**Where Next - Solaris**

- **Integrate our work with TAO**

- Continue testing to characterize the RT performance of Solaris

- Complete work on a prototype rate monotonic scheduling class

- Add connection based output queuing in the ATM driver

- Extend this work to support multiprocessor environments

- Evaluate Solaris I/O subsystem enhancements, quantify performance and consider extension.

- Evaluate alternative frameworks and operating systems
Where Next - NetBSD

** Integrate our work with TAO **
Solaris - Remote IPC

Sample Number

Round trip latency between a 300MHz Ultra2 and a 170MHz SPARC5, processes are in the TS scheduling class.

a) no competing network traffic

b) competing traffic processed with interrupt priority

c) competing traffic processed with SYS priority of 61
Solaris - Local IPC

Local IPC Round trip latency for two processes on a 170 MHz SPARC5 with real-time priorities of 125

a) no competing network traffic
b) competing traffic processed with interrupt priority
c) competing traffic processed with RT priority of 100
Status of Solaris Work

Rate Monotonic scheduling class scheduled to be completed by June 1, 1998. This includes admission control.

STREAMS subsystem modifications

- multiple kernel threads for protocol processing - prototype complete.
- demultiplex connections in ATM driver using VCs - prototype complete
- dedicated STREAMS - prototype complete
- periodic protocol processing using the real-time callout queue
- connection based buffering on the send side.
The Solution

**Thread0**
(low-delay)

**Thread1**
(periodic)

**Thread2**
(Best-Effort)

**Thread3**
(Best-Effort)

**UDP/TCP**

**<timers>**

**IP - QoS**

**IP - Best Effort, Default Path**

**TX Queue**

**RX Queue**

**ATM Driver**

**sQ**

**rQ**

Fred Kuhns 5/13/98
The Problem - Network IO

Scheduler
Disp/Sleep Queues
thread1
thread2
thread3
callout
streams
Callable Queues
Standard RT

Protocol Processing in Interrupt Context (HW or SW)

FIFO Queueing
Sources of Non-Deterministic Behavior in Solaris

Priority inversion:

- Protocol processing with Interrupt priorities
- FIFO queuing
- Hidden scheduling
- Resource locks

Lack of Periodic Real-Time CPU scheduling

Lack of QoS specification interface, admission control and enforcement
What About Solaris

Our initial goal was to port much of our work and knowledge from NetBSD to Solaris

Solaris has proven to be much more difficult than expected:

- Complexity - IP alone is 18,000 plus lines of code
- Synchronization objects and system threads complicate scheduling class implementation
- STREAMS implementation has been substantially modified from the SVR4 version
- Existence of a fixed priority Real-Time scheduling class and Real-Time callout queue ameliorate some of the problems encountered in NetBSD.
NetBSD with QoS

Low Delay, Guaranteed Bandwidth and Best Effort

(With CPU Competition)

Delay (msec)

Throughput (Mb/s)

number of PDUs

RTU Period = 1 ms
RTU Period = 5 ms
Best Effort I
Best Effort II
NetBSD Experimental Results

RTU TCP Throughput Performance

Kernel TCP Throughput Performance

Network BSD Experimental Results

TCP Connection 1
TCP Connection 2
TCP Connection 3
Changes to NetBSD

• Real-Time Upcalls (RTU) - Rate Monotonic, delayed preemption scheduling class. See http://www.arl.wustl.edu/arl/projects/ito/ton.ps

• Universal Continuous Media I/O (UCMIO) - zero-copy buffer semantics. See http://www.ccrc.wustl.edu/pub/chuck/stmt.html

• Shared file IO and Network IO buffers - Shared Network and Filesystem buffers. See http://www.arl.wustl.edu/arl/refpapers/milind/mars.html

• QoS specification API and admission control
I/O Subsystem Goals

Design, specification and prototype implementation of a high performance I/O subsystem that can provide Gbps bandwidth, bounded latency and QoS guarantees to applications.

- Support for multiple operating systems: Currently NetBSD and Solaris.
- Periodic and aperiodic data I/O
- Vertically integrated protocol stack
- Specification driven processing of I/O events
- Real-Time OS Scheduling and admission control
The Big Picture

CLIENT

operation()

in args

out args + return value

ORB QoS INTERFACE

REAL-TIME ORB CORE

REAL-TIME OBJECT ADAPTER

REAL-TIME ORB CORE

RIOP

RIDL STUBS

ORB QoS INTERFACE

REAL-TIME OBJECT ADAPTER

OS KERNEL

REAL-TIME I/O SUBSYSTEM

HIGH-SPEED NETWORK ADAPTERS

OS KERNEL

REAL-TIME I/O SUBSYSTEM

HIGH-SPEED NETWORK ADAPTERS

NETWORK
Overview

- Motivation
- I/O Subsystem Goals
- Modifications to NetBSD
- Modifications to Solaris
- Future work
High Performance I/O with QoS

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