

5.6 - Binomial Multi-section Matching Transformer

Reading Assignment: *pp. 246-250*

One way to **maximize bandwidth** is to construct a multisection matching network with a function $\Gamma(f)$ that is **maximally flat**.

Q: *Maximally flat? What kind of function is maximally flat?*

This function maximizes bandwidth by providing a solution that is **maximally flat**.

A: HO: MAXIMALLY FLAT FUNCTIONS

1. We can build a multisection matching network such that the function $\Gamma(f)$ is a **binomial function**.
2. The binomial function is **maximally flat**.

Q: *Meaning?*

A: Meaning the function $\Gamma(f)$ is maximally flat \rightarrow a **wideband solution!**

HO: THE BINOMIAL MULTI-SECTION MATCHING TRANSFORMER

Maximally Flat Functions

Consider some function $f(x)$. Say that we know the value of the function **at** $x=1$ is 5:

$$f(x=1) = 5$$

This of course says **something** about the function $f(x)$, but it **doesn't** tell us much!

We can additionally determine the **first derivative** of this function, and likewise evaluate this derivative **at** $x=1$. Say that this value turns out to be **zero**:

$$\left. \frac{df(x)}{dx} \right|_{x=1} = 0$$

Note that this does not mean that the derivative of $f(x)$ is equal to zero, it merely means that the derivative of $f(x)$ is zero **at the value** $x=1$. Presumably, $df(x)/dx$ is **non-zero** at **other** values of x .

So, we now have **two** pieces of information about the function $f(x)$. We can add to this list by continuing to take higher-order derivatives and evaluating them at the single point $x=1$.

Let's say that the values of **all** the derivatives (at $x=1$) turn out to have a zero value:

$$\left. \frac{d f^n(x)}{d x^n} \right|_{x=1} = 0 \text{ for } n = 1, 2, 3, \dots, \infty$$

We say that this function is **completely flat** at the point $x=1$. Because **all** the derivatives are zero at $x=1$, it means that the function cannot change in value from that at $x=1$.

In other words, if the function has a value of 5 at $x=1$, (i.e., $f(x=1) = 5$), then the function **must** have a value of 5 at **all** x !

The function $f(x)$ thus must be the **constant** function:

$$f(x) = 5$$

Now let's consider the following **problem**—say some function $f(x)$ has the following form:

$$f(x) = a x^3 + b x^2 + c x$$

We wish to **determine** the values a , b , and c so that:

$$f(x=1) = 5$$

and that the value of the function $f(x)$ is as **close** to a value of 5 as possible in the region where $x = 1$.

In other words, we want the function to have the value of 5 at $x=1$, and to **change** from that value as **slowly** as possible as we

"move" from $x=1$.

Q: *Don't we simply want the **completely flat** function $f(x) = 5$?*

A: That would be the **ideal** function for this case, but notice that solution is **not** an option. Note there are **no** values of a , b , and c that will make:

$$ax^3 + bx^2 + cx = 5$$

for **all** values x .

Q: *So **what** do we do?*

A: **Instead** of the completely flat solution, we can find the **maximally flat** solution!

The **maximally flat** solution comes from determining the values a , b , and c so that as many derivatives as **possible** are **zero** at the point $x=1$.

For example, we wish to make the **first derivate** equal to zero at $x=1$:

$$\begin{aligned} 0 &= \left. \frac{df(x)}{dx} \right|_{x=1} \\ &= \left. (3ax^2 + 2bx + c) \right|_{x=1} \\ &= 3a + 2b + c \end{aligned}$$

Likewise, we wish to make the **second derivative** equal to zero at $x=1$:

$$\begin{aligned} 0 &= \left. \frac{d^2 f(x)}{d x^2} \right|_{x=1} \\ &= (6ax + 2b) \Big|_{x=1} \\ &= 6a + 2b \end{aligned}$$

Here we must **stop** taking derivatives, as our solution only has **three degrees of design freedom** (i.e., 3 unknowns a, b, c).

Q: *But we only have taken **two** derivatives, can't we take **one** more?*

A: **No!** We already have a **third** "design" equation: the value of the function **must** be 5 at $x=1$:

$$\begin{aligned} 5 &= f(x=1) \\ &= a(1)^3 + b(1)^2 + c(1) \\ &= a + b + c \end{aligned}$$

So, we have used the **maximally flat** criterion at $x=1$ to generate **three** equations and **three** unknowns:

$$5 = a + b + c$$

$$0 = 3a + 2b + c$$

$$0 = 6a + 2b$$

Solving, we find:

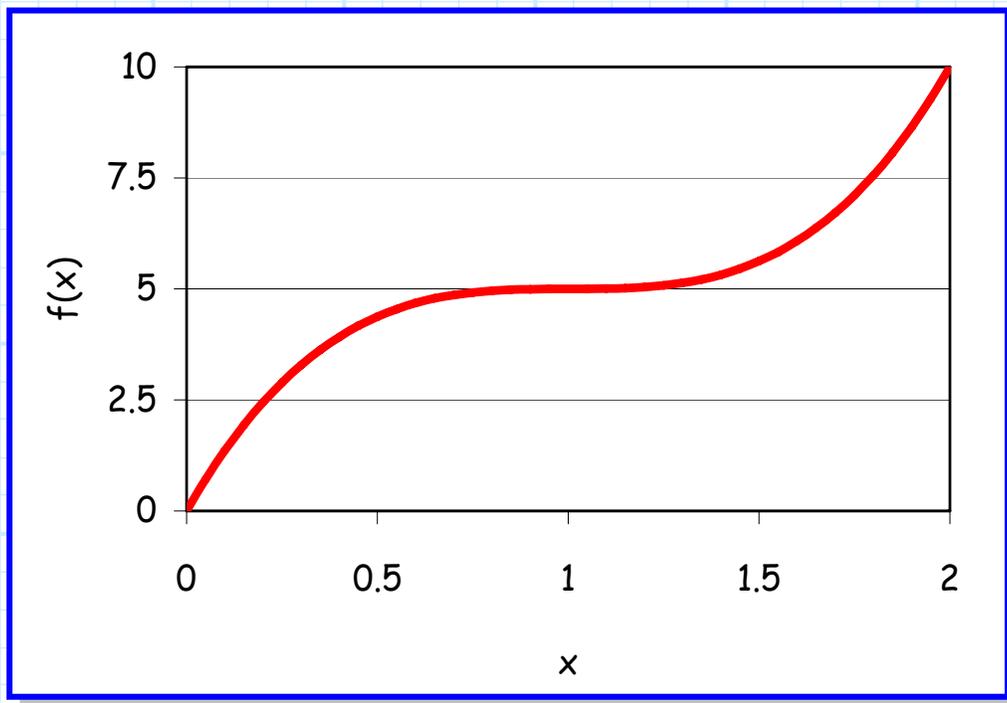
$$a = 5$$

$$b = -15$$

$$c = 15$$

Therefore, the maximally flat function (at $x=1$) is:

$$f(x) = 5x^3 - 15x^2 + 15x$$



The Binomial Multi-Section Transformer

Recall that a **multi-section matching network** can be described using the theory of small reflections as:

$$\begin{aligned}\Gamma_{in}(\omega) &= \Gamma_0 + \Gamma_1 e^{-j2\omega T} + \Gamma_2 e^{-j4\omega T} + \dots + \Gamma_N e^{-j2N\omega T} \\ &= \sum_{n=0}^N \Gamma_n e^{-j2n\omega T}\end{aligned}$$

where:

$$T \doteq \frac{\ell}{v_p} = \text{propagation time through 1 section}$$

Note that for a multi-section transformer, we have N **degrees of design freedom**, corresponding to the N characteristic impedance values Z_n .

Q: *What should the values of Γ_n (i.e., Z_n) be?*

A: We need to define N independent **design equations**, which we can then use to solve for the N values of **characteristic impedance Z_n** .

First, we start with a single **design frequency** ω_0 , where we wish to achieve a **perfect match**:

$$\Gamma_{in}(\omega = \omega_0) = 0$$

That's just **one** design equation: we need **$N - 1$** more!

These addition equations can be selected using **many** criteria—one such criterion is to make the function $\Gamma_{in}(\omega)$ **maximally flat** at the point $\omega = \omega_0$.

To accomplish this, we first consider the **Binomial Function**:

$$\Gamma(\theta) = A(1 + e^{-j2\theta})^N$$

This function has the desirable **properties** that:

$$\begin{aligned}\Gamma(\theta = \pi/2) &= A(1 + e^{-j\pi})^N \\ &= A(1 - 1)^N \\ &= 0\end{aligned}$$

and that:

$$\left. \frac{d^n \Gamma(\theta)}{d\theta^n} \right|_{\theta=\pi/2} = 0 \text{ for } n = 1, 2, 3, \dots, N - 1$$

In other words, this Binomial Function is **maximally flat** at the point $\theta = \pi/2$, where it has a value of $\Gamma(\theta = \pi/2) = 0$.

Q: *So? What does **this** have to do with our multi-section matching network?*

A: Let's **expand** (multiply out the N identical product terms) of the Binomial Function:

$$\begin{aligned}\Gamma(\theta) &= A(1 + e^{-j2\theta})^N \\ &= A(C_0^N + C_1^N e^{-j2\theta} + C_2^N e^{-j4\theta} + C_3^N e^{-j6\theta} + \dots + C_N^N e^{-j2N\theta})\end{aligned}$$

where:

$$C_n^N \doteq \frac{N!}{(N-n)!n!}$$

Compare this to an N -section transformer function:

$$\Gamma_{in}(\omega) = \Gamma_0 + \Gamma_1 e^{-j2\omega T} + \Gamma_2 e^{-j4\omega T} + \dots + \Gamma_N e^{-j2N\omega T}$$

and it is obvious the two functions have **identical** forms, **provided** that:

$$\Gamma_n = A C_n^N \quad \text{and} \quad \omega T = \theta$$

Moreover, we find that this function is very **desirable** from the standpoint of the a matching network. Recall that $\Gamma(\theta) = 0$ at $\theta = \pi/2$ --a **perfect** match!

Additionally, the function is **maximally flat** at $\theta = \pi/2$, therefore $\Gamma(\theta) \approx 0$ over a wide range around $\theta = \pi/2$ --a **wide bandwidth**!

Q: But how does $\theta = \pi/2$ relate to frequency ω ?

A: Remember that $\omega T = \theta$, so the value $\theta = \pi/2$ corresponds to the frequency:

$$\omega_0 = \frac{1}{T} \frac{\pi}{2} = \frac{v_p}{\ell} \frac{\pi}{2}$$

This frequency (ω_0) is therefore our **design** frequency—the frequency where we have a **perfect** match.

Note that the length ℓ has an interesting **relationship** with this frequency:

$$\ell = \frac{v_p}{\omega_0} \frac{\pi}{2} = \frac{1}{\beta_0} \frac{\pi}{2} = \frac{\lambda_0}{2\pi} \frac{\pi}{2} = \frac{\lambda_0}{4}$$

In other words, a **Binomial** Multi-section matching network will have a **perfect** match at the frequency where the section lengths ℓ are a **quarter wavelength!**

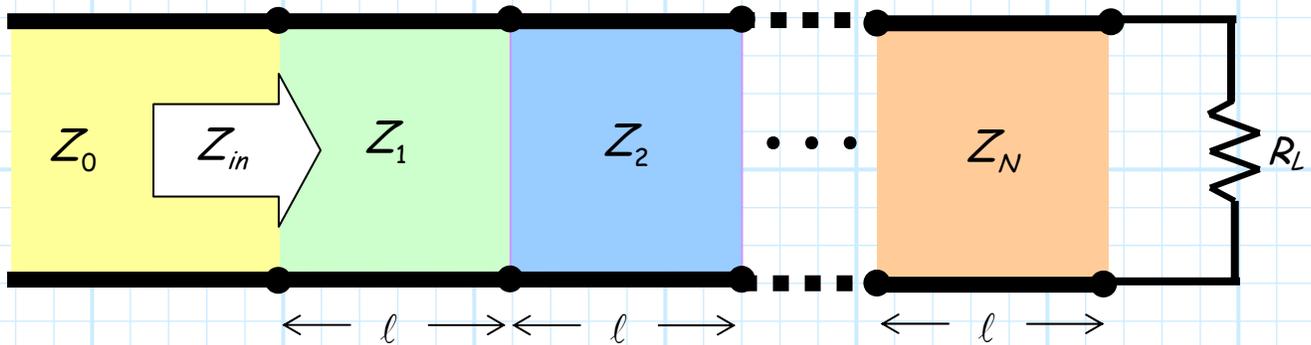
Thus, we have our **first design rule:**

Set section lengths ℓ so that they are a **quarter-wavelength** ($\lambda_0/4$) at the design frequency ω_0 .

Q: I see! And then we select all the values Z_n such that $\Gamma_n = A C_n^N$. But wait! **What is the value of A ??**

A: We can determine this value by evaluating a **boundary condition!**

Specifically, we can **easily** determine the value of $\Gamma(\omega)$ at $\omega = 0$.



Note as ω approaches **zero**, the electrical length βl of each section will **likewise** approach zero. Thus, the input impedance Z_{in} will simply be equal to R_L as $\omega \rightarrow 0$.

As a result, the input reflection coefficient $\Gamma(\omega = 0)$ **must** be:

$$\begin{aligned}\Gamma(\omega = 0) &= \frac{Z_{in}(\omega = 0) - Z_0}{Z_{in}(\omega = 0) + Z_0} \\ &= \frac{R_L - Z_0}{R_L + Z_0}\end{aligned}$$

However, we **likewise** know that:

$$\begin{aligned}\Gamma(0) &= A(1 + e^{-j2(0)})^N \\ &= A(1 + 1)^N \\ &= A2^N\end{aligned}$$

Equating the two expressions:

$$\Gamma(0) = A 2^N = \frac{R_L - Z_0}{R_L + Z_0}$$

And therefore:

$$A = 2^{-N} \frac{R_L - Z_0}{R_L + Z_0} \quad (A \text{ can be negative!}) \quad \triangle$$

We now have a form to calculate the **required marginal reflection coefficients** Γ_n :

$$\Gamma_n = A C_n^N = \frac{A N!}{(N-n)!n!}$$

Of course, we **also** know that these marginal reflection coefficients are physically related to the characteristic impedances of each section as:

$$\Gamma_n = \frac{Z_{n+1} - Z_n}{Z_{n+1} + Z_n}$$

Equating the two and solving, we find that that the section characteristic impedances must satisfy:

$$Z_{n+1} = Z_n \frac{1 + \Gamma_n}{1 - \Gamma_n} = Z_n \frac{1 + A C_n^N}{1 - A C_n^N}$$

Note this is an **iterative** result—we determine Z_1 from Z_0 , Z_2 from Z_1 , and so forth.

Q: *This result **appears** to be our second design equation. Is there some reason why you didn't draw a big blue box around it?*

A: Alas, there is a **big problem** with this result.

Note that there are $N+1$ coefficients Γ_n (i.e., $n \in \{0, 1, \dots, N\}$) in the Binomial series, yet there are only N design degrees of freedom (i.e., there are only N transmission line sections!).

Thus, our design is a bit **over constrained**, a result that manifests itself the finally marginal reflection coefficient Γ_N .

Note from the iterative solution above, the **last** transmission line impedance Z_N is selected to satisfy the **mathematical** requirement of the **penultimate** reflection coefficient Γ_{N-1} :

$$\Gamma_{N-1} = \frac{Z_N - Z_{N-1}}{Z_N + Z_{N-1}} = AC_{N-1}^N$$

Thus the last impedance must be:

$$Z_N = Z_{N-1} \frac{1 + AC_{N-1}^N}{1 - AC_{N-1}^N}$$

But there is **one more** mathematical requirement! The last marginal reflection coefficient **must** likewise satisfy:

$$\Gamma_N = A C_N^N = 2^{-N} \frac{R_L - Z_0}{R_L + Z_0}$$

where we have used the fact that $C_N^N = 1$.

But, we **just** selected Z_N to satisfy the requirement for Γ_{N-1} ,—we have no **physical** design parameter to satisfy this last **mathematical** requirement!

As a result, we find to our great consternation that the last requirement is not satisfied:

$$\Gamma_N = \frac{R_L - Z_N}{R_L + Z_N} \neq A C_N^N \quad !!!!!$$

Q: *Yikes! Does this mean that the resulting matching network will **not** have the desired Binomial frequency response?*

A: That's **exactly** what it means!

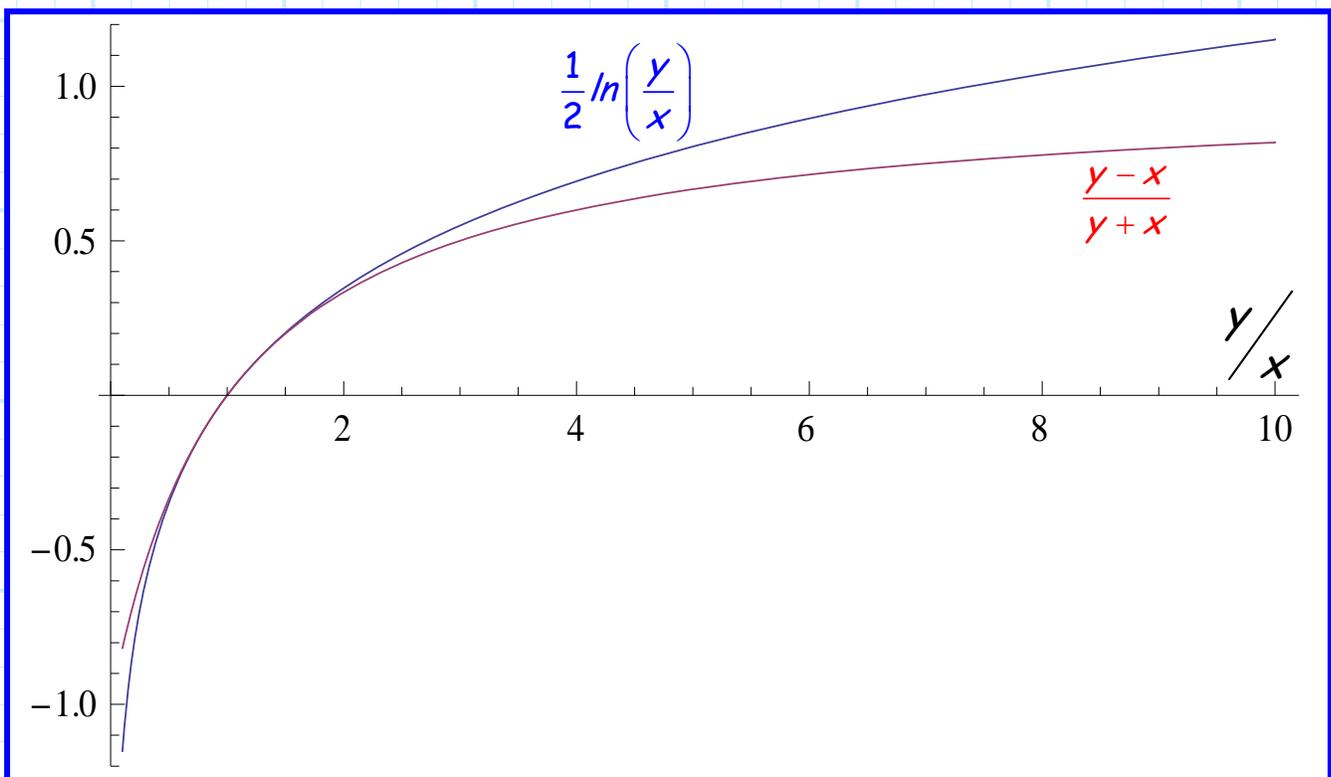
Q: *You big #@#%&!!!! Why did you **waste** all my time by discussing an over-constrained design problem that can't be built?*

A: Relax; there is a **solution** to our dilemma—albeit an **approximate** one.

You undoubtedly have previously used the **approximation**:

$$\frac{y-x}{y+x} \approx \frac{1}{2} \ln \left(\frac{y}{x} \right)$$

An approximation that is especially **accurate** when $|y-x|$ is small (i.e., when $y/x \simeq 1$).



Now, we know that the values of Z_{n+1} and Z_n in a multi-section matching network are typically **very close**, such that $|Z_{n+1} - Z_n|$ is small. Thus, we use the approximation:

$$\Gamma_n = \frac{Z_{n+1} - Z_n}{Z_{n+1} + Z_n} \approx \frac{1}{2} \ln \left(\frac{Z_{n+1}}{Z_n} \right)$$

Likewise, we can **also** apply this approximation (although not as accurately) to the value of A :

$$A = 2^{-N} \frac{R_L - Z_0}{R_L + Z_0} \approx 2^{-(N+1)} \ln\left(\frac{R_L}{Z_0}\right)$$

So, let's **start over**, only this time we'll use these **approximations**. First, determine A :

$$A \approx 2^{-(N+1)} \ln\left(\frac{R_L}{Z_0}\right) \quad (A \text{ can be negative!}) \quad \triangle!$$

Now use this result to calculate the **mathematically required** marginal reflection coefficients Γ_n :

$$\Gamma_n = A C_n^N = \frac{A N!}{(N-n)!n!}$$

Of course, we **also** know that these marginal reflection coefficients are physically related to the characteristic impedances of each section as:

$$\Gamma_n \approx \frac{1}{2} \ln\left(\frac{Z_{n+1}}{Z_n}\right)$$

Equating the two and solving, we find that that the section characteristic impedances **must** satisfy:

$$Z_{n+1} = Z_n \exp[2\Gamma_n]$$

Now **this** is our **second design rule**. Note it is an **iterative** rule—we determine Z_1 from Z_0 , Z_2 from Z_1 , and so forth.

Q: *Huh? How is this any better? How does applying **approximate** math lead to a **better** design result??*

A: Applying these approximations help resolve our over-constrained problem. Recall that the over-constraint resulted in:

$$\Gamma_N = \frac{R_L - Z_N}{R_L + Z_N} \neq A C_N^N$$

But, as it turns out, these approximations leads to the happy situation where:

$$\Gamma_N \approx \frac{1}{2} \ln\left(\frac{R_L}{Z_N}\right) = A C_N^N \quad \leftarrow \text{Sanity check!!}$$

provided that the value A is likewise the approximation given above.

Effectively, these approximations couple the results, such that each value of characteristic impedance Z_n **approximately** satisfies both Γ_n and Γ_{n+1} . Summarizing:

- * If you use the “**exact**” design equations to determine the characteristic impedances Z_n , the last value Γ_N will exhibit a significant numeric error, and your design **will not** appear to be maximally flat.
- * If you instead use the “**approximate**” design equations to determine the characteristic impedances Z_n , all values Γ_n will exhibit a slight error, but the resulting design **will** appear to be **maximally flat**, **Binomial** reflection coefficient function $\Gamma(\omega)$!

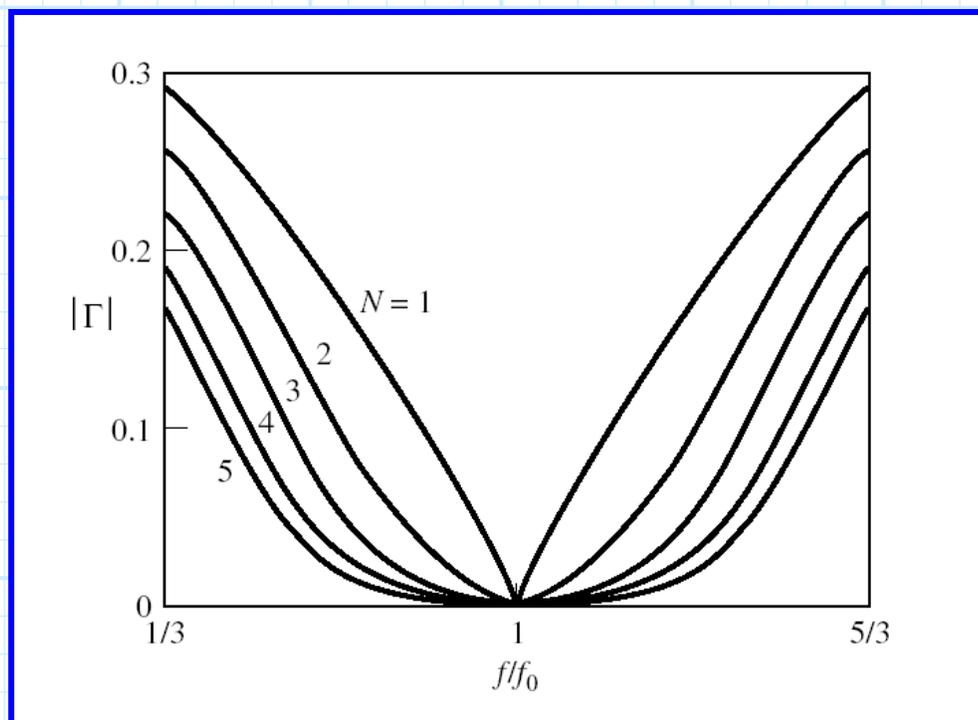


Figure 5.15 (p. 250)

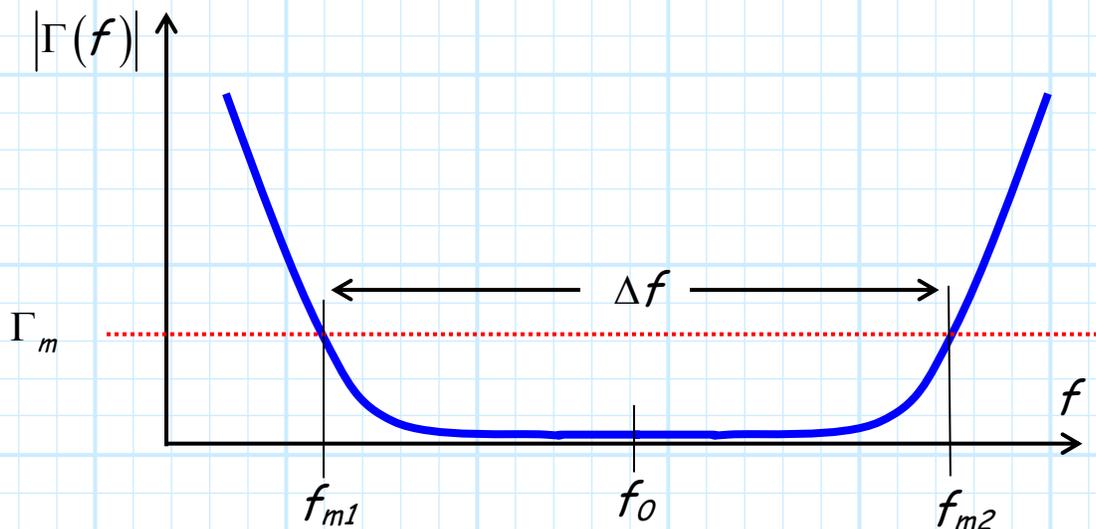
Reflection coefficient magnitude versus frequency for multisection binomial matching transformers of Example 5.6 $Z_L = 50\Omega$ and $Z_0 = 100\Omega$.

Note that as we **increase** the number of **sections**, the matching **bandwidth** increases.

Q: *Can we determine the **value** of this bandwidth?*

A: Sure! But we first must **define** what we mean by bandwidth.

As we move from the design (perfect match) frequency f_0 the value $|\Gamma(f)|$ will **increase**. At some frequency (f_m , say) the magnitude of the reflection coefficient will increase to some **unacceptably** high value (Γ_m , say). At that point, we **no longer** consider the device to be matched.



Note there are **two** values of frequency f_m —one value **less** than design frequency f_0 , and one value **greater** than design frequency f_0 . These two values define the **bandwidth** Δf of the matching network:

$$\Delta f = f_{m2} - f_{m1} = 2(f_0 - f_{m1}) = 2(f_{m2} - f_0)$$

Q: *So what is the **numerical** value of Γ_m ?*

A: **I don't know**—it's up to **you** to decide!

Every engineer must determine what **they** consider to be an acceptable match (i.e., decide Γ_m). This decision depends on the **application** involved, and the **specifications** of the overall microwave system being designed.

However, we **typically** set Γ_m to be 0.2 or less.

Q: *OK, after we have selected Γ_m , can we determine the **two** frequencies f_m ?*

A: Sure! We just have to do a little **algebra**.

We start by **rewriting** the Binomial function:

$$\begin{aligned}\Gamma(\theta) &= A(1 + e^{-j2\theta})^N \\ &= Ae^{-jN\theta} (e^{+j\theta} + e^{-j\theta})^N \\ &= Ae^{-jN\theta} (e^{+j\theta} + e^{-j\theta})^N \\ &= Ae^{-jN\theta} (2\cos\theta)^N\end{aligned}$$

Now, we take the **magnitude** of this function:

$$\begin{aligned}|\Gamma(\theta)| &= 2^N |A| |e^{-jN\theta}| |\cos\theta|^N \\ &= 2^N |A| |\cos\theta|^N\end{aligned}$$

Now, we define the values θ where $|\Gamma(\theta)| = \Gamma_m$ as θ_m . I.E., :

$$\begin{aligned}\Gamma_m &= |\Gamma(\theta = \theta_m)| \\ &= 2^N |A| |\cos \theta_m|^N\end{aligned}$$

We can now solve for θ_m (in radians!) in terms of Γ_m :

$$\theta_{m1} = \cos^{-1} \left[\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right] \qquad \theta_{m2} = \cos^{-1} \left[-\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right]$$

Note that there are **two solutions** to the above equation (one less than $\pi/2$ and one **greater** than $\pi/2$)!

Now, we can convert the values of θ_m into specific frequencies.

Recall that $\omega T = \theta$, therefore:

$$\omega_m = \frac{1}{T} \theta_m = \frac{v_p}{\ell} \theta_m$$

But recall also that $\ell = \lambda_0/4$, where λ_0 is the wavelength at the **design frequency** f_0 (not f_m !), and where $\lambda_0 = v_p/f_0$.

Thus we can conclude:

$$\omega_m = \frac{v_p}{\ell} \theta_m = \frac{4v_p}{\lambda_0} \theta_m = (4f_0) \theta_m$$

or:

$$f_m = \frac{1}{2\pi} \frac{v_p}{\ell} \theta_m = \frac{(4f_0)\theta_m}{2\pi} = \frac{(2f_0)\theta_m}{\pi}$$

where θ_m is expressed in **radians**. Therefore:

$$f_{m1} = \frac{2f_0}{\pi} \cos^{-1} \left[+\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right] \quad f_{m2} = \frac{2f_0}{\pi} \cos^{-1} \left[-\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right]$$

Thus, the **bandwidth** of the binomial matching network can be determined as:

$$\begin{aligned} \Delta f &= 2(f_0 - f_{m1}) \\ &= 2f_0 - \frac{4f_0}{\pi} \cos^{-1} \left[+\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right] \end{aligned}$$

Note that this equation can be used to determine the **bandwidth** of a binomial matching network, given Γ_m and number of sections N .

However, it can likewise be used to determine the **number of sections** N required to meet a specific bandwidth requirement!

Finally, we can list the **design steps** for a binomial matching network:

1. **Determine** the value N required to meet the bandwidth (Δf and Γ_m) requirements.
2. Determine the **approximate** value A from Z_0, R_L and N .
3. Determine the **marginal reflection coefficients** $\Gamma_n = A C_n^N$ required by the **binomial** function.
4. Determine the characteristic impedance of each section using the **iterative approximation**:

$$Z_{n+1} = Z_n \exp[2\Gamma_n]$$

5. Perform the **sanity check**:

$$\Gamma_N \approx \frac{1}{2} \ln\left(\frac{R_L}{Z_N}\right) = A C_N^N$$

6. Determine section **length** $\ell = \lambda_0/4$ for design frequency f_0 .