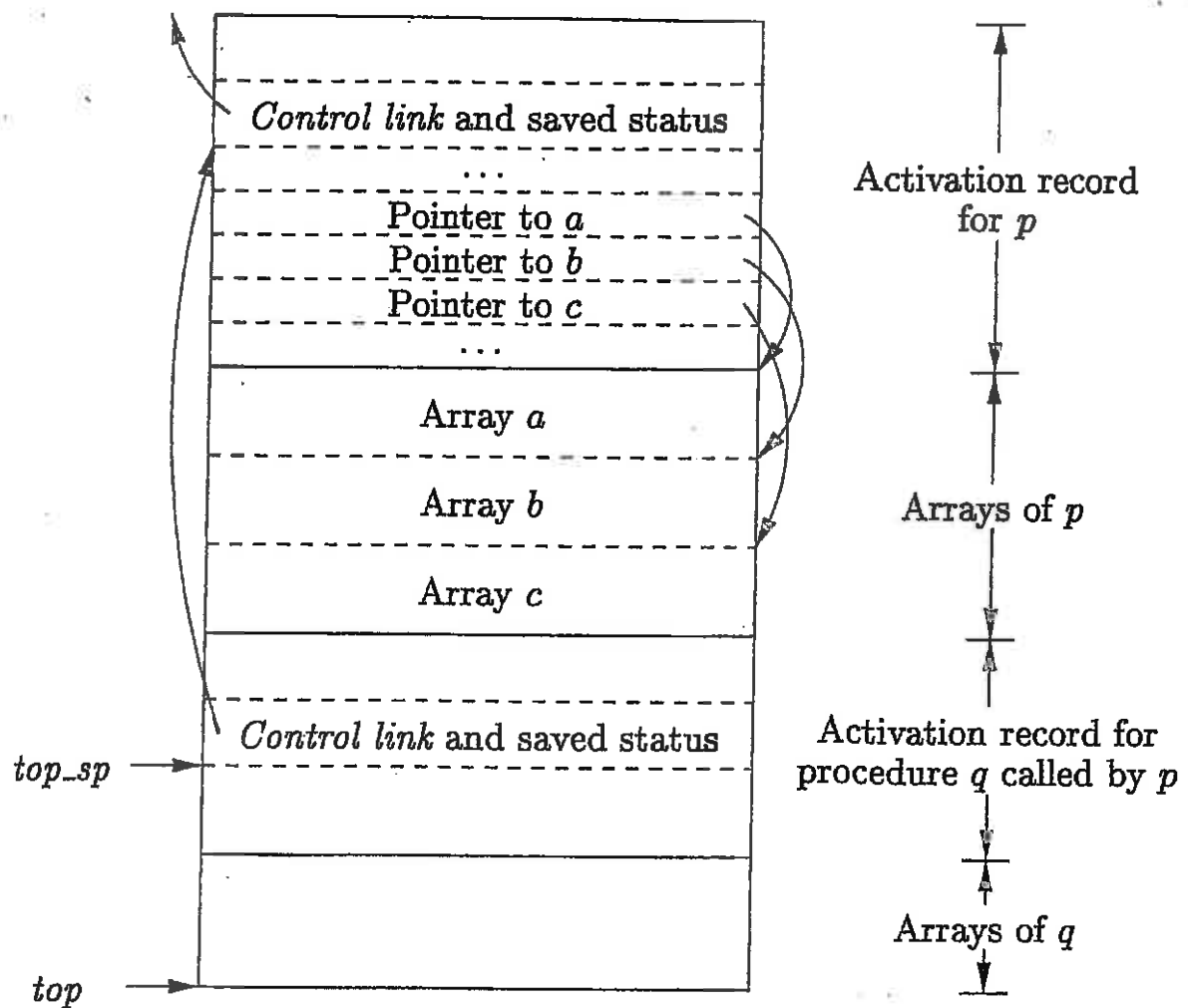


Figure 7.8: Access to dynamically allocated arrays

```

1) fun sort(inputFile, outputFile) =
    let
2)         val a = array(11,0);
3)         fun readArray(inputFile) = ... ;
4)         ... a ... ;
5)         fun exchange(i,j) =
6)             ... a ... ;
7)         fun quicksort(m,n) =
            let
8)             val v = ... ;
9)             fun partition(y,z) =
10)                 ... a ... v ... exchange ...
            in
11)                ... a ... v ... partition ... quicksort
            end
        in
12)        ... a ... readArray ... quicksort ...
        end;

```

Figure 7.10: A version of quicksort, in ML style, using nested functions

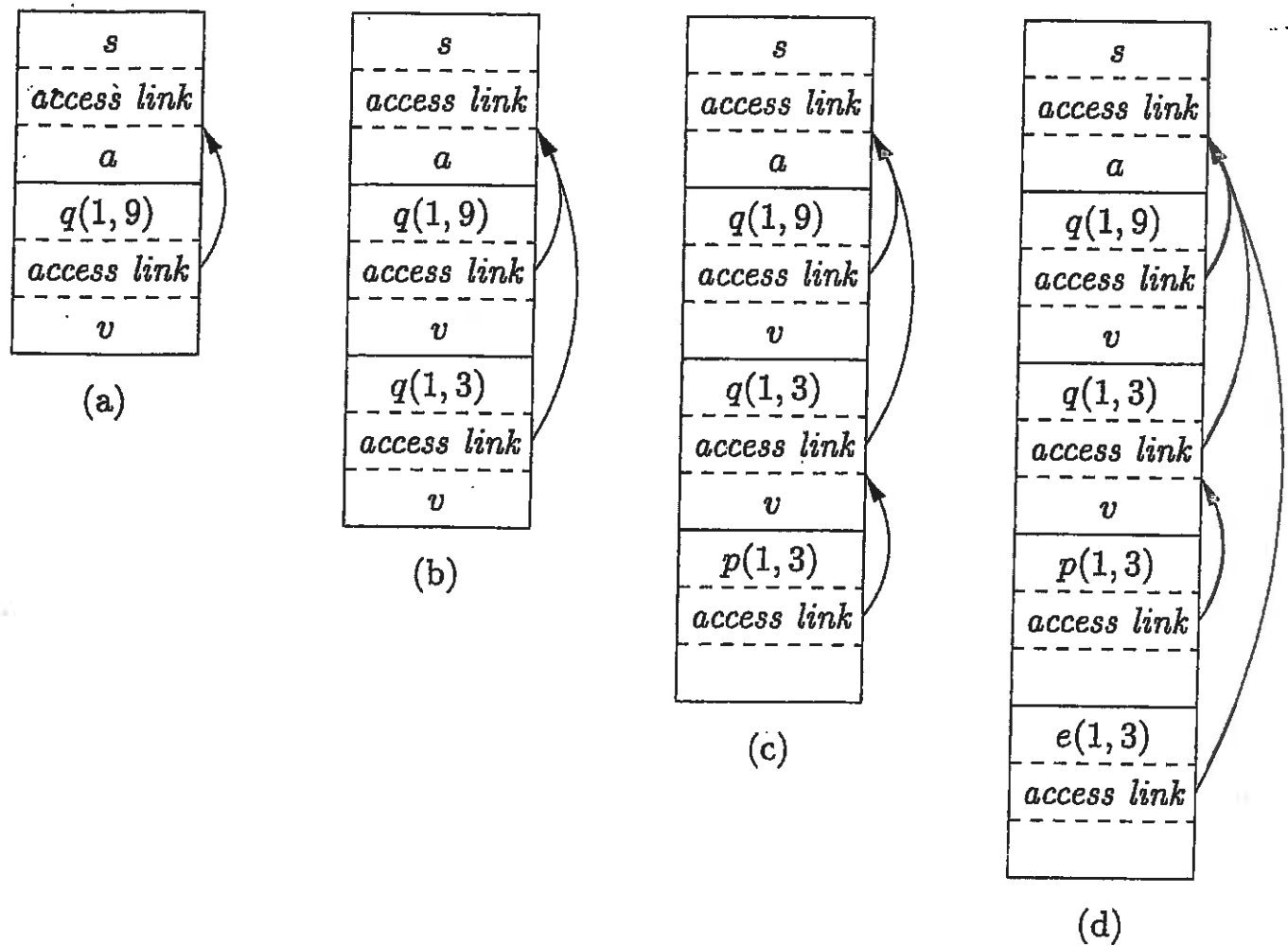


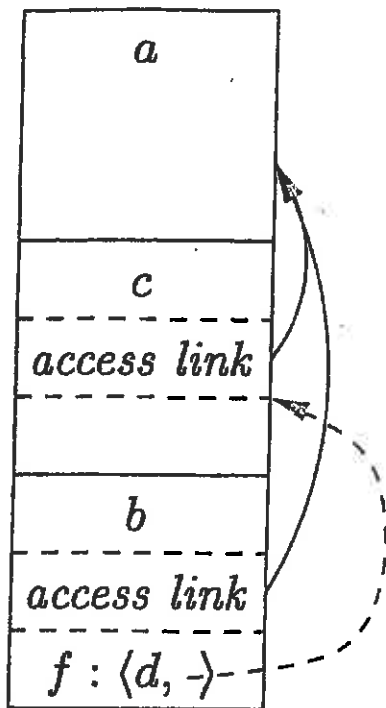
Figure 7.11: Access links for finding nonlocal data

```

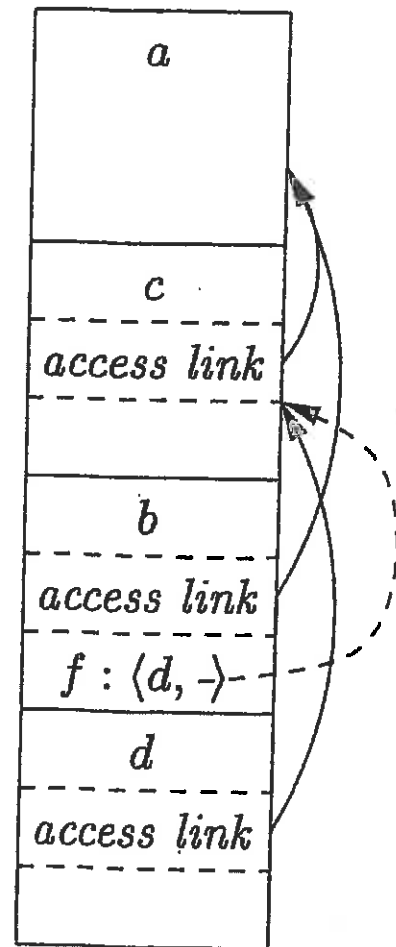
fun a(x) =
  let
    fun b(f) =
      ... f ... ;
    fun c(y) =
      let
        fun d(z) = ...
          in
            ... b(d) ...
          end
        in
          ... c(1) ...
        end;
  end;

```

Figure 7.12: Sketch of ML program that uses function-parameters



(a)



(b)

Figure 7.13: Actual parameters carry their access link with them

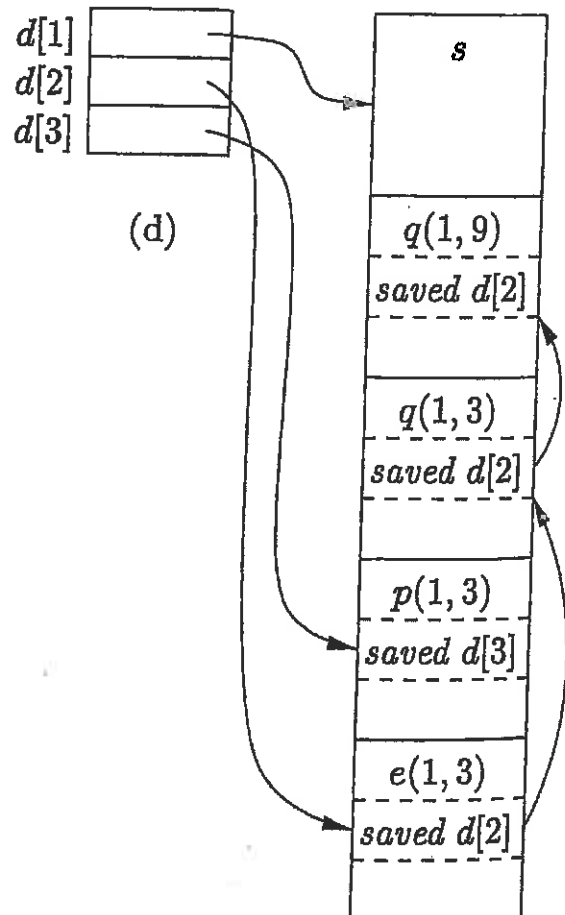
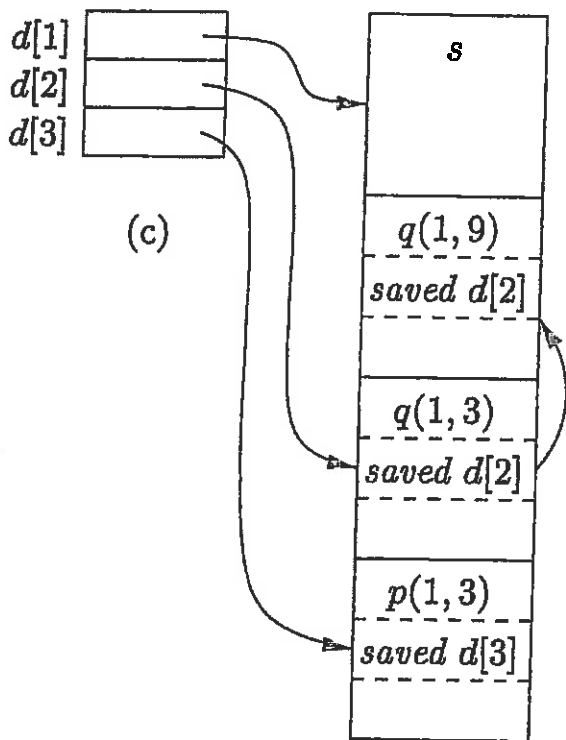
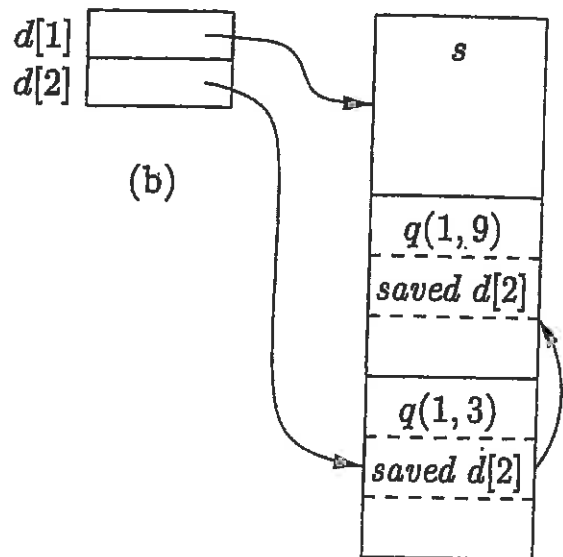
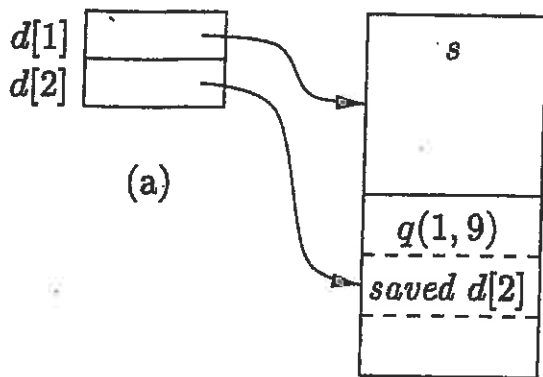


Figure 7.14: Maintaining the display